

## 第二章

# 静电场

### 2.5 静电场的多极矩

## 2.5.1 静电势多极矩展开

### 1. 问题分析

理论上: 已知  $\rho(\vec{x}')$ , 原则上由

$$\varphi(\vec{x}) = \int_V \frac{\rho(\vec{x}') dV'}{4\pi\epsilon_0 r} \quad \text{求电势。}$$

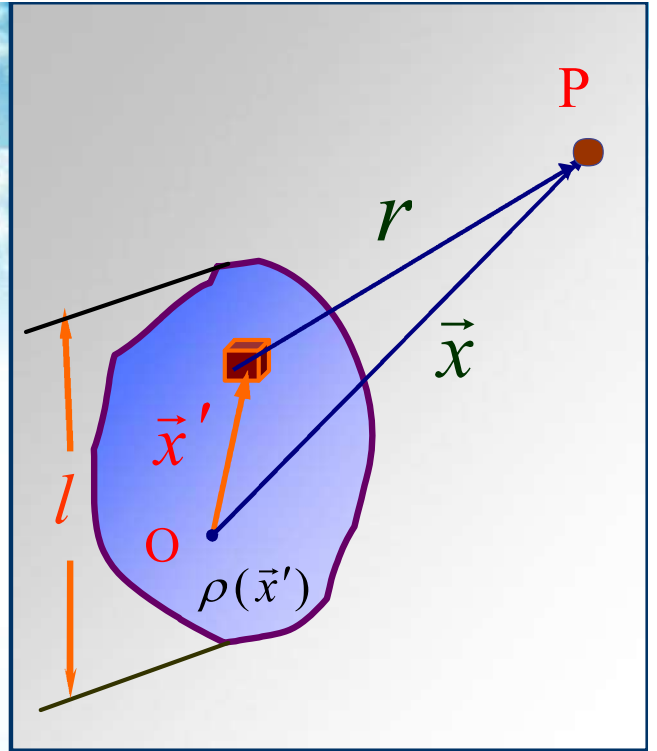
实际问题: 体电荷分布不均匀或区域不规则, 积分困难

特殊情况: 区域的线度远小于该区域到场点的距离, 可以近似求解。 条件  $l \ll r$

$$r \approx |\vec{x}| = R \Rightarrow$$

$$\varphi(\vec{x}) \approx \frac{Q}{4\pi\epsilon_0 R}$$

目的: 寻求精度更高的级数解



## 2. $\frac{1}{r}$ 的麦克劳林展开

(1) 一元函数的麦克劳林展开式 (在坐标原点展开)

$$f(x) = f(0) + \frac{1}{1!} \frac{df(0)}{dx} x + \frac{1}{2!} \frac{d^2 f(0)}{dx^2} x^2 + \dots$$

(2) 三元函数的麦克劳林展开

$$f(\vec{x}) = f(x_1, x_2, x_3)$$

$$\begin{aligned} &= f(0,0,0) + \frac{1}{1!} \left( x_1 \frac{\partial f(0,0,0)}{\partial x_1} + x_2 \frac{\partial f(0,0,0)}{\partial x_2} + x_3 \frac{\partial f(0,0,0)}{\partial x_3} \right) \\ &+ \frac{1}{2!} \left[ x_1^2 \frac{\partial^2 f(0,0,0)}{\partial x_1^2} + x_2^2 \frac{\partial^2 f(0,0,0)}{\partial x_2^2} + x_3^2 \frac{\partial^2 f(0,0,0)}{\partial x_3^2} \right. \\ &\left. + 2x_1 x_2 \frac{\partial^2 f}{\partial x_1 \partial x_2} + 2x_1 x_3 \frac{\partial^2 f}{\partial x_1 \partial x_3} + 2x_2 x_3 \frac{\partial^2 f}{\partial x_2 \partial x_3} \right] + \dots \end{aligned}$$

$$f(\vec{x}) = f(x_1, x_2, x_3)$$

$$= f(0) + \frac{1}{1!} \left( x_1 \frac{\partial}{\partial x_1} + x_2 \frac{\partial}{\partial x_2} + x_3 \frac{\partial}{\partial x_3} \right) f(0)$$

$$+ \frac{1}{2!} \left( x_1 \frac{\partial}{\partial x_1} + x_2 \frac{\partial}{\partial x_2} + x_3 \frac{\partial}{\partial x_3} \right)^2 f(0) + \dots$$

$$= f(0) + \sum_{i=1}^3 x_i \frac{\partial}{\partial x_i} f(0) + \frac{1}{2} \left[ \sum_i x_i \frac{\partial}{\partial x_i} \sum_j x_j \frac{\partial}{\partial x_j} \right] f(0) + \dots$$

$$= f(0) + \sum_{i=1}^3 x_i \frac{\partial}{\partial x_i} f(0) + \frac{1}{2} \sum_{ij} x_i x_j \frac{\partial^2}{\partial x_i \partial x_j} f(0) + \dots$$

$$= f(0) + (\vec{x} \cdot \nabla) f(0) + \frac{1}{2} (\vec{x} \cdot \nabla)^2 f(0) + \dots$$

$$f(\vec{x}') = f(x'_1, x'_2, x'_3)$$

$$= f(0) + (\vec{x}' \cdot \nabla') f(0) + \frac{1}{2} (\vec{x}' \cdot \nabla')^2 f(0) + \dots$$

$$f(\vec{x}') = f(x'_1, x'_2, x'_3)$$

$$= f(0) + (\vec{x}' \cdot \nabla') f(0) + \frac{1}{2} (\vec{x}' \cdot \nabla')^2 f(0) + \dots$$

(3) 将  $\frac{1}{r}$  在  $\vec{x}' = 0$  点展开

$$\frac{1}{r} = \frac{1}{|\vec{x} - \vec{x}'|} = f(\vec{x} - \vec{x}'), \quad \vec{x}' = 0, \quad \frac{1}{r} = \frac{1}{R}$$

对应  $f(\vec{x}')$   $\longrightarrow$   $f(\vec{x} - \vec{x}') = \frac{1}{r} = \frac{1}{|\vec{x} - \vec{x}'|}$

关系  $f(0)$   $\longrightarrow$   $f(\vec{x} - \vec{x}')|_{\vec{x}'=0} = \frac{1}{r}|_{\vec{x}'=0} = f(\vec{x}) = \frac{1}{R}$

$$f(\vec{x} - \vec{x}') = f(\vec{x}) + (\vec{x}' \cdot \nabla') f(\vec{x}) + \frac{1}{2} (\vec{x}' \cdot \nabla')^2 f(\vec{x}) + \dots$$

$$f(\vec{x} - \vec{x}') = f(\vec{x}) + (\vec{x}' \cdot \nabla') f(\vec{x}) + \frac{1}{2} (\vec{x}' \cdot \nabla')^2 f(\vec{x}) + \dots$$

$$\frac{1}{r} = \frac{1}{|\vec{x} - \vec{x}'|} = f(\vec{x} - \vec{x}')$$

$$f(\vec{x} - \vec{x}')|_{\vec{x}'=0} = \frac{1}{r}|_{\vec{x}'=0} = f(\vec{x}) = \frac{1}{R}$$

$$\frac{1}{r} = \frac{1}{R} + (\vec{x}' \cdot \nabla') \frac{1}{r} \Big|_{\vec{x}'=0} + \frac{1}{2} (\vec{x}' \cdot \nabla')^2 \frac{1}{r} \Big|_{\vec{x}'=0} + \dots$$

$$= \frac{1}{R} - (\vec{x}' \cdot \nabla) \frac{1}{R} + \frac{1}{2} (\vec{x}' \cdot \nabla)^2 \frac{1}{R} + \dots$$

$$= \frac{1}{R} - (\vec{x}' \cdot \nabla) \frac{1}{R} + \frac{1}{2} (\vec{x}' \vec{x}' : \nabla \nabla) \frac{1}{R} + \dots$$

其中  $(\nabla' \frac{1}{r} \Big|_{\vec{x}'=0} = -\nabla \frac{1}{r} \Big|_{\vec{x}'=0} = -\nabla \frac{1}{R}$  ,  $\vec{a}\vec{a} : \vec{b}\vec{b} = (\vec{a} \cdot \vec{b})^2$  )

$$\frac{1}{r} = \frac{1}{R} - (\vec{x}' \cdot \nabla) \frac{1}{R} + \frac{1}{2} (\vec{x}' \vec{x}' : \nabla \nabla) \frac{1}{R} + \dots$$

$$\frac{1}{r} = \frac{1}{R} - (\vec{x}' \cdot \nabla) \frac{1}{R} + \frac{1}{2} (\vec{x}' \cdot \nabla)^2 \frac{1}{R} + \dots$$

### 3. 小区域电荷分布产生的电势

$$\varphi(\vec{x}) = \int_{\infty} \frac{\rho(\vec{x}') dV'}{4\pi\epsilon_0 r} = \frac{1}{4\pi\epsilon_0} \int_{\infty} \rho(\vec{x}') \frac{1}{r} dV'$$

$$\varphi(\vec{x}) = \frac{1}{4\pi\epsilon_0} \int \rho(\vec{x}') \left[ \frac{1}{R} - \vec{x}' \cdot \nabla \frac{1}{R} + \frac{1}{2} \vec{x}' \vec{x}' : \nabla \nabla \frac{1}{R} + \dots \right] dV'$$

$$\varphi(\vec{x}) = \frac{1}{4\pi\epsilon_0} \int_V \rho(\vec{x}') \left[ \frac{1}{R} - \vec{x}' \cdot \nabla \frac{1}{R} + \frac{1}{2} \vec{x}' \vec{x}' : \nabla \nabla \frac{1}{R} + \dots \right] dV'$$

$$= \frac{1}{4\pi\epsilon_0} \int_V \rho(\vec{x}') dV' \frac{1}{R} \quad \rightarrow \quad Q = \int_V \rho(\vec{x}') dV' \quad \begin{array}{l} \text{点电荷} \\ \text{零极矩} \end{array}$$

$$+ \frac{-1}{4\pi\epsilon_0} \int_V \rho(\vec{x}') \vec{x}' dV' \cdot \nabla \frac{1}{R} \quad \rightarrow \quad \vec{p} = \int_V \rho(\vec{x}') \vec{x}' dV' \quad \begin{array}{l} \text{电偶极} \\ \text{矩矢量} \end{array}$$

$$+ \frac{1}{4\pi\epsilon_0} \frac{1}{6} \int_V 3\rho(\vec{x}') \vec{x}' \vec{x}' dV' : \nabla \nabla \frac{1}{R} \quad \rightarrow \quad \overleftrightarrow{\mathcal{D}} = \int_V 3\vec{x}' \vec{x}' \rho(\vec{x}') dV'$$

$$+ \frac{1}{4\pi\epsilon_0} \int_V \rho(\vec{x}') [\dots + \dots] dV'$$

电四极矩张量

$$\text{分量式: } D_{ij} = \int 3x'_i x'_j \rho(\vec{x}') dV' \quad i = 1 \rightarrow 3, j = 1 \rightarrow 3$$



$$\varphi(\vec{x}) = \frac{Q}{4\pi\epsilon_0 R} + \frac{-1}{4\pi\epsilon_0} \vec{p} \cdot \nabla \frac{1}{R} + \frac{1}{4\pi\epsilon_0} \frac{1}{6} \overleftrightarrow{\mathcal{D}} : \nabla \nabla \frac{1}{R} + \dots$$

$$\varphi^{(0)} = \frac{Q}{4\pi\epsilon_0 R}$$

$$\varphi^{(1)} = -\frac{1}{4\pi\epsilon_0} \vec{p} \cdot \nabla \frac{1}{R}$$

$$\varphi^{(2)} = \frac{1}{4\pi\epsilon_0} \frac{1}{6} \overleftrightarrow{\mathcal{D}} : \nabla \nabla \frac{1}{R} + \dots$$

$$Q = \int_V \rho(\vec{x}') dV'$$

$$\vec{p} = \int_V \rho(\vec{x}') \vec{x}' dV'$$

$$\overleftrightarrow{\mathcal{D}} = \int_V 3\vec{x}'\vec{x}' \rho(\vec{x}') dV'$$

$$\varphi(\vec{x}) = \varphi^{(0)} + \varphi^{(1)} + \varphi^{(2)} + \dots$$

## 2.5.2 电多极矩

### 1. 展开式的物理意义

$$\varphi^{(0)} = \frac{Q}{4\pi\epsilon_0 R} \quad \Rightarrow \quad \text{球体}$$

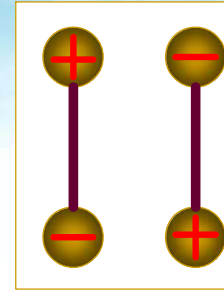
等效于坐标原点  
点电荷产生的电势。  
因此小电荷体系在电  
荷分布区外产生的电  
势在零级近似下可视  
为将电荷集中于原点  
处产生的电势。

$$\varphi^{(1)} = -\frac{1}{4\pi\epsilon_0} \vec{p} \cdot \nabla \frac{1}{R} = -\frac{1}{4\pi\epsilon_0} \vec{p} \cdot \left(-\frac{\vec{R}}{R^3}\right) = \frac{\vec{p} \cdot \vec{R}}{4\pi\epsilon_0 R^3}$$



等效电偶极矩  $\vec{p}$  产生的电势。最简单的体系为两  
个点电荷产生的电势。

$$\varphi^{(2)} = \frac{1}{4\pi\epsilon_0} \frac{1}{6} \overleftrightarrow{\mathcal{D}} : \nabla \nabla \frac{1}{R} = \frac{1}{4\pi\epsilon_0} \frac{1}{6} \sum_{ij} D_{ij} \frac{\partial^2}{\partial x_i \partial x_j} \frac{1}{R}$$



$$\overleftrightarrow{\mathcal{D}} : \nabla \nabla = \sum_{ij} D_{ij} \vec{e}_i \vec{e}_j : \sum_{kl} \frac{\partial^2}{\partial x_k \partial x_l} \vec{e}_k \vec{e}_l$$

$$= \sum_{ij} D_{ij} \sum_{kl} \frac{\partial^2}{\partial x_k \partial x_l} \delta_{jk} \delta_{il} = \sum_{ij} D_{ij} \frac{\partial^2}{\partial x_i \partial x_j}$$

$\varphi^{(2)}$  等效为体系电四极矩张量产生的电势。最简单的体系为坐标原点附近 (+, -, +, -) 四个点电荷产生的电势

2. 电四极矩张量  $\overleftrightarrow{\mathcal{D}} = \int_V 3\vec{x}'\vec{x}'\rho(\vec{x}')dV'$

有9个分量  $D_{ij} = \int 3x'_ix'_j\rho(\vec{x}')dV'$

$D_{ij} = D_{ji}$  ( $i \neq j$ ) 此6个不同分量，只有三个独立

重新定义:  $\overleftrightarrow{\mathcal{D}} = \int [3\vec{x}'\vec{x}' - r'^2 \overleftrightarrow{\mathcal{F}}] \rho(\vec{x}')dV'$

$D_{ij} = \int [3x'_ix'_j - \delta_{ij}r'^2] \rho(\vec{x}')dV'$

$\overleftrightarrow{\mathcal{F}} = \sum_{ij} \delta_{ij} \vec{e}_i \vec{e}_j$

可以证明它不改变  $\varphi^{(2)}$

此时有  $D_{11} + D_{22} + D_{33} = 0$

所以电四极矩张量

只有5个独立分量

$\varphi^{(2)} = \frac{1}{4\pi\epsilon_0} \frac{1}{6} \overleftrightarrow{\mathcal{D}} : \nabla\nabla \frac{1}{R} = \frac{1}{4\pi\epsilon_0} \frac{1}{6} \sum_{ij} D_{ij} \frac{\partial^2}{\partial x_i \partial x_j} \frac{1}{R}$

### 3. 证明两种电四极矩表示式对应的电势表示等效

$$D_{ij} = \int 3x'_i x'_j \rho(\vec{x}') dV' \quad \text{原表示}$$

$$D_{ij} = \int [3x'_i x'_j - \delta_{ij} r'^2] \rho(\vec{x}') dV' \quad \text{新表示}$$

$$\begin{aligned} \varphi^{(2)} &= \frac{1}{4\pi\epsilon_0} \frac{1}{6} \left[ \int 3\vec{x}'\vec{x}' \rho(\vec{x}') dV' \right] : \nabla\nabla \frac{1}{R} \quad \boxed{\text{加入一个0项}} \\ &= \frac{1}{4\pi\epsilon_0} \frac{1}{6} \left[ \int 3\vec{x}'\vec{x}' \rho(\vec{x}') dV' : \nabla\nabla \frac{1}{R} - \int r'^2 \overleftrightarrow{\mathcal{F}} : \nabla\nabla \frac{1}{R} \rho(\vec{x}') dV' \right] \\ &= \frac{1}{4\pi\epsilon_0} \frac{1}{6} \left[ \int (3\vec{x}'\vec{x}' - r'^2 \overleftrightarrow{\mathcal{F}}) \rho(\vec{x}') dV' \right] : \nabla\nabla \frac{1}{R} \quad \left( = \nabla^2 \frac{1}{R} = 0 \quad (R \neq 0) \right) \end{aligned}$$

#### 4. 电四极矩最简单体系举例

四个点电荷在一直线上排列，可看作一对正负电偶极子。

(1) 运用多极展开式计算电势

$$l = a + b$$

$$\vec{P}_{\text{上}} = Q(b - a)\vec{e}_z = \vec{p}$$

$$\vec{P}_{\text{下}} = -Q(b - a)\vec{e}_z = -\vec{p}$$

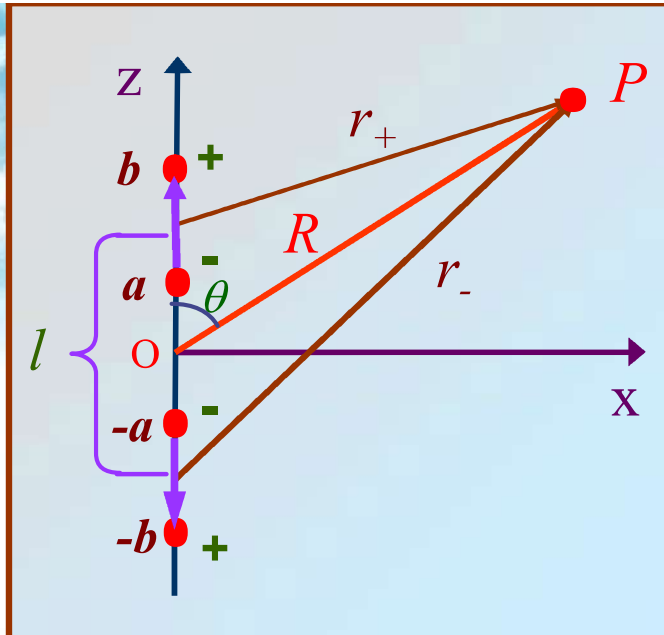
$$Q = \int_V \rho(\vec{x}') dV' = 0$$

$$\vec{p} = \int_V \rho(\vec{x}') \vec{x}' dV' = 0$$

$$\varphi^{(0)} = \frac{Q}{4\pi\epsilon_0 R} = 0$$

体系总电荷、总电偶极矩为零

$$\varphi^{(1)} = -\frac{1}{4\pi\epsilon_0} \vec{p} \cdot \nabla \frac{1}{R} = 0$$



$D_{ij} = \int 3x'_i x'_j \rho(\vec{x}') dV'$  依定义  $D_{33} \neq 0$  其它分量均为零

$$\rho(\vec{x}') = \sum_{i=1}^4 Q'_i \delta(x') \delta(y') \delta(z' - z_i)$$

$$Q'_1 = Q, \quad z_1 = b, \quad Q'_2 = -Q, \quad z_2 = a,$$

$$Q'_3 = -Q, \quad z_3 = -a, \quad Q'_4 = Q, \quad z_4 = -b$$

$$D_{33} = \int_V 3z'z' \rho(\vec{x}') dV'$$

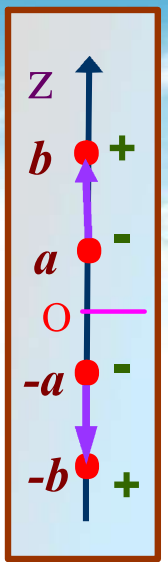
$$= \iiint_V 3z'z' \sum_{i=1}^4 Q'_i \delta(x') \delta(y') \delta(z' - z_i) dx' dy' dz'$$

$$= \sum_{i=1}^4 3 \int_{z'=-\infty}^{z'=\infty} z'z' Q'_i \delta(z' - z_i) dz'$$

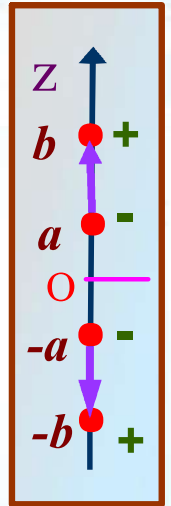
$$= 3z_1z_1Q - 3z_2z_2Q - 3z_3z_3Q + 3z_4z_4Q$$

$$= 3(b^2 - a^2 - a^2 + b^2)Q = 6Q(b^2 - a^2)$$

$$= 6Q(b - a)(b + a) = 6pl$$



$$\begin{aligned}
\varphi(\vec{x}) &= \frac{Q}{4\pi\epsilon_0 R} + \frac{-1}{4\pi\epsilon_0} \vec{p} \cdot \nabla \frac{1}{R} + \frac{1}{4\pi\epsilon_0} \frac{1}{6} \mathcal{D} : \nabla \nabla \frac{1}{R} + \dots \\
&= 0 + 0 + \frac{1}{4\pi\epsilon_0} \frac{1}{6} \sum_{ij} D_{ij} \frac{\partial^2}{\partial x_i \partial x_j} \frac{1}{R} \\
&= \frac{1}{4\pi\epsilon_0} \frac{1}{6} D_{33} \frac{\partial^2}{\partial x_3 \partial x_3} \frac{1}{R} \\
\varphi = \varphi^{(2)} &= \frac{1}{4\pi\epsilon_0} pl \frac{\partial^2}{\partial z^2} \left( \frac{1}{R} \right)
\end{aligned}$$



忽略更高极势后，系统的势等于第三项的势

(2) 运用电势的积分式计算（忽略三级小量保留二级小量）

在近似条件下，可采用两个电偶极子的电势迭加计算。



$$\varphi = \frac{\vec{p} \cdot \vec{r}_+}{4\pi\epsilon_0 r_+^3} - \frac{\vec{p} \cdot \vec{r}_-}{4\pi\epsilon_0 r_-^3} = -\frac{1}{4\pi\epsilon_0} \vec{p} \cdot \left[ \nabla \frac{1}{r_+} - \nabla \frac{1}{r_-} \right]$$

$$= -\frac{1}{4\pi\epsilon_0} p \frac{\partial}{\partial z} \left( \frac{1}{r_+} - \frac{1}{r_-} \right) \quad (\vec{p} = p\vec{e}_z)$$

$$r_+ \approx R - \frac{l}{2} \cos\theta \quad r_- \approx R + \frac{l}{2} \cos\theta \quad \frac{1}{r_+} - \frac{1}{r_-} = \frac{r_- - r_+}{r_+ r_-} \approx \frac{l \cos\theta}{R^2}$$

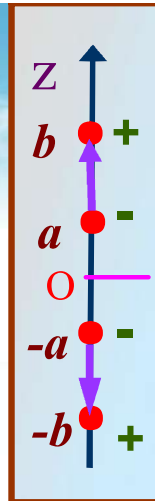
$$\frac{\partial}{\partial z} \frac{1}{R} = -\frac{1}{R^2} \frac{\partial R}{\partial z} = -\frac{1}{R^2} \frac{z}{R} = -\frac{\cos\theta}{R^2} \quad (z = R \cos\theta)$$

$$\varphi = \frac{1}{4\pi\epsilon_0} p l \frac{\partial^2}{\partial z^2} \left( \frac{1}{R} \right)$$

$$R = \sqrt{x^2 + y^2 + z^2} \quad \frac{\partial R}{\partial z} = \frac{z}{R}$$

此为电四极子势

两种方法讲算结果一致，表明  $\varphi^{(2)}$  为电四极子势



## 电四极矩其它例子

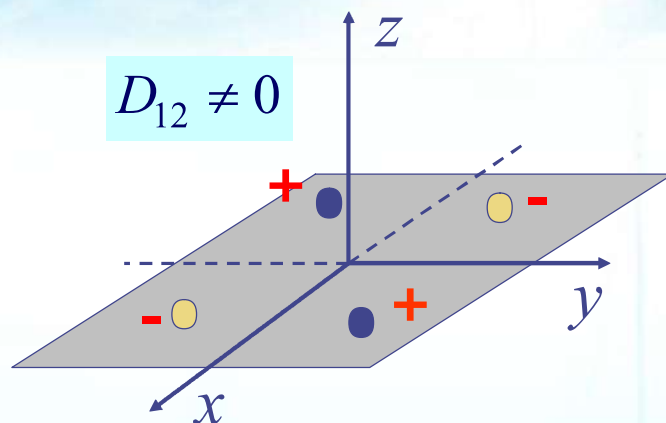
$D_{11} \neq 0$  四个点电荷在  $x$  轴

$D_{22} \neq 0$  四个点电荷在  $y$  轴

$D_{12} = D_{21} \neq 0$   $x$ - $y$  平面

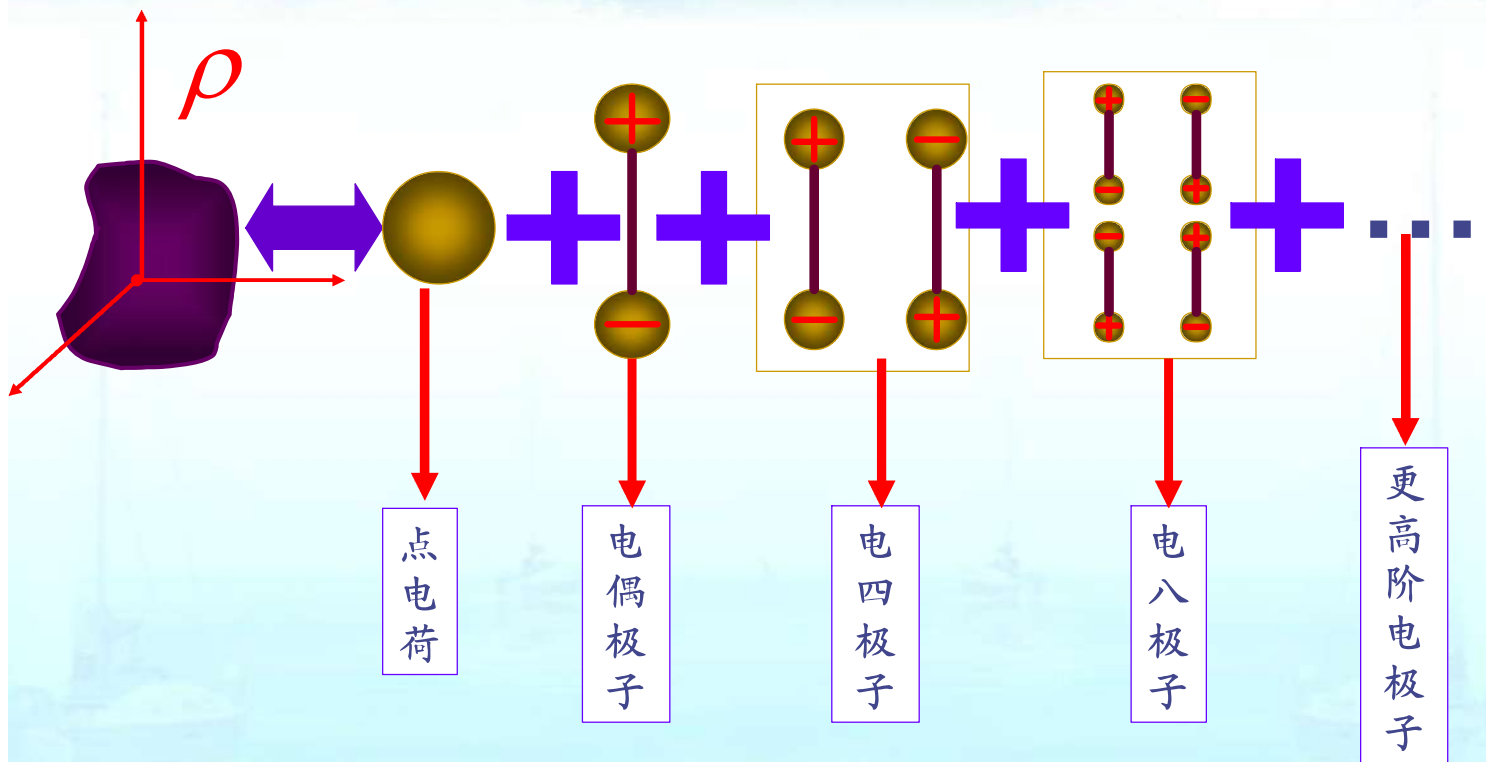
$D_{13} = D_{31} \neq 0$   $x$ - $z$  平面

$D_{23} = D_{32} \neq 0$   $y$ - $z$  平面



# 小结：电多极展开要点概述

1.带电体系可等效分解为不同级的理想电多极子迭加



## 2. 带电体系势的级数分解

$$\varphi(\vec{x}) = \int_V \frac{\rho(\vec{x}') dV'}{4\pi\epsilon_0 r}$$

$$\frac{1}{r} = \frac{1}{R} - (\vec{x}' \cdot \nabla) \frac{1}{R} + \frac{1}{2} (\vec{x}' \cdot \nabla)^2 \frac{1}{R} + \dots$$

$$\varphi(\vec{x}) = \frac{Q}{4\pi\epsilon_0 R} + \frac{-1}{4\pi\epsilon_0} \vec{p} \cdot \nabla \frac{1}{R} + \frac{1}{4\pi\epsilon_0} \frac{1}{6} \overleftrightarrow{\mathcal{D}} : \nabla \nabla \frac{1}{R} + \dots$$

$$\varphi^{(0)} = \frac{Q}{4\pi\epsilon_0 R}$$

$$\varphi^{(1)} = -\frac{\vec{p} \cdot \vec{R}}{4\pi\epsilon_0 R^3}$$

$$\varphi^{(2)} = \frac{1}{4\pi\epsilon_0} \frac{1}{6} \overleftrightarrow{\mathcal{D}} : \nabla \nabla \frac{1}{R}$$

$$Q = \int_V \rho(\vec{x}') dV'$$

点电荷

$$\vec{p} = \int_V \rho(\vec{x}') \vec{x}' dV'$$

偶极矩

$$\overleftrightarrow{\mathcal{D}} = \int_V 3\vec{x}'\vec{x}' \rho(\vec{x}') dV'$$

四极矩

$$D_{ij} = \int 3x'_i x'_j \rho(\vec{x}') dV'$$

### 3.电多极展开的特点

- ①带电体系的势可分解成无穷多项电极子势的迭加，根据问题精度的需要进行取舍，使运算得到简化。
- ②各项多极势的大小依赖于原点的选取，总势与原点选取无关。
- ③高级势比低级势效应小
- ④在实际应用中，往往可以根据势的特征反推体系的电结构特征。