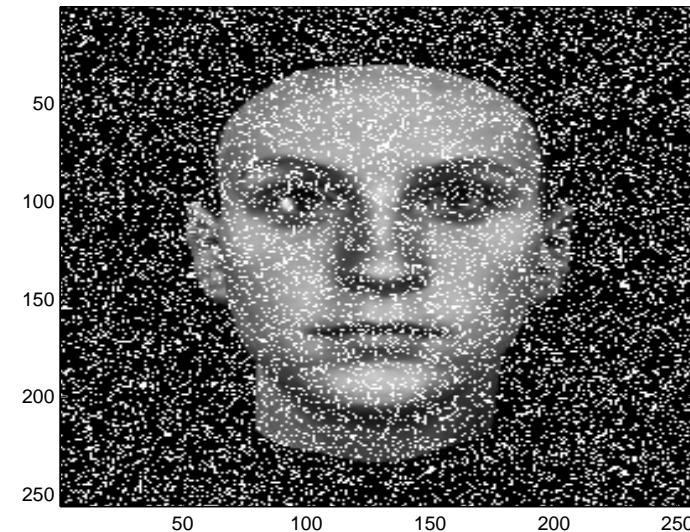
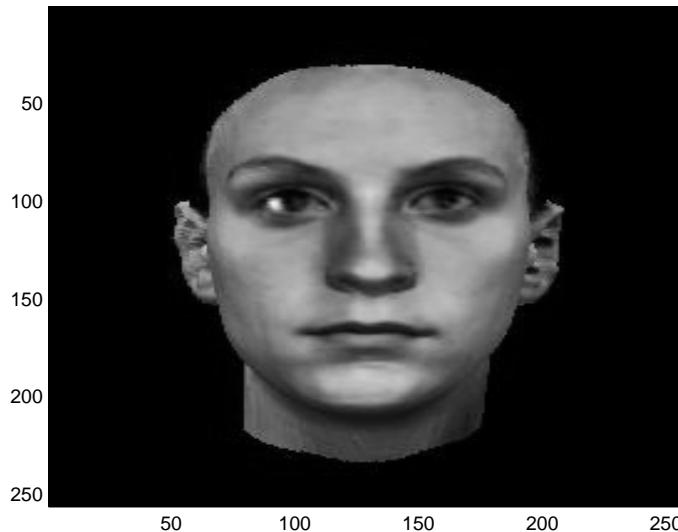
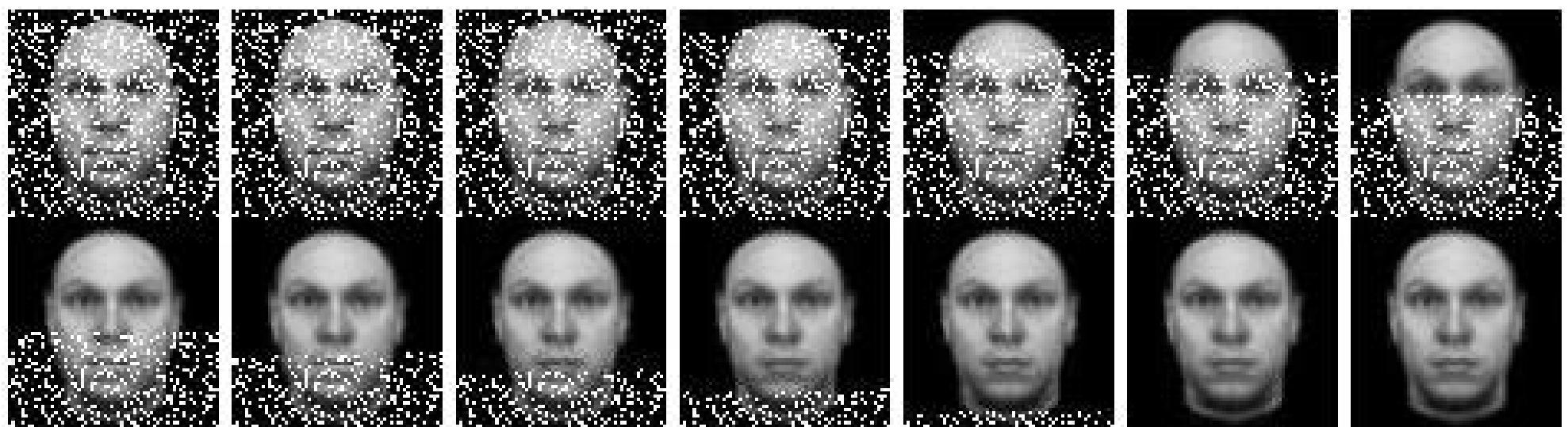


# Image Denoising via Solution Paths



Joint work with Li Wang (PhD student, University of Michigan)

# Image Denoising via Solution Paths



# Image Denoising via Solution Paths



# Sparse Covariance Estimation When Variables are Ordered

Ji Zhu  
Assistant Professor  
Statistics Department  
University of Michigan

# Acknowledgment

Joint work with Liza Levina (Assistant Professor,  
Department of Statistics, University of Michigan)



# Outline

- Background
- Decomposing the covariance matrix
- Covariance estimation via regression
- LASSO penalty vs. AB penalty
- Numerical results
- Concluding remarks

# Why Covariance Matrix

Many statistical and machine learning tools require an estimate of a covariance matrix.

- PCA
- LDA/QDA
- Graphical models
- :

# Basic Background

- Observe  $n$  i.i.d. samples, often from  $\text{Normal}(\mathbf{0}, \Sigma_{p \times p})$

$$\mathbf{X}_{n \times p}^* = \begin{pmatrix} x_{11} & x_{12} & \cdots & \cdots & x_{1p} \\ x_{21} & x_{22} & \cdots & \cdots & x_{2p} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ x_{n1} & \cdots & \cdots & \cdots & x_{np} \end{pmatrix}$$

$$\Sigma_{p \times p} = \begin{pmatrix} \text{Var}(X_1) & \text{Cov}(X_1, X_2) & \cdots \\ \text{Cov}(X_2, X_1) & \text{Var}(X_2) & \cdots \\ \vdots & \vdots & \vdots \\ \text{Cov}(X_p, X_1) & \cdots & \cdots \end{pmatrix}$$

## Sample Covariance Matrix

- Wish to estimate  $\Sigma$
- Assuming the columns are centered, then the sample covariance matrix is

$$\hat{S} = \frac{1}{n-1} \mathbf{X}^{*\top} \mathbf{X}^*$$

# Beyond the Sample Covariance Matrix

- Although the sample covariance matrix is unbiased, it can be **extremely noisy**, especially when  $p$  is large (Johnstone, 2001)
- Shrinkage methods
  - Haff, 1980; Dey & Srinivasan, 1985; Friedman, 1989; Ledoit & Wolf, 2003
  - Dempster, 1972; Pourahmadi, 1999; Wu & Pourahmadi, 2003; Meinshausen & Bühlmann, 2006; Huang et al., 2006

# Our Focus

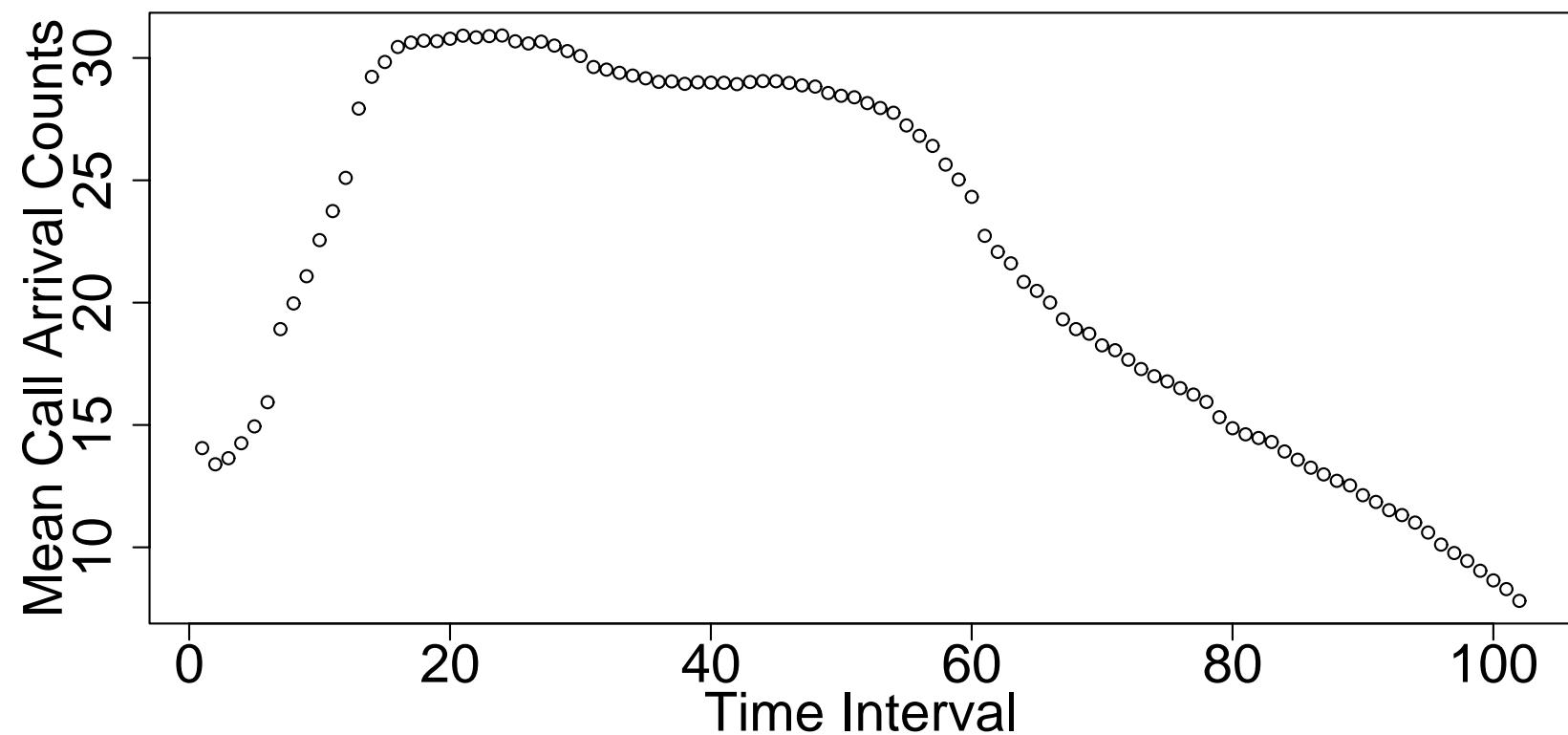
- We are interested in the case when there is an **intrinsic order** among the variables
- Examples:
  - $X_1, \dots, X_p$  are information collected over **time** (longitudinal study)
  - The indices  $1, \dots, p$  represent a meaningful order (**spectrum**)

## Example: Call Center

- Data were collected from a call center in a U.S. financial organization (Shen & Huang, 2005)
- Each day was divided into 102 time intervals
- $x_{ij}$ : number of calls arrived during the  $j$ th time interval on the  $i$ th day
- $n = 239$  days in year 2002
- Forecast the call arrival counts in the later half of a day using the arrival counts in the early half of the day

## Example: Call Center

Average mean counts over the 239 days



## Example: Call Center

Assume multivariate normality

$$\begin{pmatrix} \mathbf{X}^{(1)} \\ \mathbf{X}^{(2)} \end{pmatrix} \sim \text{Normal} \left( \begin{pmatrix} \boldsymbol{\mu}_1 \\ \boldsymbol{\mu}_2 \end{pmatrix}, \begin{pmatrix} \boldsymbol{\Sigma}_{11} & \boldsymbol{\Sigma}_{12} \\ \boldsymbol{\Sigma}_{21} & \boldsymbol{\Sigma}_{22} \end{pmatrix} \right)$$

Then

$$\mathbb{E}(\mathbf{X}^{(2)} | \mathbf{X}^{(1)}) = \boldsymbol{\mu}_2 + \boldsymbol{\Sigma}_{21} \boldsymbol{\Sigma}_{11}^{-1} (\mathbf{X}^{(1)} - \boldsymbol{\mu}_1)$$

# Example: Protein Mass Spectroscopy

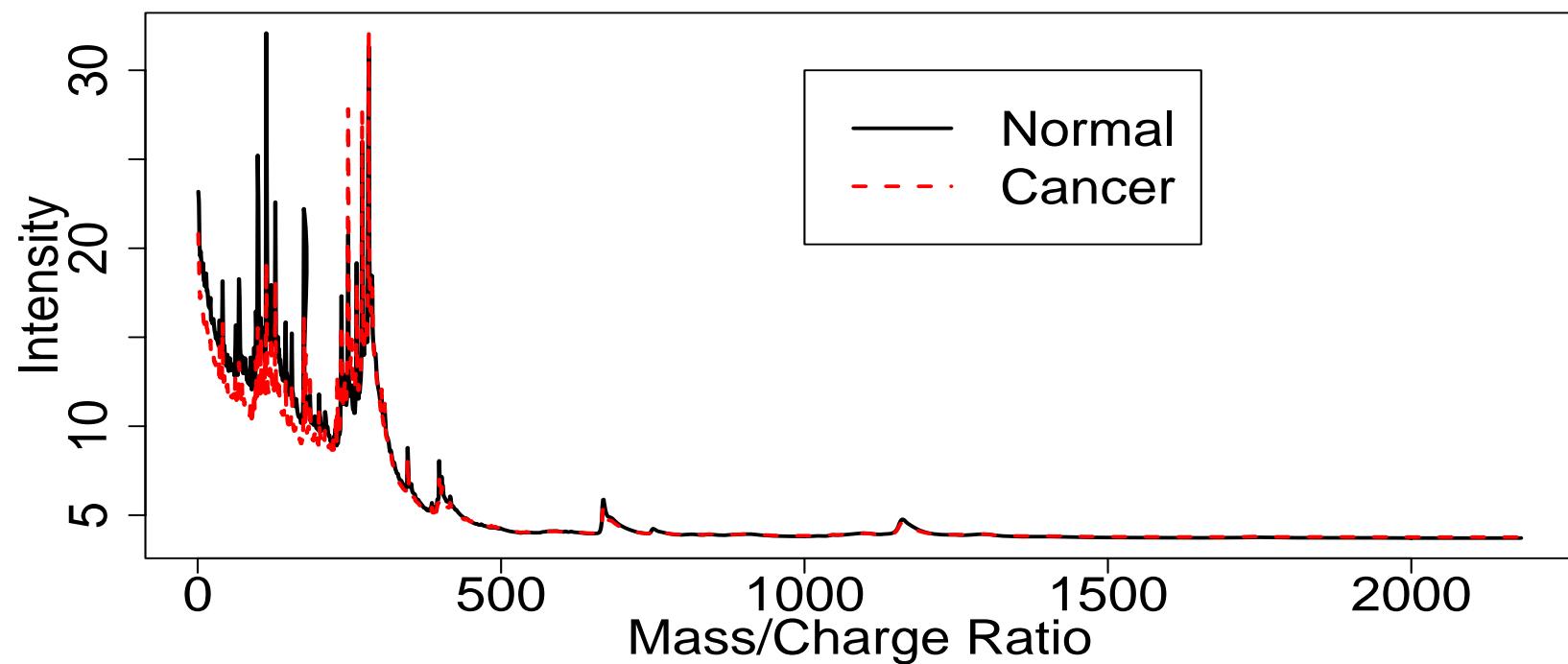
- Discriminate between healthy patients and prostate cancer patients using their blood serum samples
- For each sample  $i$ ,  $x_{ij}$  is the intensity at the  $j$ th mass over charge ratio ( $m/z$ ) of the constituent proteins
- Discriminant functions

$$\text{LDA} : \mathbf{x}^\top \boldsymbol{\Sigma}^{-1} \boldsymbol{\mu}_k - \frac{1}{2} \boldsymbol{\mu}_k^\top \boldsymbol{\Sigma}^{-1} \boldsymbol{\mu}_k, \quad k = 1, 2$$

$$\text{QDA} : \frac{1}{2} \ln |\boldsymbol{\Sigma}_k^{-1}| - \frac{1}{2} (\mathbf{x} - \boldsymbol{\mu}_k)^\top \boldsymbol{\Sigma}_k^{-1} (\mathbf{x} - \boldsymbol{\mu}_k), \quad k = 1, 2$$

# Example: Protein Mass Spectroscopy

Average spectra profiles for healthy patients and those with prostate cancer



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## Decomposition of $\Sigma$

The population covariance matrix can be re-written using the modified Cholesky decomposition (Pourahmadi 1999)

$$\mathbf{L}\boldsymbol{\Sigma}\mathbf{L}^\top = \mathbf{D}$$

where  $\mathbf{L}$  is a lower triangular matrix with diagonal elements equal to 1 and  $\mathbf{D}$  is a diagonal matrix.

$$\mathbf{L} = \begin{pmatrix} 1 & 0 & \cdots & \cdots \\ ? & 1 & 0 & \cdots \\ ? & ? & \ddots & 0 \\ ? & ? & \cdots & 1 \end{pmatrix}, \quad \mathbf{D} = \begin{pmatrix} d_1^2 & 0 & \cdots & \cdots \\ 0 & d_2^2 & 0 & \cdots \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \cdots & 0 & d_p^2 \end{pmatrix}$$

## Elements of $L$ and $D$

It turns out

$$X_1 = \epsilon_1$$

$$X_2 = \phi_{21} X_1 + \epsilon_2$$

$$X_3 = \phi_{32} X_2 + \phi_{31} X_1 + \epsilon_3$$

$$\vdots \quad \vdots$$

$$X_p = \phi_{p,p-1} X_{p-1} + \cdots + \phi_{p1} X_1 + \epsilon_p$$

Hence  $\mathbf{L}\mathbf{X} = \boldsymbol{\epsilon}$ , where  $L_{jj'} = -\phi_{jj'}$  for  $j > j'$ , and  $d_j^2 = \text{var}(\epsilon_j)$ . Notice  $\boldsymbol{\Sigma}^{-1} = \mathbf{L}^\top \mathbf{D}^{-1} \mathbf{L}$ .

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## Negative Log-likelihood

Denote  $\mathbf{x} = (x_1, \dots, x_p)^\top$ . If we assume Normality, the negative log-likelihood can be written as

$$\begin{aligned}\ell(\mathbf{x}, \Sigma) &= \ln |\Sigma| + \mathbf{x}^\top \Sigma^{-1} \mathbf{x} \\ &= \ln |\mathbf{D}| + \mathbf{x}^\top \mathbf{L}^\top \mathbf{D}^{-1} \mathbf{L} \mathbf{x} \\ &= \sum_{j=1}^p \ln d_j^2 + \sum_{j=1}^p \frac{\epsilon_j^2}{d_j^2}\end{aligned}$$

## Estimating $\phi_{jj'}$ and $d_j^2$

The negative log-likelihood on the training data

$\boldsymbol{x}_1, \dots, \boldsymbol{x}_n$

$$\begin{aligned}\ell(\boldsymbol{X}^*, \boldsymbol{\Sigma}) &= n \sum_{j=1}^p \ln d_j^2 + \sum_{j=1}^p \sum_{i=1}^n \frac{\epsilon_{ij}^2}{d_j^2} \\ &= \sum_{j=1}^p \ell_j(\boldsymbol{X}^*, \boldsymbol{\Sigma})\end{aligned}$$

## Estimating $\phi_{jj'}$ and $d_j^2$

The negative log-likelihood decomposes into

$$j = 1 \quad \ell_1(\mathbf{X}^*, \Sigma) = nd_1^2 + \frac{1}{d_1^2} \sum_{i=1}^n x_{i1}^2$$

$$j > 1 \quad \ell_j(\mathbf{X}^*, \Sigma) = nd_j^2 + \frac{1}{d_j^2} \sum_{i=1}^n (x_{ij} - \phi_{j,j-1}x_{i,j-1} - \cdots - \phi_{j1}x_{i1})^2$$

We can minimize them **separately** to find  $\hat{\phi}_{jj'}$  and  $\hat{d}_j^2$   
 (Each is essentially an OLS).

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# Regularization

In practice, shrinkage is necessary, so we consider

$$\min_{\phi_j, d_j} \ell_j(\mathbf{X}^*, \Sigma) + \lambda \cdot J(\phi_j)$$

where  $J(\phi_j)$  is a penalty term.

## LASSO Penalty

Using the  $L_1$ -norm (LASSO) penalty (Huang et al. 2006)

$$J(\boldsymbol{\phi}_j) = \sum_{j'=1}^{j-1} |\phi_{jj'}|$$

- Shrinkage
- Sparseness: some  $\hat{\phi}_{jj'} = 0$
- Sparse in  $\mathbf{L}$ , not necessarily in  $\boldsymbol{\Sigma}^{-1} = \mathbf{L}^\top \mathbf{D}^{-1} \mathbf{L}$

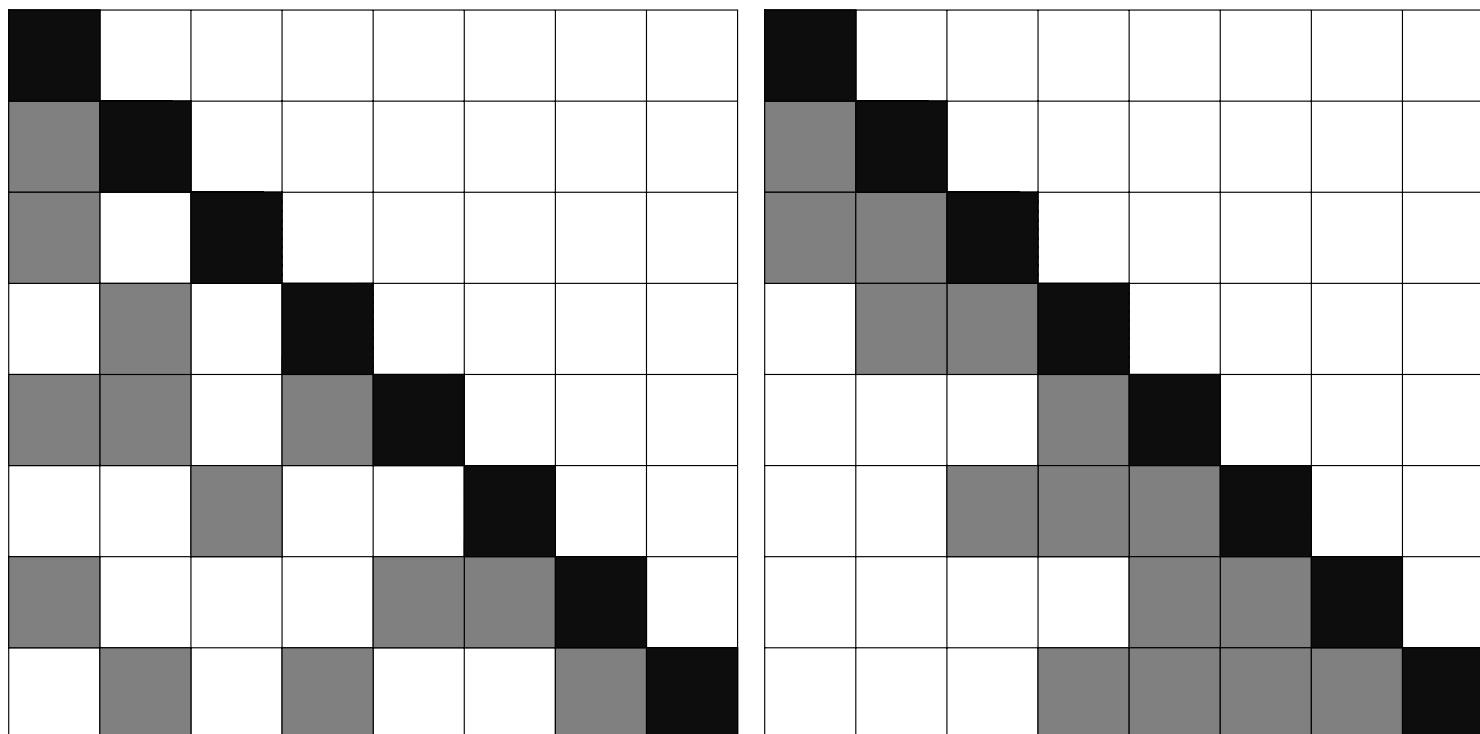
# Incorporating the Order Information

We propose (Hierarchical LASSO)

$$J(\boldsymbol{\phi}_j) = |\phi_{j,j-1}| + \frac{|\phi_{j,j-2}|}{|\phi_{j,j-1}|} + \frac{|\phi_{j,j-3}|}{|\phi_{j,j-2}|} + \dots + \frac{|\phi_{j,1}|}{|\phi_{j,2}|}$$

- Shrinkage
- Sparseness: If  $\hat{\phi}_{jk} = 0$  for some  $k$ , then  $\hat{\phi}_{jj'} = 0$  for all  $j' < k$ .
- Sparse in  $\mathbf{L}$  and  $\boldsymbol{\Sigma}^{-1}$
- Hierarchical LASSO  $\implies$  Adaptive Banding of  $\boldsymbol{\Sigma}^{-1}$

# LASSO vs Adaptive Banding (AB)



## Estimation

The penalized negative log-likelihood on  $\ell_j(\mathbf{X}^*, \Sigma)$  becomes

$$\begin{aligned} \min_{\phi_j, d_j} \quad & n \ln d_j^2 + \frac{1}{d_j^2} \sum_{i=1}^n (x_{ij} - \phi_{j,j-1} x_{i,j-1} - \cdots - \phi_{j1} x_{i1})^2 + \\ & + \lambda \cdot \left( |\phi_{j,j-1}| + \sum_{j'=2}^{j-1} \frac{|\phi_{j,j'-1}|}{|\phi_{j,j'}|} \right) \end{aligned}$$

## Iterative Procedure

1. Fix  $\phi_j$ , solve for  $d_j$
2. Fix  $d_j$ , solve for  $\phi_j$
3. Iterate between 1 and 2 until convergence

## Step 1

When  $\phi_j$  is fixed,  $n\hat{d}_j^2$  is the residual sum of squares

$$\hat{d}_j^2 = \frac{1}{n} \sum_{i=1}^n (x_{ij} - \phi_{j,j-1}x_{i,j-1} - \cdots - \phi_{j1}x_{i1})^2$$

## Step 2

When  $d_j$  is fixed, the criterion becomes

$$\begin{aligned} \min_{\phi_j} \quad & \frac{1}{d_{jj}^2} \sum_{i=1}^n (x_{ij} - \phi_{j,j-1}x_{i,j-1} - \cdots - \phi_{j1}x_{i1})^2 + \\ & + \lambda \cdot \left( |\phi_{j,j-1}| + \sum_{j'=2}^{j-1} \frac{|\phi_{j,j'-1}|}{|\phi_{j,j'}|} \right) \end{aligned}$$

# Need another Iterative Procedure

1. Initialize  $\phi_j^{(0)}$
2. Given  $\phi_j^{(k)}$ , we solve (a ridge problem)

$$\begin{aligned} \phi_j^{(k+1)} = & \arg \min_{\phi_j} \frac{1}{d_j^2} \sum_{i=1}^n (x_{ij} - \phi_{j,j-1} x_{i,j-1} - \cdots - \phi_{j,1} x_{i1})^2 + \\ & + \lambda \cdot \left( \frac{\phi_{j,j-1}^2}{|\phi_{j,j-1}^{(k)}|} + \sum_{j'=2}^{j-1} \frac{\phi_{j,j'-1}^2}{|\phi_{j,j'-1}^{(k)}| \cdot |\phi_{j,j'}^{(k)}|} \right) \end{aligned}$$

3.  $k \leftarrow k + 1$  and go to 2 until convergence

Similar to Fan & Li (2001)

## Regression Variant

Instead of using the negative log-likelihood, we can fit a penalized regression model directly ([without  \$d\_j\$](#) )

$$\begin{aligned}\hat{\phi}_j &= \arg \min_{\phi_j} \sum_{i=1}^n (x_{ij} - \phi_{j,j-1}x_{i,j-1} - \cdots - \phi_{j1}x_{i1})^2 + \\ &\quad + \lambda \cdot \left( |\phi_{j,j-1}| + \sum_{j'=2}^{j-1} \frac{|\phi_{j,j'-1}|}{|\phi_{j,j'}|} \right)\end{aligned}$$

and set

$$\hat{d}_j^2 = \frac{1}{n} \sum_{i=1}^n (x_{ij} - \hat{\phi}_{j,j-1}x_{i,j-1} - \cdots - \hat{\phi}_{j1}x_{i1})^2$$

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## Simulation Setup

$\Sigma_1$  Identity

$\Sigma_2$   $d_j = 0.01$ ,  $\phi_{j,j-1} = 0.8$  and  $\phi_{jj'} = 0$  otherwise (so  $\Sigma_2^{-1}$  is tri-diagonal)

$\Sigma_3$   $d_j = 0.01$  and  $\phi_{jj'} = 0.5^{|j-j'|}$  (non-sparse)

## Simulation Setup

- $n = 100$  training data, 100 validation data
- $p = 30$  and 100
- $\mathbf{X} \sim \text{Normal}(\mathbf{0}, \boldsymbol{\Sigma})$  and Multivariate  $T_3$
- Compare sample covariance, LASSO, AB-Lik (likelihood-based) and AB-Reg (regression-based)
- Entropy loss (Anderson 2003)

$$\Delta_E(\boldsymbol{\Sigma}, \hat{\boldsymbol{\Sigma}}) = \text{tr} \left( \boldsymbol{\Sigma}^{-1} \hat{\boldsymbol{\Sigma}} \right) - \ln \left| \boldsymbol{\Sigma}^{-1} \hat{\boldsymbol{\Sigma}} \right| - p$$

## Simulation Result: $\Sigma_1$

$p$	Sample	LASSO	AB-Lik	AB-Reg
Multivariate Normal				
30	5.24(0.30)	0.30(0.08)	0.31(0.08)	0.31(0.08)
100	133.8(3.2)	0.99(0.16)	0.99(0.16)	0.99(0.16)
Multivariate $T_3$				
30	15.4(5.8)	2.72(2.69)	2.80(3.95)	2.46(2.55)
100	206.8(27.3)	9.64(7.45)	9.22(6.79)	9.08(6.60)

## Simulation Result: $\Sigma_2$

$p$	Sample	LASSO	AB-Lik	AB-Reg
Multivariate Normal				
30	5.32(0.33)	1.10(0.19)	0.69(0.15)	0.72(0.14)
100	133.0(3.2)	5.43(0.52)	2.29(0.24)	2.46(0.24)
Multivariate $T_3$				
30	18.7(16.4)	7.7(14.1)	7.6(16.4)	5.8(10.6)
100	208.5(45.3)	26.1(27.3)	14.9(24.2)	14.1(16.6)

## Simulation Result: $\Sigma_3$

$p$	Sample	LASSO	AB-Lik	AB-Reg
Multivariate Normal				
30	5.14(0.31)	3.16(0.34)	1.20(0.12)	1.18(0.13)
100	133.5(3.4)	24.7(3.5)	4.33(0.25)	4.25(0.24)
Multivariate $T_3$				
30	15.0(5.6)	14.4(5.3)	5.00(3.50)	4.69(2.72)
100	200.8(26.1)	164.7(22.4)	18.5(10.9)	17.3(9.5)

## Percentage of Zeros (Normal)

(# zeros in the estimate / # zeros in the truth)

		$\Sigma^{-1}$
$p$	LASSO	AB
$\Sigma_1, 30$	99.9(0.2)%	99.4(1.1)%
$\Sigma_1, 100$	99.9(0.1)%	99.9(0.1)%
$\Sigma_2, 30$	31.9(7.2)%	95.1(1.4)%
$\Sigma_2, 100$	76.4(3.6)%	98.9(0.2)%

## Percentage of Zeros ( $T_3$ )

(# zeros in the estimate / # zeros in the truth)

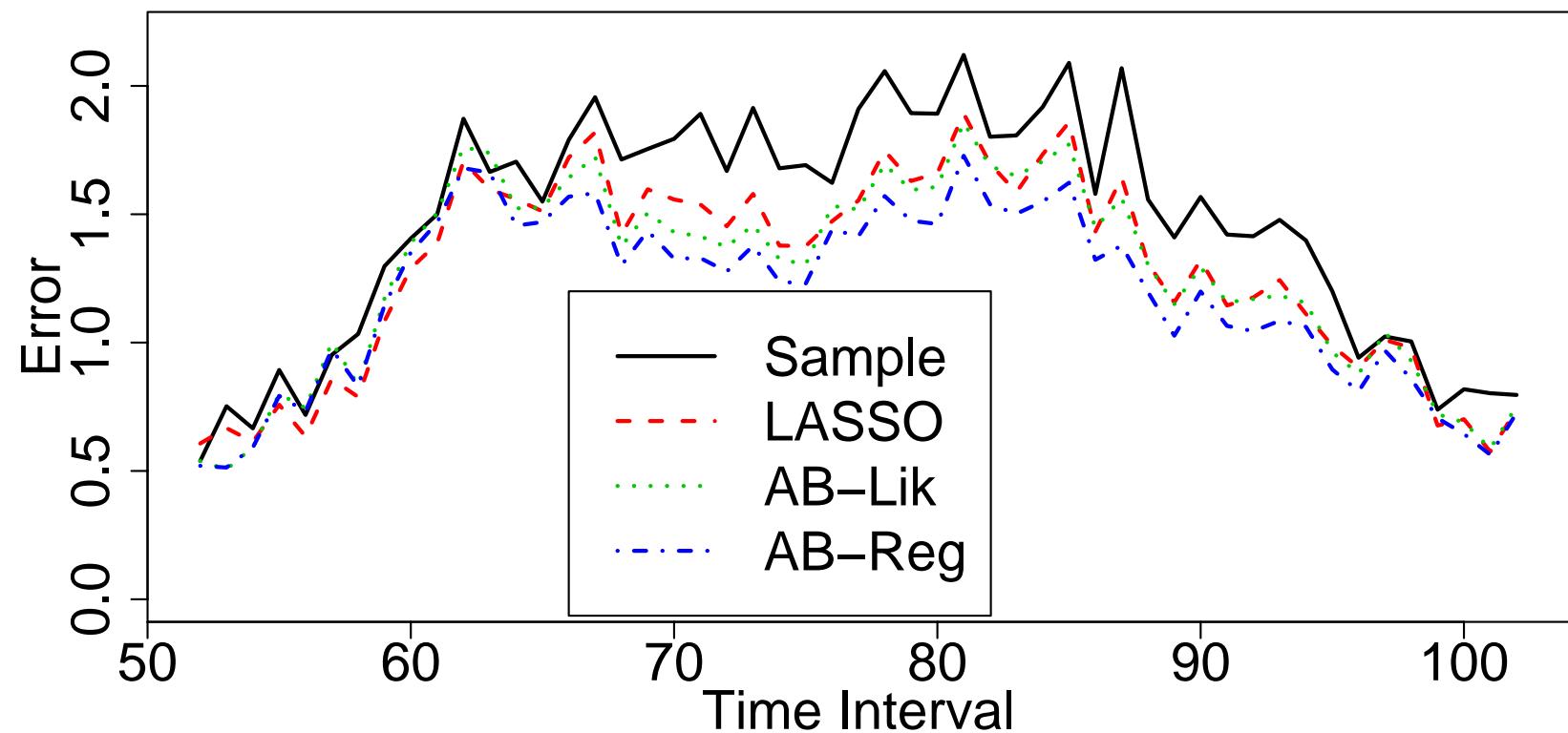
		$\Sigma^{-1}$
$p$	LASSO	AB
$\Sigma_1, 30$	93.8(11.3)%	98.0(5.9)%
$\Sigma_1, 100$	99.3(2.1)%	99.9(0.2)%
$\Sigma_2, 30$	45.3(13.5)%	94.9(4.0)%
$\Sigma_2, 100$	37.4(4.5)%	98.6(1.0)%

## Call Center Data

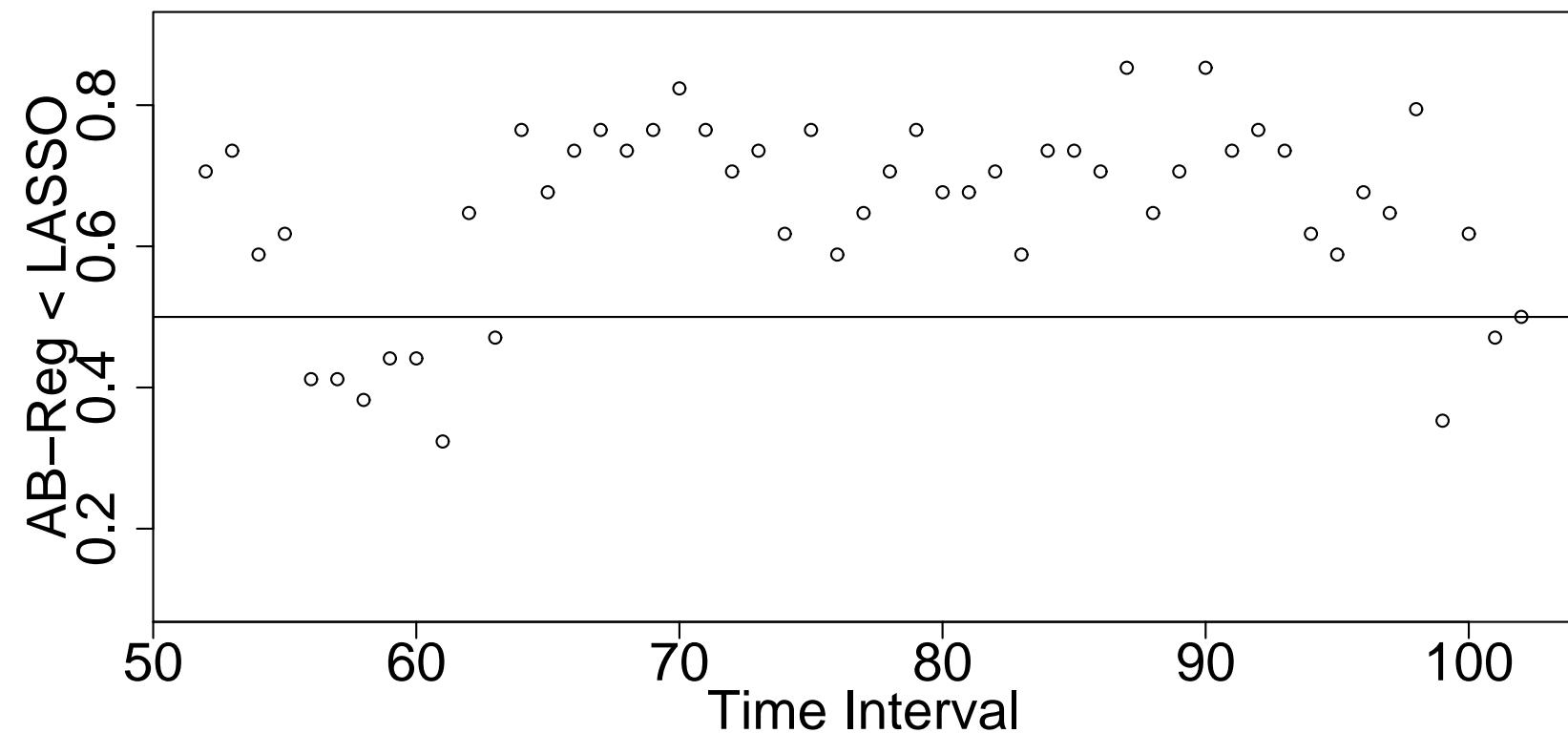
- Divide the data into training set (January to October) and testing set (November and December):  
$$239 = 205 + 34$$
- Use the 51 arrival counts in the early half of a day to forecast the 51 arrival counts in the later half of the day
- For each time interval  $j$ , the forecast error is

$$\text{error}_j = \frac{1}{34} \sum_{i=206}^{239} |\hat{x}_{ij} - x_{ij}|$$

## Call Center Data



## Call Center Data



## Concluding Remarks

- Adaptive Banding: achieves shrinkage, incorporates order information, preserves sparsity; better than LASSO
- Open issues
  - Evaluating the performance (other loss functions)
  - Multiple  $\lambda_j$ 's
  - Imposing other structures