# Random Attractors for Stochastic Wave Equations with Critical Exponents on $\mathbb{R}^n$

**Bixiang Wang** 

**Department of Mathematics** 

**New Mexico Tech** 

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# Random Attractors for Wave Equations

### **Outline**

- Stochastic wave equations on  $\mathbb{R}^n$ .
- Random attractors theory.
- Random absorbing sets for wave equations.
- Pullback asymptotic compactness.
- Existence of random attractors.

# **Wave Equations**

# The stochastic wave equation on $\mathbb{R}^n$ :

$$u_{tt} + \alpha u_t - \Delta u + \lambda u + f(x, u) = g(x) + h(x) \frac{dw}{dt}.$$

- $\lambda$  and  $\alpha$  are positive constants.
- g and h are given functions on  $\mathbb{R}^n$ .
- ullet w is a two-sided Wiener process.
- ullet f is a smooth nonlinear function satisfying certain growth conditions.

# Question: Long term behavior of solutions?

- Stochastic PDEs on bounded domains:
  - Crauel and Flandoli (1994);
  - Flandoli and Schmalfuss (1996);
  - Arnold (1998);
  - Caraballo, Langa and Robinson (2001);
  - Chueshov and Scheutzow (2004);
  - Chueshov and Schmalfuss (2007);
  - Li and Guo (2008), etc.
- Stochastic systems on unbounded domains:
  - Bates, Lisei and Lu (2006);
  - Brzezniak and Li (2006);
  - Bates, Lu and Wang (2008).

Difficulty: Sobolev embeddings are not compact on unbounded domains.

# Some methods to overcome the difficulty:

- Weighted spaces: Abergel (1989); Babin and Vishik (1990), etc.
- Energy equation approach:
   Ball (1997, 2004); Rosa (1998); Moise, Rosa and X.Wang (1998); Ju (2000, 2001); Goubet and Rosa (2002); Brzezniak and Li (2006), etc.
- Tail estimates approach:

B.Wang (1999); Antoci and Prizzi (2001, 2002); Morillas and Valero (2005); Prizzi (2005); Yang, Sun and Zhong (2007); Bates, Lu and Wang (2008), etc.

Goal: Prove existence of a random attractor for the stochastic wave equation.

The concept of random attractors for stochastic PDEs is an extension of global attractors of deterministic PDEs. This extension was developed by Crauel-Flandoli (1994) and Flandoli-Schmalfuss (1996).

(X,d): metric space with Borel  $\sigma$ -algebra  $\mathcal{B}(X)$ .  $(\Omega,\mathcal{F},P)$ : probability space.

 $\mathcal{D}$ : collection of some random subsets of X.

Definition (Shift Operators). Let  $\theta: \mathbb{R} \times \Omega \to \Omega$  be  $(\mathcal{B}(\mathbb{R}) \times \mathcal{F}, \mathcal{F})$ -measurable. Then  $(\theta_t)_{t \in \mathbb{R}}$  is called a family of shift operators on  $\Omega$  if

- $\theta_0$  is the identity on  $\Omega$ ;
- $\theta_{s+t} = \theta_t \circ \theta_s$  for all  $s, t \in \mathbb{R}$ .

Definition (Metric Dynamical System). Let  $(\theta_t)_{t\in\mathbb{R}}$  be a family of shift operators. Then  $(\Omega, \mathcal{F}, P, (\theta_t)_{t\in\mathbb{R}})$  is called a metric dynamical system if  $(\theta_t)_{t\in\mathbb{R}}$  is measure preserving, i.e.,  $\theta_t P = P$  for all  $t \in \mathbb{R}$ .

Definition (Random Dynamical System). Let  $(\Omega, \mathcal{F}, P, (\theta_t)_{t \in \mathbb{R}})$  be a metric dynamical system, and  $\Phi$  a mapping:

$$\Phi: \mathbb{R}^+ \times \Omega \times X \to X \quad (t, \omega, x) \mapsto \Phi(t, \omega, x).$$

Then  $\Phi$  is called a continuous random dynamical system on X if  $\Phi$  is  $(\mathcal{B}(\mathbb{R}^+) \times \mathcal{F} \times \mathcal{B}(X), \mathcal{B}(X))$ -measurable and satisfies, for P-a.e.  $\omega \in \Omega$ ,

- (i)  $\Phi(0,\omega,\cdot)$  is the identity on X;
- (ii)  $\Phi(t+s,\omega,\cdot) = \Phi(t,\theta_s\omega,\cdot)\circ\Phi(s,\omega,\cdot)\ \forall t,s\geq 0$ ;
- (iii)  $\Phi(t,\omega,\cdot):X\to X$  is continuous  $\forall t\in\mathbb{R}^+$ .

Definition (Tempered Sets). Let  $\{B(\omega)\}_{\omega \in \Omega}$  be a random bounded subset of X. Then  $\{B(\omega)\}_{\omega \in \Omega}$  is called tempered with respect to  $(\theta_t)_{t \in \mathbb{R}}$  if there exists  $x_0 \in X$  such that for P-a.e.  $\omega \in \Omega$ ,

$$\lim_{t \to -\infty} e^{\beta t} d(x_0, B(\theta_t \omega)) = 0 \quad \text{for all } \beta > 0.$$

All bounded deterministic sets are tempered.

Definition (Random Absorbing Sets). Let  $\mathcal{D}$  be a collection of random subsets of X and  $\{K(\omega)\}_{\omega\in\Omega}\in\mathcal{D}$ . Then  $\{K(\omega)\}_{\omega\in\Omega}$  is called a random absorbing set of  $\Phi$  in  $\mathcal{D}$  if for every  $B\in\mathcal{D}$  and P-a.e.  $\omega\in\Omega$ , there exists  $T(\omega,B)>0$  such that

$$\Phi(t, \theta_{-t}\omega, B(\theta_{-t}\omega)) \subseteq K(\omega)$$
 for all  $t \ge T(\omega, B)$ .

Definition (Pullback Asymptotic Compactness).  $\Phi$  is said to be  $\mathcal{D}$ -pullback asymptotically compact in X if for P-a.e.  $\omega \in \Omega$ ,  $\{\Phi(t_n, \theta_{-t_n}\omega, x_n)\}_{n=1}^{\infty}$  has a convergent subsequence in X whenever  $t_n \to \infty$ , and  $x_n \in B(\theta_{-t_n}\omega)$  with  $\{B(\omega)\}_{\omega \in \Omega} \in \mathcal{D}$ .

Definition (Random Attractor). A random set  $\{\mathcal{A}(\omega)\}_{\omega\in\Omega}\in\mathcal{D}$  is called a  $\mathcal{D}$ -random attractor for  $\Phi$  if for P-a.e.  $\omega\in\Omega$  and all  $t\geq0$ ,

- $\mathcal{A}(\omega)$  is compact, and  $\omega \mapsto d(x, \mathcal{A}(\omega))$  is measurable for every  $x \in X$ ;
- $\{A(\omega)\}_{\omega \in \Omega}$  is invariant:  $\Phi(t, \omega, A(\omega)) = A(\theta_t \omega)$ ;
- $\{A(\omega)\}_{\omega\in\Omega}$  attracts every set in  $\mathcal{D}$ : for every  $B=\{B(\omega)\}_{\omega\in\Omega}\in\mathcal{D}$ ,

$$\lim_{t \to \infty} d(\Phi(t, \theta_{-t}\omega, B(\theta_{-t}\omega)), \mathcal{A}(\omega)) = 0,$$

where d is the Hausdorff semi-distance.

Definition (Inclusion-Closed Collection). A collection  $\mathcal{D}$  of random subsets of X is called inclusion closed if  $\{D(\omega)\}_{\omega\in\Omega}\in\mathcal{D}$  and  $\tilde{D}(\omega)\subseteq D(\omega)$  for all  $\omega\in\Omega$  imply  $\tilde{D}\in\mathcal{D}$ .

Proposition (see, e.g., Bates-Lisei-Lu, 2006). Let  $\mathcal{D}$  be inclusion closed and  $\Phi$  be continuous on X over  $(\Omega, \mathcal{F}, P, (\theta_t)_{t \in \mathbb{R}})$ . If  $\Phi$  has a closed absorbing set  $\{K(\omega)\}_{\omega \in \Omega}$  in  $\mathcal{D}$  and is also  $\mathcal{D}$ -pullback asymptotically compact in X, then  $\Phi$  has a unique  $\mathcal{D}$ -random attractor  $\{\mathcal{A}(\omega)\}_{\omega \in \Omega}$ :

$$\mathcal{A}(\omega) = \bigcap_{\tau \geq 0} \ \overline{\bigcup_{t \geq \tau} \Phi(t, \theta_{-t}\omega, K(\theta_{-t}\omega))}.$$

# The stochastic wave equation on $\mathbb{R}^3$ :

$$u_{tt} + \alpha u_t - \Delta u + \lambda u + f(x, u) = g(x) + h(x) \frac{dw}{dt}.$$

The nonlinearity f and its antiderivative F satisfy, for some  $\gamma \in [1,3]$  ,

$$|f(x,u)| \le c_1 |u|^{\gamma} + \phi_1(x),$$

$$|f'_u(x,u)| \le c_2 |u|^{\gamma-1} + \phi_2(x),$$

$$f(x,u)u - c_3 F(x,u) \ge \phi_3(x),$$

$$F(x,u) \ge c_4 |u|^{\gamma+1} - \phi_4(x),$$

Example.  $f(u) = |u|^{\gamma - 1}u$ ,  $\gamma = 3$ : critical.

# **Stochastic Wave Equation**

# The probability space $(\Omega,\mathcal{F},P)$ is given by

- $\Omega = \{ \omega \in C(\mathbb{R}, \mathbb{R}) : w(0) = 0 \}.$
- $\mathcal{F}$  is the Borel  $\sigma$ -algebra induced by the compact-open topology of  $\Omega$ .
- P is the Wiener measure on  $(\Omega, \mathcal{F})$ .

# The shift operator is given by

$$\theta_t \omega(\cdot) = \omega(\cdot + t) - \omega(t), \quad \omega \in \Omega, \quad t \in \mathbb{R}.$$

 $(\Omega, \mathcal{F}, P, (\theta_t)_{t \in \mathbb{R}})$  is a metric dynamical system.

# **Stochastic Wave Equation**

# **Change of variables:**

$$z = u_t + \delta u, \quad \delta > 0.$$

# The system for (u, z) is given by

$$\frac{\partial u}{\partial t} + \delta u = z,$$

$$\frac{\partial z}{\partial t} + (\alpha - \delta)z + (\lambda + \delta^2 - \alpha \delta)u - \Delta u + f(x, u) = g + h\frac{dw}{dt},$$

### with the initial conditions:

$$u(x,\tau) = u_{\tau}(x), \quad z(x,\tau) = z_{\tau}(x).$$

# Change of variables:

$$v(t, \tau, \omega, v_{\tau}) = z(t, \tau, \omega, z_{\tau}) - h\omega(t).$$

# **Stochastic Wave Equation**

# The system for (u, v) is given by

$$\frac{\partial u}{\partial t} + \delta u - v = h\omega(t),$$

$$\frac{\partial v}{\partial t} + (\alpha - \delta)v + (\lambda + \delta^2 - \alpha \delta)u - \Delta u + f(x, u) = g + (\delta - \alpha)h\omega(t),$$

#### with the initial conditions:

$$u(x,\tau) = u_{\tau}(x), \ v(x,\tau) = v_{\tau}(x) = z_{\tau}(x) - h(x)\omega(\tau).$$

This problem is well-posed in  $H^1(\mathbb{R}^3) imes L^2(\mathbb{R}^3)$ .

z is given by  $z(t, \tau, \omega, z_{\tau}) = v(t, \tau, \omega, v_{\tau}) + h\omega(t)$ .

# Let $\Phi$ be a mapping given by

$$\Phi: \mathbb{R}^+ \times \Omega \times (H^1(\mathbb{R}^3) \times L^2(\mathbb{R}^3)) \to H^1(\mathbb{R}^3) \times L^2(\mathbb{R}^3),$$

$$\Phi(t,\omega,(u_0,v_0)) = (u(t,0,\omega,u_0),z(t,0,\omega,z_0)),$$
 where  $z(t,0,\omega,z_0) = v(t,0,\omega,v_0) + h\omega(t).$ 

 $\Phi$  is a continuous random dynamical system on  $H^1(\mathbb{R}^3) \times L^2(\mathbb{R}^3)$  over  $(\Omega, \mathcal{F}, P, (\theta_t)_{t \in \mathbb{R}})$ .

$$\mathcal{D} = \{ \{B(\omega)\}_{\omega \in \Omega} : B \text{ is temped in } H^1(\mathbb{R}^3) \times L^2(\mathbb{R}^3) \}.$$

# Random Absorbing Set

Lemma. For every  $B=\{B(\omega)\}_{\omega\in\Omega}\in\mathcal{D}$  and P-a.e.  $\omega\in\Omega$ , there exists  $T=T(\omega,B)<0$  such that for all  $\tau\leq T$  and  $t\in[\tau,0]$ ,

$$||u(t,\tau,\omega,u_{\tau})||_{H^{1}(\mathbb{R}^{3})}^{2} + ||v(t,\tau,\omega,v_{\tau})||^{2} \le e^{-\sigma t} r(\omega),$$

where  $\sigma > 0$  is a constant, and  $r(\omega)$  is tempered.

Particularly, for t = 0, we have:

$$||u(0,\tau,\omega,u_{\tau})||_{H^{1}(\mathbb{R}^{3})}^{2} + ||v(0,\tau,\omega,v_{\tau})||^{2} \leq r(\omega).$$

A random absorbing set is given by:

$$K(\omega) = \{(u, v) \in H^1(\mathbb{R}^3) \times L^2(\mathbb{R}^3) : ||u||_{H^1}^2 + ||v||^2 \le r(\omega)\}$$

#### **Uniform Tail Estimates**

Lemma. For every  $\epsilon>0$ ,  $B=\{B(\omega)\}_{\omega\in\Omega}$  and P-a.e.  $\omega\in\Omega$ , there exist  $T=T(\epsilon,\omega,B)<0$  and  $K(\epsilon,\omega)>0$  such that for all  $\tau\leq T$  and  $t\in[\tau,0]$ ,

$$\int_{|x| \ge K} \left( |u(t, \tau, \omega, u_{\tau})|^2 + |\nabla u(t, \tau, \omega, u_{\tau})|^2 \right) dx \le \epsilon e^{-\sigma t},$$

$$\int_{|x| \ge K} |v(t, \tau, \omega, v_{\tau})|^2 dx \le \epsilon e^{-\sigma t},$$

where  $\sigma$  is a positive deterministic constant.

The estimates for t=0 are of particular interest.

Asymptotic compactness: For P-a.e.  $\omega \in \Omega$ ,  $\{\Phi(t_n,\theta_{-t_n}\omega,(u_{0,n},v_{0,n}))\}$  has a convergent subsequence in  $H^1(\mathbb{R}^3)\times L^2(\mathbb{R}^3)$  provided  $t_n\to\infty$ ,  $B=\{B(\omega)\}_{\omega\in\Omega}\in\mathcal{D}$  and  $(u_{0,n},v_{0,n})\in B(\theta_{-t_n}\omega)$ .

# Idea of proof:

• By tail estimates,  $\forall \epsilon > 0$ ,  $\exists K(\epsilon), N(\epsilon) > 0$ :

$$\|\Phi(t_n, \theta_{-t_n}\omega, (u_{0,n}, v_{0,n}))\|_{H^1(\mathbb{R}^3 \setminus Q_K) \times L^2(\mathbb{R}^3 \setminus Q_K)} \le \epsilon,$$

for 
$$n \geq N$$
 and  $Q_K = \{x \in \mathbb{R}^3 : |x| \leq K(\epsilon)\}.$ 

• Prove  $\Phi$  is asymptotically compact in  $H^1(Q_K) \times L^2(Q_K)$  by a decomposition trick.

Let  $\psi$  be a smooth function such that

$$\psi(s) = 1$$
 if  $|s| \le 1$ ;  $\psi(s) = 0$  if  $|s| \ge 2$ .

Given  $k \geq 1$ , set  $\tilde{u} = \psi(\frac{|x|}{k})u$  and  $\tilde{v} = \psi(\frac{|x|}{k})v$ .

The system for  $(\tilde{u}, \tilde{v})$  is defined on  $Q_{2k}$ :

$$\tilde{u}_t + \delta \tilde{u} - \tilde{v} = \psi h \omega(t),$$

$$\tilde{v}_t + (\alpha - \delta)\tilde{v} + (\lambda + \delta^2 - \alpha\delta)\tilde{u} - \Delta\tilde{u} + \psi f(x, u)$$
$$= \psi g + (\delta - \alpha)\psi h\omega(t) - u\Delta\psi - 2\nabla\psi\nabla u,$$

with zero boundary conditions.

# Consider the eigenvalue problem:

$$-\Delta \tilde{u} = \lambda \tilde{u}$$
 in  $Q_{2k}$ , with  $\tilde{u}|_{\partial Q_{2k}} = 0$ .

**Eigenvalues:**  $\lambda_1 \leq \lambda_2 \leq \ldots \leq \lambda_n \to \infty$ .

Eigenfunctions:  $\{e_n\}_{n=1}^{\infty}$ , a basis of  $L^2(Q_{2k})$ .

$$X_n = \operatorname{span}\{e_1, \cdots, e_n\}$$
 and  $P_n: L^2(Q_{2k}) \to X_n$ .

Lemma. For every  $\epsilon>0$ ,  $B=\{B(\omega)\}_{\omega\in\Omega}\in\mathcal{D}$  and P-a.e.  $\omega\in\Omega$ , there exist  $K=K(\omega,\epsilon)>0$ ,  $N=N(\omega,\epsilon)>0$  and  $T=T(B,\omega,\epsilon)<0$  such that for all  $k\geq K$ ,  $n\geq N$  and  $\tau\leq T$ ,

$$||(I-P_n)\tilde{u}(0,\tau,\omega)||_{H_0^1(Q_{2k})} + ||(I-P_n)\tilde{v}(0,\tau,\omega)||_{L^2(Q_{2k})} \le \epsilon.$$

Proof. Set  $\tilde{u}_n = (I - P_n)\tilde{u}$  and  $\tilde{v}_n = (I - P_n)\tilde{v}$ .

$$\frac{d}{dt} (\|\tilde{v}_n\|^2 + \alpha_1 \|\tilde{u}_n\|^2 + \|\nabla \tilde{u}_n\|^2 + 2(\psi f(x, u), \tilde{u}_n))$$

$$+\sigma \left(\|\tilde{v}_n\|^2 + \alpha_1\|\tilde{u}_n\|^2 + \|\nabla \tilde{u}_n\|^2 + 2(\psi f(x, u), \tilde{u}_n)\right)$$

$$\leq c\lambda_{n+1}^{\frac{\gamma-3}{2}} \left(\|v\|^6 + \|u\|_{H^1}^{3\gamma-3}\right) + \frac{c}{k^2} \|u\|_{H^1}^2 + \dots$$

# For $\gamma < 3$ and sufficiently large n and k:

$$\frac{d}{dt} (\|\tilde{v}_n\|^2 + \alpha_1 \|\tilde{u}_n\|^2 + \|\nabla \tilde{u}_n\|^2 + 2(\psi f(x, u), \tilde{u}_n))$$

$$+\sigma \left( \|\tilde{v}_n\|^2 + \alpha_1 \|\tilde{u}_n\|^2 + \|\nabla \tilde{u}_n\|^2 + 2(\psi f(x, u), \tilde{u}_n) \right)$$

$$\leq \epsilon \left( \|v\|^6 + \|u\|_{H^1}^{3\gamma - 3} \right) + \epsilon \|u\|_{H^1}^2 + \dots$$

Asymptotic compactness:  $\{\Phi(t_n, \theta_{-t_n}\omega, (u_{0,n}, v_{0,n}))\}$  has a convergent subsequence in  $H^1(\mathbb{R}^3) \times L^2(\mathbb{R}^3)$  if  $t_n \to \infty$  and  $(u_{0,n}, v_{0,n}) \in B(\theta_{-t_n}\omega)$ .

#### **Proof:**

ullet Tail estimates:  $\forall \epsilon$ ,  $\exists K$ ,  $\exists N$  s.t. for  $n \geq N$ ,

$$\|\Phi(t_n, \theta_{-t_n}\omega, (u_{0,n}, v_{0,n}))\|_{H^1(\mathbb{R}^3 \setminus Q_K) \times L^2(\mathbb{R}^3 \setminus Q_K)} \le \epsilon,$$

ullet There is m>0 such that for  $n\geq N$ ,

$$||(I-P_m)\Phi(t_n, \theta_{-t_n}\omega, (u_{0,n}, v_{0,n}))||_{H^1(Q_K)\times L^2(Q_K)} \le \epsilon.$$

•  $P_m(\Phi(t_n, \theta_{-t_n}\omega, (u_{0,n}, v_{0,n})))$  is bounded in the finite dimensional space  $P_m(H^1(Q_K) \times L^2(Q_K))$ .

Method: Tail estimates and energy equations.

Idea of the energy equation approach:

$$u_n \to u \text{ in } L^2 \Longleftrightarrow u_n \rightharpoonup u \text{ in } L^2 \text{ and } \|u_n\|_{L^2} \to \|u\|_{L^2}$$

# The energy equation approach was

- introduced by J. M. Ball (1997, 2004);
- used by Rosa (1998); Moise, Rosa and X.Wang (1998); Ju (2000, 2001); Goubet and Rosa (2002); Brzezniak and Li (2006), and many others.

# $H^1 \times L^2$ energy of wave equation:

$$\frac{d}{dt}E(u,v) + 4\sigma E(u,v) = \Psi(u,v),$$

$$E(u,v) = ||v||^2 + (\lambda + \delta^2 - \alpha \delta) ||u||^2 + ||\nabla u||^2 + 2 \int_{\mathbb{R}^3} F(x,u) dx,$$

$$\Psi(u, v) = -2(\alpha - \delta - 2\sigma) \|v\|^2 - 2(\delta - 2\sigma)(\lambda + \delta^2 - \alpha\delta) \|u\|^2$$

$$-2(\delta-2\sigma)\|\nabla u\|^{2}+8\sigma\int_{\mathbb{R}^{3}}F(x,u)dx-2\delta\int_{\mathbb{R}^{3}}f(x,u)udx$$
$$+2(\lambda+\delta^{2}-\alpha\delta)(u,h)\omega(t)+2(\nabla u,\nabla h)\omega(t)$$
$$+2\omega(t)\int_{\mathbb{R}^{3}}f(x,u)h(x)dx+2(g,v)+2(\delta-\alpha)(v,h)\omega(t).$$

# $H^1 \times L^2$ energy equation:

$$E(u(t,\tau,\omega,u_{\tau}),v(t,\tau,\omega,v_{\tau})) = e^{-4\sigma(t-\tau)}E(u_{\tau},v_{\tau})$$
$$+ \int_{\tau}^{t} e^{4\sigma(\xi-t)}\Psi(u(\xi,\tau,\omega,u_{\tau}),v(\xi,\tau,\omega,v_{\tau}))d\xi.$$

# Lemma (asymptotic compactness)

 $\{\Phi(t_n,\theta_{-t_n}\omega,(u_{0,n},v_{0,n}))\}$  is precompact in  $H^1(\mathbb{R}^3)\times L^2(\mathbb{R}^3)$  if  $t_n\to\infty$  and  $(u_{0,n},v_{0,n})\in B(\theta_{-t_n}\omega)$ ; that is,

 $\{(u(0,-t_n,\omega,u_{0,n}),v(0,-t_n,\omega,v_{0,n}))\}$  has a convergent subsequence in  $H^1(\mathbb{R}^3)\times L^2(\mathbb{R}^3)$  if  $t_n\to\infty$  and  $(u_{0,n},v_{0,n})\in B(\theta_{-t_n}\omega)$ .

#### Proof.

ullet There is N such that for all  $n \geq N$ ,

$$||u(0, -t_n, \omega, u_{0,n})||_{H^1}^2 + ||v(0, -t_n, \omega, v_{0,n})||^2 \le R(\omega).$$

• There is  $(\tilde{u},\tilde{v})\in H^1(\mathbb{R}^3)\times L^2(\mathbb{R}^3)$  such that, up to a subsequence,

$$(u(0, -t_n, \omega, u_{0,n}), v(0, -t_n, \omega, v_{0,n})) \to (\tilde{u}, \tilde{v})$$
 weakly,

# This implies that

$$\liminf_{n \to \infty} \|(u(0, -t_n, \omega, u_{0,n}), v(0, -t_n, \omega, v_{0,n}))\| \ge \|(\tilde{u}, \tilde{v})\|$$

## We only need to prove

$$\limsup_{n \to \infty} \|(u(0, -t_n, \omega, u_{0,n}), v(0, -t_n, \omega, v_{0,n}))\| \le \|(\tilde{u}, \tilde{v})\|$$

• Notice that, for any fixed  $m \ge 1$ ,

$$u(0, -t_n, \omega, u_{0,n}) = u(0, -m, \omega, u(-m, -t_n, \omega, u_{0,n})),$$

and

$$v(0, -t_n, \omega, v_{0,n}) = v(0, -m, \omega, v(-m, -t_n, \omega, v_{0,n})).$$

• Energy equation in  $H^1 \times L^2$ :

$$E(u(t,\tau,\omega,\mathbf{u_{\tau}}),v(t,\tau,\omega,\mathbf{v_{\tau}})) = e^{-4\sigma(t-\tau)}E(u_{\tau},v_{\tau})$$

$$+ \int_{\tau}^{t} e^{4\sigma(\xi-t)} \Psi(u(\xi,\tau,\omega,u_{\tau}),v(\xi,\tau,\omega,v_{\tau})) d\xi.$$

$$\begin{split} E \Big( u \Big( 0, -t_n, \omega, u_{0,n} \big), v \Big( 0, -t_n, \omega, v_{0,n} \big) \Big) \\ &= e^{-4\sigma m} E \big( u \big( -m, -t_n, \omega, u_{0,n} \big), v \big( -m, -t_n, \omega, v_{0,n} \big) \big) \\ &- 2 \big( \alpha - \delta - 2\sigma \big) \int_{-m}^{0} e^{4\sigma \xi} \| v \big( \xi, -m, \omega, v \big( -m, -t_n, \omega, v_{0,n} \big) \big) \|^2 d\xi \\ &- 2 \big( \delta - 2\sigma \big) \big( \lambda + \delta^2 - \alpha \delta \big) \int_{-m}^{0} e^{4\sigma \xi} \| u \big( \xi, -m, \omega, u \big( -m, -t_n, \omega, u_{0,n} \big) \big) \|^2 d\xi \\ &- 2 \big( \delta - 2\sigma \big) \int_{-m}^{0} e^{4\sigma \xi} \| \nabla u \big( \xi, -m, \omega, u \big( -m, -t_n, \omega, u_{0,n} \big) \big) \|^2 d\xi \\ &+ 8\sigma \int_{-m}^{0} e^{4\sigma \xi} \int_{\mathbb{R}^3} F \big( x, u \big( \xi, -m, \omega, u \big( -m, -t_n, \omega, u_{0,n} \big) \big) \big) dx d\xi \\ &- 2\delta \int_{-m}^{0} e^{4\sigma \xi} \int_{\mathbb{R}^3} u \big( \xi, -m, \omega, u \big( -m, -t_n, \omega, u_{0,n} \big) \big) \times f \big( x, u \big( \xi, -m, \omega, u \big) \\ &+ 2 \big( \lambda + \delta^2 - \alpha \delta \big) \int_{-m}^{0} e^{4\sigma \xi} \int_{\mathbb{R}^3} h \big( x \big) u \big( \xi, -m, \omega, u \big( -m, -t_n, \omega, u_{0,n} \big) \big) \omega \big( \xi \big) \\ &+ 2 \int_{-m}^{0} e^{4\sigma \xi} \int_{\mathbb{R}^3} \nabla h \big( x \big) \cdot \nabla u \big( \xi, -m, \omega, u \big( -m, -t_n, \omega, u_{0,n} \big) \big) \omega \big( \xi \big) \\ &+ 2 \int_{-m}^{0} e^{4\sigma \xi} \int_{\mathbb{R}^3} h \big( x \big) f \big( x, u \big( \xi, -m, \omega, u \big( -m, -t_n, \omega, u_{0,n} \big) \big) \omega \big( \xi \big) \\ &+ 2 \int_{-m}^{0} e^{4\sigma \xi} \int_{\mathbb{R}^3} g \big( x \big) v \big( \xi, -m, \omega, v \big( -m, -t_n, \omega, v_{0,n} \big) \big) dx d\xi \\ &+ 2 \big( \delta - \alpha \big) \int_{-m}^{0} e^{4\sigma \xi} \int_{\mathbb{R}^3} h \big( x \big) v \big( \xi, -m, \omega, v \big( -m, -t_n, \omega, v_{0,n} \big) \big) \omega \big( \xi \big) dx d\xi. \end{split}$$

ullet For any fixed m, there is  $(\tilde{u}_m, \tilde{v}_m) \in H^1 \times L^2$ :

$$\tilde{u} = u(0, -m, \omega, \tilde{\underline{u}}_m)$$
 and  $\tilde{v} = v(0, -m, \omega, \tilde{v}_m),$ 

• Energy equation in  $H^1 \times L^2$ :

$$E(u(t,\tau,\omega,\mathbf{u_{\tau}}),v(t,\tau,\omega,\mathbf{v_{\tau}})) = e^{-4\sigma(t-\tau)}E(u_{\tau},v_{\tau})$$

$$+ \int_{\tau}^{t} e^{4\sigma(\xi-t)} \Psi(u(\xi,\tau,\omega,u_{\tau}),v(\xi,\tau,\omega,v_{\tau})) d\xi.$$

$$E(\tilde{u}, \tilde{v}) = e^{-4\sigma m} E(\tilde{u}_m, \tilde{v}_m)$$

$$-2(\alpha - \delta - 2\sigma) \int_{-m}^{0} e^{4\sigma \xi} ||v(\xi, -m, \omega, \tilde{v}_m)||^2 d\xi$$

$$-2(\delta - 2\sigma)(\lambda + \delta^2 - \alpha\delta) \int_{-m}^{0} e^{4\sigma \xi} ||u(\xi, -m, \omega, \tilde{u}_m)||^2 d\xi$$

$$-2(\delta - 2\sigma) \int_{-m}^{0} e^{4\sigma \xi} ||\nabla u(\xi, -m, \omega, \tilde{u}_m)||^2 d\xi$$

$$+8\sigma \int_{-m}^{0} e^{4\sigma \xi} \int_{\mathbb{R}^3} F(x, u(\xi, -m, \omega, \tilde{u}_m)) dx d\xi$$

$$-2\delta \int_{-m}^{0} e^{4\sigma \xi} \int_{\mathbb{R}^3} u(\xi, -m, \omega, \tilde{u}_m) \times f(x, u(\xi, -m, \omega, \tilde{u}_m))$$

$$+2(\lambda + \delta^2 - \alpha\delta) \int_{-m}^{0} e^{4\sigma \xi} \int_{\mathbb{R}^3} h(x) u(\xi, -m, \omega, \tilde{u}_m) \omega(\xi)$$

$$+2 \int_{-m}^{0} e^{4\sigma \xi} \int_{\mathbb{R}^3} \nabla h(x) \cdot \nabla u(\xi, -m, \omega, \tilde{u}_m) \omega(\xi) dx d\xi$$

$$+2 \int_{-m}^{0} e^{4\sigma \xi} \int_{\mathbb{R}^3} h(x) f(x, u(\xi, -m, \omega, \tilde{u}_m)) \omega(\xi)$$

$$+2 \int_{-m}^{0} e^{4\sigma \xi} \int_{\mathbb{R}^3} g(x) v(\xi, -m, \omega, \tilde{v}_m) dx d\xi$$

$$+2(\delta - \alpha) \int_{-m}^{0} e^{4\sigma \xi} \int_{\mathbb{R}^3} h(x) v(\xi, -m, \omega, \tilde{v}_m) \omega(\xi) dx d\xi.$$

$$\begin{split} E \big( u \big( 0, -t_n, \omega, u_{0,n} \big), v \big( 0, -t_n, \omega, v_{0,n} \big) \big) \\ &= e^{-4\sigma m} E \big( u (-m, -t_n, \omega, u_{0,n}), v (-m, -t_n, \omega, v_{0,n}) \big) \\ &- 2 (\alpha - \delta - 2\sigma) \int_{-m}^{0} e^{4\sigma \xi} \| v (\xi, -m, \omega, v (-m, -t_n, \omega, v_{0,n})) \|^2 d\xi \\ &- 2 (\delta - 2\sigma) \big( \lambda + \delta^2 - \alpha \delta \big) \int_{-m}^{0} e^{4\sigma \xi} \| u (\xi, -m, \omega, u (-m, -t_n, \omega, u_{0,n})) \|^2 d\xi \\ &- 2 (\delta - 2\sigma) \int_{-m}^{0} e^{4\sigma \xi} \| \nabla u (\xi, -m, \omega, u (-m, -t_n, \omega, u_{0,n})) \|^2 d\xi \\ &+ 8\sigma \int_{-m}^{0} e^{4\sigma \xi} \int_{\mathbb{R}^3} F(x, u (\xi, -m, \omega, u (-m, -t_n, \omega, u_{0,n}))) dx d\xi \\ &- 2\delta \int_{-m}^{0} e^{4\sigma \xi} \int_{\mathbb{R}^3} u (\xi, -m, \omega, u (-m, -t_n, \omega, u_{0,n})) \times f(x, u (\xi, -m, \omega, u)) \\ &+ 2 (\lambda + \delta^2 - \alpha \delta) \int_{-m}^{0} e^{4\sigma \xi} \int_{\mathbb{R}^3} h(x) u (\xi, -m, \omega, u (-m, -t_n, \omega, u_{0,n})) \omega(\xi) \\ &+ 2 \int_{-m}^{0} e^{4\sigma \xi} \int_{\mathbb{R}^3} \nabla h(x) \cdot \nabla u (\xi, -m, \omega, u (-m, -t_n, \omega, u_{0,n})) \omega(\xi) dx d\xi \\ &+ 2 \int_{-m}^{0} e^{4\sigma \xi} \int_{\mathbb{R}^3} h(x) f(x, u (\xi, -m, \omega, u (-m, -t_n, \omega, u_{0,n}))) \omega(\xi) \\ &+ 2 \int_{-m}^{0} e^{4\sigma \xi} \int_{\mathbb{R}^3} g(x) v (\xi, -m, \omega, v (-m, -t_n, \omega, v_{0,n})) dx d\xi \\ &+ 2 (\delta - \alpha) \int_{-m}^{0} e^{4\sigma \xi} \int_{\mathbb{R}^3} h(x) v (\xi, -m, \omega, v (-m, -t_n, \omega, v_{0,n})) \omega(\xi) dx d\xi. \end{split}$$

## For instance, the following convergence holds:

$$\lim_{n \to \infty} \int_{-m}^{0} e^{4\sigma\xi} \int_{\mathbb{R}^3} F(x, u(\xi, -m, \omega, u(-m, -t_n, \omega, u_{0,n})))$$

$$= \int_{-m}^{0} e^{4\sigma\xi} \int_{\mathbb{R}^3} F(x, u(\xi, -m, \omega, \tilde{u}_m)) dx d\xi,$$

#### which is implied by

$$|\int_{-m}^{0} e^{4\sigma\xi} \int_{\mathbb{R}^3} \left( F(x, u(\xi, -m, \omega, u(-m, -t_n, \omega, u_{0,n}))) - F(x, u(\xi, -m, \omega, \tilde{u}_m)) \right) |$$

$$\leq \int_{-m}^{0} e^{4\sigma\xi} \int_{|x|>k} |F(x, u(\xi, -m, \omega, u(-m, -t_n, \omega, u_{0,n}))) - F(x, u(\xi, -m, \omega, \tilde{u}_m))|$$

$$+ |\int_{-m}^{0} e^{4\sigma\xi} \int_{|x| < k} F(x, u(\xi, -m, \omega, u(-m, -t_n, \omega, u_{0,n}))) - F(x, u(\xi, -m, \omega, \tilde{u}_m))|.$$

#### Finally, we have

$$\limsup_{n \to \infty} E(u(0, -t_n, \omega, u_{0,n}), v(0, -t_n, \omega, v_{0,n})) \le E(\tilde{u}, \tilde{v}),$$

# which implies that

$$\limsup_{n \to \infty} \|(u(0, -t_n, \omega, u_{0,n}), v(0, -t_n, \omega, v_{0,n}))\| \le \|(\tilde{u}, \tilde{v})\|.$$

#### We also have

$$\liminf_{n \to \infty} \|(u(0, -t_n, \omega, u_{0,n}), v(0, -t_n, \omega, v_{0,n}))\| \ge \|(\tilde{u}, \tilde{v})\|.$$

#### Then it follows that

$$\lim_{n \to \infty} \|(u(0, -t_n, \omega, u_{0,n}), v(0, -t_n, \omega, v_{0,n}))\| = \|(\tilde{u}, \tilde{v})\|,$$

# which along with the weak convergence yields

$$(u(0,-t_n,\omega,u_{0,n}),v(0,-t_n,\omega,v_{0,n})) \rightarrow (\tilde{u},\tilde{v})$$
 strongly.

#### **Existence of Random Attractors**

Theorem. The random dynamical system  $\Phi$  has a unique  $\mathcal{D}$ -random attractor  $\{\mathcal{A}(\omega)\}_{\omega\in\Omega}$  in  $H^1(\mathbb{R}^3)\times L^2(\mathbb{R}^3)$ , i.e., for P-a.e.  $\omega\in\Omega$ ,

- $\mathcal{A}(\omega)$  is compact in  $L^2(\mathbb{R}^n)$ .
- $\{A(\omega)\}_{\omega \in \Omega}$  is invariant:

$$\phi(t,\omega,\mathcal{A}(\omega)) = \mathcal{A}(\theta_t\omega), \quad \forall \ t \geq 0.$$

•  $\{A(\omega)\}_{\omega \in \Omega}$  attracts every tempered random subset  $\{B(\omega)\}_{\omega \in \Omega} \in \mathcal{D}$ :

$$\lim_{t \to \infty} d_{H^1 \times L^2}(\phi(t, \theta_{-t}\omega, B(\theta_{-t}\omega)), \mathcal{A}(\omega)) = 0.$$

#### **Remarks:**

• Existence of attractors in

$$\mathcal{D}_{\sigma} = \{ D = \{ D(\omega) \}_{\omega \in \Omega} : \lim_{t \to \infty} e^{-\sigma t} || D(\theta_{-t}\omega) || = 0 \}.$$

• Existence of invariant measures.

#### **Future work:**

- Uniqueness of invariant measures.
- Structures of attractors.