# BOUNDS ON OSCILLATORY INTEGRAL OPERATORS BASED ON MULTILINEAR ESTIMATES 

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## §1. Summary

Let $S \subset \mathbb{R}^{n}$ be a smooth, compact hyper-surface with positive definite second fundamental form. Let $\sigma$ be its surface measure.

We prove the following result with respect to the Fourier restriction/extension problem.

Theorem 1. Assume the exponent $p$ satisfies

$$
\left\{\begin{align*}
p>2 \frac{4 n+3}{4 n-3} \text { if } n \equiv 0(\bmod 3)  \tag{1.1}\\
p>\frac{2 n+1}{n-1} \text { if } n \equiv 1(\bmod 3) \\
p>\frac{4(n+1)}{2 n-1} \text { if } n \equiv 2(\bmod 3)
\end{align*}\right.
$$

Then the inequality

$$
\begin{equation*}
\|\hat{\mu}\|_{p} \lesssim C_{p}\left\|\frac{d \mu}{d \sigma}\right\|_{\infty} \tag{1.2}
\end{equation*}
$$

holds for measures $\mu \ll \sigma$ such that $\frac{d \mu}{d \sigma} \in L^{\infty}(S, \sigma)$.
See $\S 3$. For $n=3$ (resp. $n=4$ ), the exponent in (1.2) is $\frac{10}{3}$ (resp. 3) and coincides with the condition $p \geq \frac{2(n+2)}{n}$ resulting from the bilinear $L^{2}$-approach in [T1]. For $n \geq 5$, the result is new.

Recall that, according to the restriction conjecture, due to E. Stein, cf. [St1], (1.1) should remain valid for all $p>\frac{2 n}{n-1}$.

We also point out that if $S$ is the $(n-1)$-sphere or paraboloid, then (1.2) may be strengthen to

$$
\|\hat{\mu}\|_{p} \leq C_{p}\left\|\frac{d \mu}{d \sigma}\right\|_{p}
$$

for $p$ satisfying (1.1) (the argument combines Theorem 1, the Maurey-Nikishin factorization theorem and invariance considerations, the usual way; cf. [B1]).

The main ingredient in our approach is the multilinear theory developed in [BCT] that we will recall in $\S 5$. In $\S 2$ we treat the case $n=3$ to explain the method in its simplest form. In $\S 4$, the analysis is refined further and combined with T. Wolff's Kakeya maximal function estimate [Wo1] to establish (1.1) for $n=3$ under the condition

$$
\begin{equation*}
p>3 \frac{3}{10} . \tag{1.3}
\end{equation*}
$$

Thus we have the following small improvement of the $p>\frac{10}{3}$ result in 3D.
Theorem 2. For $n=3$ and $S$ as above, we have

$$
\begin{equation*}
\|\hat{\mu}\|_{p} \leq C_{p}\left\|\frac{d \mu}{d \sigma}\right\|_{\infty} \text { for } p>3 \frac{3}{10} \tag{1.4}
\end{equation*}
$$

assuming $\mu \ll \sigma$ and $\frac{d \mu}{d \sigma} \in L^{\infty}(S, d \sigma)$.
By using ' $\varepsilon$-removal lemmas', Theorems 1 and 2 may be derived from a weaker 'local' version, more precisely

Theorem 1'. Let $n \geq 3$ and $S$ as above.
Denote

$$
Q_{R}^{(p)}=\max \|\hat{\mu}\|_{L^{p}\left(B_{R}\right)}
$$

where the maximum is taken over all measures $\mu \ll \sigma$ on $S$ such that $\left\|\frac{d \mu}{d \sigma}\right\|_{\infty} \leq 1$. Then, for all $\varepsilon>0$

$$
\begin{equation*}
Q_{R}^{(p)} \ll R^{\varepsilon} \tag{1.5}
\end{equation*}
$$

provided $p$ satisfies (1.1).
and

Theorem 2'. Same statement for $n=3$ and $p \geq 3 \frac{3}{10}$.
The use of such $\varepsilon$-removal lemmas is by now standard (cf. [T2]), but we will include an argument for completeness sake in the Appendix, since we process here $L^{\infty}-L^{p}$ inequalities rather than $L^{p}-L^{p}$ inequalities, as in [T2].

The technique used applies also in the variable coefficient (Hörmander) setting. Thus we consider oscillatory integral operators

$$
\begin{equation*}
\left(T_{\lambda} f\right)(x)=\int e^{i \lambda \psi(x, y)} f(y) d y \quad\left(\|f\|_{\infty} \leq 1\right) \tag{1.6}
\end{equation*}
$$

with real analytic phase function

$$
\begin{equation*}
\psi(x, y)=x_{1} y_{1}+\cdots+x_{n-1} y_{n-1}+x_{n}\langle A y, y\rangle+O\left(|x||y|^{3}\right)+O\left(|x|^{2}|y|^{2}\right) \tag{1.7}
\end{equation*}
$$

and $A$ non-degenerate.
( $x \in \mathbb{R}^{n}, y \in \mathbb{R}^{n-1}$ are restricted to a neighborhood of 0 .)
Our concern is then in which range of $p$, a bound

$$
\begin{equation*}
\left\|T_{\lambda} f\right\|_{p} \leq c \lambda^{-\frac{n}{p}} \tag{1.8}
\end{equation*}
$$

holds. Recall Stein's result [St2]

$$
\begin{equation*}
\left\|T_{\lambda} f\right\|_{p} \leq c\|f\|_{2} \text { for } p \geq \frac{2(n+1)}{n-1} \tag{1.9}
\end{equation*}
$$

Also, for $n$ odd, there are examples showing that, replacing $\|f\|_{2}$ by $\|f\|_{\infty}$, an inequality (1.8) may only hold for $p \geq \frac{2(n+1)}{n-1}$ (see [B2]).

However, as proven in $\S 5$, if we make the additional hypothesis that $A$ in (1.7) is positive (or negative) definite, then (1.8) holds under the condition (1.1). Thus we have

Theorem 3. Let $T_{\lambda}$ be as above with $A$ positive or negative definite in (1.7). Then

$$
\begin{equation*}
\left\|T_{\lambda} f\right\|_{p} \leq C_{p} \lambda^{-\frac{n}{p}}\|f\|_{\infty} \tag{1.10}
\end{equation*}
$$

holds for $p$ satisfying (1.1).
For $n$ even, there is the following statement (with only the non-degeneracy assumption on $A$ ).

Theorem 4. Let $n$ be even and $T_{\lambda}$ as above, assuming in (1.7) that $A$ is nondegenerate. Then

$$
\begin{equation*}
\left\|T_{\lambda} f\right\|_{p} \leq C_{p} \lambda^{-\frac{n}{p}}\|f\|_{\infty} \text { for } p>\frac{2(n+2)}{n} \tag{1.11}
\end{equation*}
$$

(apart from the endpoint, the condition on $p$ in Theorem 4 was already previously observed to be best possible, cf. [B2].)

It turns out, rather surprisingly, that for $n=3$ the exponent $\frac{10}{3}$ in Theorem 3 is also optimal. In $\S 6$, we describe a specific example (with $A$ elliptic), making the comparison with the hyperbolic case, and explaining the role of the Kakeya compression phenomenon. For $n=3$, in both elliptic and hyperbolic cases, there may be a curved Kakeya compression in a 2-dimensional set at the coarse scale $\frac{1}{\sqrt{\lambda}}$, but the local behaviour of the oscillatory integrals is different.

The proof of Theorems 3 and 4 is based on an application of Theorem 6.2 from [BCT], but we need a version without the extra $\lambda^{\varepsilon}$-factors. Hence, we proceed to ' $\varepsilon$-removal' at the multilinear stage (see Appendix), which also provides an alternative strategy to derive Theorem 1 directly, without passing through Theorem 1' (let us point out that this $\varepsilon$-removal argument applies only to our particular application of [BCT], Theorem 6.2, see §5.)

Returning to curved Kakeya compression, it is shown that a curved Kakeya set in even dimension $n$ has Minkowski dimension at least $\frac{n}{2}+1$ (see $\S 6$ ). This statement was known to be optimal (see [B2]).

Details are given in $\S 7$ for $n=4$, where it is shown how to derive this property from multi-linear Kakeya-type results. This strategy may be seen as the essence of our paper and is basically repeated to obtain the oscillatory integral bounds cited above.

Returning to Theorem 3, we should point out the application to the BochnerRiesz multilinear problem. Recall that the Bochner-Riesz multiplier $S_{\delta}$ is defined by $\left(S_{\delta} f\right)^{\wedge}(\xi)=\left(1-|\xi|^{2}\right)_{+}^{\delta} \hat{f}(\xi)$. Equivalently $S_{\delta} f=f * K_{\delta}$, where $K_{\delta}$ has the asymptotic

$$
\begin{equation*}
K_{\delta}(x) \sim e^{e^{ \pm 2 \pi i|x|}} /|x|^{\frac{n+1}{2}+\delta} . \tag{1.12}
\end{equation*}
$$

The problem is then to obtain the optimal condition on $\delta \geq 0$ to satisfy

$$
\begin{equation*}
\left\|S_{\delta} f\right\|_{L^{p}\left(\mathbb{R}^{n}\right)} \leq C\|f\|_{L^{p}\left(\mathbb{R}^{n}\right)} \tag{1.13}
\end{equation*}
$$

C. Fefferman's proof of the ball-multiplier conjecture implies that certainly $\delta>0$ for $p \neq 2$ (note that the problem is self-dual). In view of (1.12), the condition

$$
\begin{equation*}
\delta>\max \left(0,\left|\frac{1}{2}-\frac{1}{p}\right| n-\frac{1}{2}\right) \tag{1.14}
\end{equation*}
$$

is clearly necessary. It is conjectured that (1.14) also suffices for (1.13) to hold and this was proven for $n=2$ in [C-S] and, independently, in [Hor].

In fact, Hörmander's approach consists in reducing the study of convolution by $K_{\delta}$ to some specific oscillatory integral operator $T_{\lambda}$, of the type considered above (note that regarding dimension, the $\mathbb{R}^{d}-\mathbb{R}^{d}$ problem is replaced by an $\mathbb{R}^{d-1}-\mathbb{R}^{d}$ problem in this reduction). As a corollary of our Theorem 3 together with the standard factorization and rotational invariance considerations (already mentioned above), we obtain (cf. [B2] for details).

Theorem 5. Let $n \geq 3$. Then the Bochner-Riesz conjecture holds providing $\max \left(p, p^{\prime}\right)$ satisfies (1.1).

On the geometric side, the Kakeya-type maximal function underlying the BochnerRiesz operators (sometimes called 'Nikodym maximal function) involves also averaging over straight line segments and, for $n=3$, T. Wolff's $\frac{5}{2}$-inequality is again known to hold (see [Wo1]). Thus in principle, one could expect the proof of Theorem 2 to carry over and lead to the validity of the Bochner-Riesz conjecture for $\max \left(p, p^{\prime}\right) \geq 3 \frac{3}{10}$, if $n=3$. We do not pursue the details of this matter here. In fact, it is well-possible that the exponent $3 \frac{3}{10}$ from Theorem 2 may be improved further, by reorganizing and refining the method. No serious attempt was given to do so, as our primary goal is to show how to obtain some progress over the present results, keeping the arguments as simple as possible.

Finally, let us cite [T3] as a survey work on the problems discussed in this paper and where the reader will find many background material and references.

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## §2. An Approach to the Restriction Problem in 3D

(alternative proof of the $L^{10 / 3}$-bound)

1. Consider the oscillatory integral operator

$$
T f(x)=\int e^{i \phi(x, y)} f(y) d y \quad(|f| \leq 1)
$$

where $y \in \Omega$ is a neighborhood of $0 \in \mathbb{R}^{2}$ and $x \in \mathbb{R}^{3} \cap[|x|<R]$,

$$
\begin{equation*}
\phi(x, y)=x_{1} y_{1}+x_{2} y_{2}+x_{3} \phi_{1}(y) \tag{1.1}
\end{equation*}
$$

with $\phi_{1}(y)=y_{1}^{2}+y_{2}^{2}$ (paraboloid), or more generally

$$
\begin{equation*}
\phi_{1}(y)=\langle A y, y\rangle+O\left(|y|^{3}\right) \quad(A=\text { positive definite }) \tag{1.2}
\end{equation*}
$$

(we will comment on the indefinite case at the end of this section).
The purpose of this section is to explain in a simple case how the multi-linear theory from [BCT] can be exploited to produce results in the usual restriction problem.

Given a phase function $\phi$ as above, we introduce at a given point $y \in \Omega$ the vector

$$
\begin{equation*}
Z=Z(y)=\partial_{y_{1}}\left(\nabla_{x} \phi\right) \wedge \partial_{y_{2}}\left(\nabla_{x} \phi\right)=\left(-\partial_{1} \phi_{1}(y),-\partial_{2} \phi_{1}(y), 1\right) \tag{1.3}
\end{equation*}
$$

For simplicity, we carry the discussion for the case of the paraboloid, thus

$$
\phi_{1}(y)=y_{1}^{2}+y_{2}^{2} .
$$

In this case, the transversality condition of $\left\{Z\left(y^{(i)}\right), i=1,2,3\right\}$, where $y^{(i)}$ is restricted to some small disc $\Omega_{i} \subset \Omega$ (as needed for the trilinear $L^{3}$-bound from [BCT]) amounts to non-collinearity of $\Omega_{1}, \Omega_{2}, \Omega_{3}$.

Discussion of the general situation (1.2) would require to introduce the Gauss map associated to the surface

$$
\left(y_{1}, y_{2}\right) \mapsto\left(y_{1}, y_{2}, \phi_{1}(y)\right)
$$

(see $\S 3$. )
2. Fix $K$ (a large parameter).

Partition $\Omega=\bigcup \Omega_{\alpha}, \Omega_{\alpha}$ balls of size $\frac{1}{K} ; y_{\alpha} \in \Omega_{\alpha}$. There are $\sim K^{2}$ values of $\alpha$. Write

$$
\begin{align*}
T f(x) & =\sum_{\alpha} e^{i \phi\left(x, y_{\alpha}\right)}\left[\int_{\Omega_{\alpha}} e^{i\left[\phi(x, y)-\phi\left(x, y_{\alpha}\right)\right]} f(y) d y\right] \\
& =\sum_{\alpha} e^{i \phi\left(x, y_{\alpha}\right)}\left(T_{\alpha} f\right)(x) \tag{2.1}
\end{align*}
$$

Note that

$$
\left|\nabla_{x}\left[\phi(x, y)-\phi\left(x, y_{\alpha}\right)\right]\right| \leq \frac{1}{K} \text { for } y \in \Omega_{\alpha}
$$

Take a smooth rapidly decaying bumpfunction $\eta$ s.t. $\hat{\eta}(\omega)=1$ on $\left[\omega \in \mathbb{R}^{3} ;|\omega| \leq 1\right]$. Let $\eta_{K}(x)=\frac{1}{K^{3}} \eta\left(\frac{x}{K}\right)$ satisfying $\hat{\eta}_{K}(\omega)=1$ for $|\omega|<1 / K$.

Thus

$$
T_{\alpha} f=T_{\alpha} f * \eta_{K}
$$

and

$$
\left|T_{\alpha} f(x)\right| \leq \int\left|T_{\alpha} f(z)\right|\left|\eta_{K}(x-z)\right| d z
$$

Restrict $x$ to a ball $B(a, K) \subset \mathbb{R}^{3}$. Set $a=0$.
For $x \in B(0, K)$

$$
\begin{equation*}
\left|T_{\alpha} f(x)\right| \leq \int\left|T_{\alpha} f(z)\right| \zeta_{K}(z) d z=c_{\alpha} \tag{2.2}
\end{equation*}
$$

where

$$
\zeta(x)=\max _{\left|x-x^{\prime}\right| \leq 1}\left|\eta\left(x^{\prime}\right)\right|
$$

3. Denote $c_{*}=\max c_{\alpha}=c_{\alpha_{*}}$. Let $K_{1} \ll K$ be a second large parameter. We distinguish several possibilities.

## (3.1) Non-coplanar interaction.

There are $\alpha, \beta, \gamma$ such that $c_{\alpha}, c_{\beta}, c_{\gamma}>K^{-4} c_{*}$ and

$$
\left|y_{\alpha}-y_{\beta}\right| \geq\left|y_{\alpha}-y_{\gamma}\right| \geq \operatorname{dist}(y_{\gamma}, \underbrace{y_{\alpha}+\mathbb{R}\left(y_{\beta}-y_{\alpha}\right)}_{\equiv \ell\left(y_{\alpha}, y_{\beta}\right)})>10^{3} \frac{1}{K}
$$



In this situation we use the trilinear theory from $[B C T]$.

## (3.2) Non-transverse interaction.

If $\left|y_{\alpha}-y_{\alpha_{*}}\right|>\frac{1}{K_{1}}$, then $c_{\alpha} \leq K^{-4} c_{*}$. Here we use rescaling (cf. [T-V-V]).
(3.3) Transverse coplanar interaction.

There is $\alpha_{* *}$ with $c_{\alpha_{* *}}>K^{-4} c_{*},\left|y_{\alpha_{*}}-y_{\alpha_{* *}}\right|>\frac{1}{K_{1}}$.
Assuming (3.1) fails, it follows that moreover

$$
c_{\alpha} \leq K^{-4} c_{*} \text { if } \operatorname{dist}\left(y_{\alpha}, \ell\left(y_{\alpha_{*}}, y_{\alpha_{* *}}\right)\right)>10^{3} \frac{K_{1}}{K}
$$

In this case we rely on the by now standard square function estimates going back to A. Cordoba's work [C].
4. Assume (3.1)

For $x \in B(0, K)$, by $(2.2),(1.1)$

$$
|T f(x)| \leq \sum_{\alpha} c_{\alpha}<K^{2} c_{*}<K^{6}\left(c_{\alpha} c_{\beta} c_{\gamma}\right)^{\frac{1}{3}}
$$

Hence, for $q \geq 3$

$$
\begin{aligned}
|T f(x)|^{q} \leq|T f(x)|^{3} & \leq K^{18} \int\left|T_{\alpha} f\right|\left(z_{1}\right)\left|T_{\beta} f\right|\left(z_{2}\right)\left|T_{\gamma} f\right|\left(z_{3}\right) \zeta_{K}\left(z_{1}\right) \zeta_{K}\left(z_{2}\right) \zeta_{K}\left(z_{3}\right) d z_{1} d z_{2} d z_{3} \\
& \leq K^{18} \sum_{\alpha, \beta, \gamma\left(3.1^{\prime}\right)} \int\left|T_{\alpha} f\right|\left(x-z_{1}\right)\left|T_{\beta} f\right|\left(x-z_{2}\right)\left|T_{\gamma} f\right|\left(x-z_{3}\right) \zeta_{K}\left(z_{1}\right) \zeta_{K}\left(z_{2}\right) \zeta_{K}\left(z_{3}\right)
\end{aligned}
$$

The corresponding contribution is estimated using the trilinear bound from [BCT]

$$
\begin{equation*}
\int_{B_{R}}\left|T_{\alpha} f\right|\left(x-z_{1}\right)\left|T_{\beta} f\right|\left(x-z_{2}\right)\left|T_{\gamma} f\right|\left(x-z_{3}\right) d x<R^{\varepsilon} . C(K)<R^{2 \varepsilon} \tag{4.1}
\end{equation*}
$$

5. Assume (3.2). For $x \in B(0, K)$, estimate

$$
\begin{align*}
|T f(x)| & \leq 10 \max _{\tau}\left|\int_{\tilde{\Omega}_{\tau}} e^{i \phi(x, y)} f(y) d y\right|+\sum_{\left|y_{\alpha}-y_{\alpha_{*}}\right|>\frac{1}{K_{1}}} c_{\alpha} \\
& \leq 10 \cdot \max _{\tau}\left|\tilde{T}_{\tau} f(x)\right|+K^{-2} c_{*} \tag{5.1}
\end{align*}
$$

where $\Omega=\bigcup \tilde{\Omega}_{\tau}$ is a partition of $\Omega$ in balls of size $\frac{1}{K_{1}}$.

Thus (5.1) implies for $x \in B(0, K)$

$$
\begin{equation*}
|T f(x)|^{q} \leq C \sum_{\tau=1}^{\sim K_{1}^{2}}\left|\tilde{T}_{\tau} f\right|^{q}(x)+C K^{-2 q} \sum_{\alpha=1}^{\sim K^{2}} \int\left|T_{\alpha} f\right|^{q}(x-z) \zeta_{K}(z) d z . \tag{5.2}
\end{equation*}
$$

The corresponding contribution is at most

$$
\begin{equation*}
C \sum_{\tau} \int_{B_{R}}\left|\tilde{T}_{\tau} f\right|^{q}+C K^{-2 q} \sum_{\alpha} \int_{B_{R}}\left|T_{\alpha} f\right|^{q} \tag{5.3}
\end{equation*}
$$

At this point, we use the (parabolic) rescaling

$$
\begin{aligned}
& \left|\int_{|y-\bar{y}|<\rho} e^{i \phi(x, y)} f(y) d y\right|= \\
& y=\bar{y}+y^{\prime} \\
& \left|\int_{\left|y^{\prime}\right|<\rho} e^{i\left[\left(x_{1}+2 \bar{y}_{1} x_{3}\right) y_{1}^{\prime}+\left(x_{2}+2 \bar{y}_{2} x_{3}\right) y_{2}^{\prime}+x_{3}\left|y^{\prime}\right|^{2}\right]} f\left(\bar{y}+y^{\prime}\right) d y^{\prime}\right|=(5.4)
\end{aligned}
$$

and

$$
\begin{equation*}
\|(5.4)\|_{L^{q}\left(B_{R}\right)} \leq C \rho^{2} \rho^{-\frac{4}{q}} Q_{\rho R} \tag{5.5}
\end{equation*}
$$

where we define

$$
\begin{equation*}
Q_{R}=\max _{|f| \leq 1}\|T f\|_{L^{q}\left(B_{R}\right)} \tag{5.6}
\end{equation*}
$$

Substituting (5.5) in (5.3) gives the contribution ( $\rho=\frac{1}{K_{1}}$ and $\rho=\frac{1}{K}$ )

$$
C K_{1}^{2} \cdot K_{1}^{-2 q+4} Q_{R / K_{1}}^{q}+C K^{-2 q} \cdot K^{2} \cdot K^{-2 q+4} Q_{R / K}^{q}
$$

and hence for the $L^{q}$-norm

$$
\begin{equation*}
<C K_{1}^{-2\left(1-\frac{3}{q}\right)} Q_{R / K_{1}}+C K^{-4+\frac{6}{\varepsilon}} Q_{R / K} \tag{5.7}
\end{equation*}
$$

6. Assume (3.3). Thus, denoting $\ell=\ell\left(y_{\alpha_{*}}, y_{\alpha_{* *}}\right)$, for $x \in B(a, R)$

$$
\begin{align*}
\left|\int_{\operatorname{dist}(y, \ell)>10^{4} \frac{K_{1}}{K}} e^{i \phi(x, y)} f(y) d y\right| & \leq \sum_{\operatorname{dist}\left(y_{\alpha}, \ell\right)>10^{3} \frac{K_{1}}{K}}\left|T_{\alpha} f(x)\right|<K^{2} K^{-4} c_{*} \\
& <K^{-2} \int\left|T_{\alpha_{*}} f(a-z)\right| \zeta_{K}(z) d z . \tag{6.1}
\end{align*}
$$

Hence

$$
\begin{equation*}
\left|\int_{\operatorname{dist}(y, \ell)>10^{4} \frac{K_{1}}{K}} e^{i \phi(x, y)} f(y) d y\right|^{q}<K^{-2 q} \sum_{\alpha=1}^{\sim K^{2}} \int\left|T_{\alpha} f(x-z)\right|^{q} \zeta_{K}(z) d z \tag{6.2}
\end{equation*}
$$

and by (5.5), the corresponding contribution is at most

$$
\begin{equation*}
K^{-2} \cdot K^{\frac{2}{q}} \cdot K^{\frac{4}{q}-2} Q_{R / K}<K^{-2} Q_{R / K} \tag{6.3}
\end{equation*}
$$

Considering the partition $\Omega=\bigcup \tilde{\Omega}_{\tau}$ in balls of size $\frac{1}{K_{1}}$ and fixing $x \in B(a, K)$, there are clearly the following alternatives

$$
\begin{equation*}
|T f(x)|<C \max _{\tau}\left|\int_{\tilde{\Omega}_{\tau}} e^{i \phi(x, y)} f(y) d y\right| \tag{6.4}
\end{equation*}
$$

(6.5) There are $\tau, \tau^{\prime}$ such that dist $\left(\tilde{\Omega}_{\tau}, \tilde{\Omega}_{\tau^{\prime}}\right)>\frac{10^{6}}{K_{1}}$ and

$$
\left|\int_{\tilde{\Omega}_{\tau}} e^{i \phi(x, y)} f(y) d y\right|,\left|\int_{\tilde{\Omega}_{\tau^{\prime}}} e^{i \phi(x, y)} f(y) d y\right|>\frac{1}{10 K_{1}^{2}}|T f(x)| .
$$

If (6.4), write

$$
|T f(x)| \leq C\left[\sum_{\tau=1}^{\sim K_{1}^{2}}\left|\int_{\tilde{\Omega}_{\tau}} e^{i \phi(x, y)} f(y) d y\right|^{q}\right]^{\frac{1}{q}}=
$$

and by (5.4), (5.5)

$$
\begin{equation*}
\|(6.6)\|_{L^{q}\left(B_{R}\right)} \leq K_{1}^{\frac{2}{q}} \cdot K_{1}^{\frac{4}{q}-2} Q_{R / K_{1}}<K_{1}^{-2\left(1-\frac{3}{q}\right)} Q_{R / K_{1}} \tag{6.7}
\end{equation*}
$$

Assume (6.5). Estimate further

$$
\begin{aligned}
&\left|\int_{\tilde{\Omega}_{\tau}} e^{i \phi(x, y)} f(y) d y\right| \leq\left|\sum_{\substack{\Omega_{\alpha} \subset \tilde{\Omega}_{\tau} \\
\operatorname{dist}\left(y_{\alpha}, \ell\right) \leq 10^{3} \frac{K_{1}}{K}}} e^{i \phi\left(x, y_{2}\right)}\left(T_{\alpha} f\right)(x)\right|+\sum_{\substack{\Omega_{\alpha} \subset \tilde{\Omega}_{\tau} \\
\operatorname{dist}\left(y_{\alpha}, \ell\right)>10^{3} \frac{K_{1}}{K}}}\left|T_{\alpha} f\right| \\
&=(6.8)+(6.9)
\end{aligned}
$$

and similarly for $\left|\int_{\tilde{\Omega}_{\tau^{\prime}}} e^{i \phi(x, y)} f(y) d y\right|$.
The contribution of (6.9) was evaluated in (6.1), (6.3).

Thus it remains to obtain a bound on

$$
\begin{equation*}
\int_{B(a, K)}\left|\sum_{\substack{\Omega_{\alpha} \subset \tilde{\Omega}_{\tau} \\ \operatorname{dist}\left(y_{\alpha}, \ell\right) \leq 10^{3} \frac{K_{1}}{K}}} e^{i \phi\left(x, y_{\alpha}\right)}\left(T_{\alpha} f\right)(x)\right|^{\frac{q}{2}}\left|\sum_{\substack{\Omega_{\alpha} \subset \tilde{\Omega}_{\tau^{\prime}} \\ \operatorname{dist}\left(y_{\alpha}, \ell\right) \leq 10^{3} \frac{K_{1}}{K}}} e^{i \phi\left(x, y_{\alpha}\right)}\left(T_{\alpha} f\right)(x)\right|^{\frac{q}{2}} d x \tag{6.10}
\end{equation*}
$$



By Hölder's inequality, assuming $q<4$

$$
\begin{equation*}
(6.10) \lesssim K^{3\left(1-\frac{q}{4}\right)}\left[\int_{B(a, K)}|\cdots|^{2}|\cdots|^{2} d x\right]^{q / 4} \tag{6.11}
\end{equation*}
$$

Consider

$$
\begin{align*}
& \int_{B(a, K)}|\cdots|^{2}|\cdots|^{2} \leq \\
& \sum_{\substack{\Omega_{\alpha_{1}}, \Omega_{\alpha_{2}} \subset \tilde{\Omega}_{\tau} \cap \Delta \\
\Omega_{\alpha_{1}^{\prime}}, \Omega_{\alpha_{2}^{\prime}} \subset \tilde{\Omega}_{\tau^{\prime}} \cap \Delta}}\left|\int_{B(a, K)} T_{\alpha_{1}} f \overline{T_{\alpha_{2}} f} \overline{T_{\alpha_{1}^{\prime}} f} T_{\alpha_{2}^{\prime}} f \quad e^{i\left[\phi\left(x, y_{\alpha_{1}}\right)-\phi\left(x, y_{\alpha_{2}}\right) \cdots\right]} d x\right| \tag{6.12}
\end{align*}
$$

where $\Delta=\left\{y \in B(0,1) ; \operatorname{dist}(y, \ell)<10^{3} \frac{K_{1}}{K}\right\}$.
Rewriting

$$
\begin{aligned}
& \phi\left(x, y_{\alpha_{1}}\right)-\phi\left(x, y_{\alpha_{2}}\right)-\phi\left(x, y_{\alpha_{1}^{\prime}}\right)+\phi\left(x, y_{\alpha_{2}^{\prime}}\right)= \\
& <\left(x_{1}, x_{2}\right), y_{\alpha_{1}}-y_{\alpha_{2}}-y_{\alpha_{1}^{\prime}}+y_{\alpha_{2}^{\prime}}>+x_{3}\left(\phi_{1}\left(y_{\alpha_{1}}\right)-\phi_{1}\left(y_{\alpha_{2}}\right)-\phi_{1}\left(y_{\alpha_{1}^{\prime}}\right)+\phi_{1}\left(y_{\alpha_{2}^{\prime}}\right)\right)
\end{aligned}
$$

we see that in (6.12) we may restrict the summation to those quadruples $\left(\alpha_{1}, \alpha_{2}, \alpha_{1}^{\prime}, \alpha_{2}^{\prime}\right)$ for which

$$
\left\{\begin{array}{l}
\left|y_{\alpha_{1}}-y_{\alpha_{2}}-y_{\alpha_{1}^{\prime}}+y_{\alpha_{2}^{\prime}}\right| \lesssim \frac{1}{K}  \tag{6.13}\\
\left|\phi_{1}\left(y_{\alpha_{1}}\right)-\phi_{1}\left(y_{\alpha_{2}}\right)-\phi_{1}\left(y_{\alpha_{1}^{\prime}}\right)+\phi_{1}\left(y_{\alpha_{2}^{\prime}}\right)\right| \lesssim \frac{1}{K}
\end{array}\right.
$$

Let $\ell=b+\mathbb{R} v(|v|=1)$ and $\left|y_{\alpha_{i}}-\left(b+t_{i} v\right)\right|<10^{3} \frac{K_{1}}{K},\left|y_{\alpha_{1}^{\prime}}-\left(b+t_{i}^{\prime} v\right)\right|<10^{3} \frac{K_{1}}{K}$.
Recall from (6.5) that

$$
\left|t_{1}-t_{2}\right|,\left|t_{1}^{\prime}-t_{2}^{\prime}\right| \leq \frac{2}{K_{1}},\left|t_{1}-t_{1}^{\prime}\right|>\frac{10^{6}}{K_{1}} .
$$

Hence (6.13), (6.13') imply by the preceding

$$
\left\{\begin{array}{l}
\left|t_{1}-t_{2}-t_{1}^{\prime}+t_{2}^{\prime}\right| \lesssim C \frac{K_{1}}{K}  \tag{6.14}\\
\left|t_{1}^{2}-t_{2}^{2}-\left(t_{1}^{\prime}\right)^{2}+\left(t_{2}^{\prime}\right)^{2}\right| \lesssim C \frac{K_{1}}{K}
\end{array}\right.
$$

and we obtain from the separation property that

$$
\left|\left(t_{1}+t_{2}\right)-\left(t_{1}^{\prime}+t_{2}^{\prime}\right)\right| \lesssim C \frac{K_{1}^{2}}{K}
$$

Hence $\left|t_{1}-t_{2}\right|,\left|t_{1}^{\prime}-t_{2}^{\prime}\right|<C \frac{K_{1}^{2}}{K}$, thus $\left|y_{\alpha_{1}}-y_{\alpha_{2}}\right|,\left|y_{\alpha_{1}^{\prime}}-y_{\alpha_{2}^{\prime}}\right|<C \frac{K_{1}^{2}}{K}$.
Consequently

$$
\begin{equation*}
(6.12) \lesssim K_{1}^{8} \sum_{\substack{\Omega_{\alpha} \subset \tilde{\Omega}_{\tau} \cap \Delta \\ \Omega_{\alpha^{\prime}} \subset \tilde{\Omega}_{\tau^{\prime}} \cap \Delta}} \int_{B(a, K)}\left|\left(T_{\alpha} f\right)(x)\right|^{2}\left|\left(T_{\alpha^{\prime}} f\right)(x)\right|^{2} d x \tag{6.15}
\end{equation*}
$$

and

$$
\begin{align*}
& \lesssim K^{3\left(1-\frac{q}{4}\right)} K_{1}^{2 q} K^{\frac{3 q}{4}}\left[\sum_{\Omega_{\alpha} \subset \tilde{\Omega}_{\tau} \cap \Delta} c_{\alpha}^{2}\right]^{\frac{q}{4}}\left[\sum_{\Omega_{\alpha^{\prime}} \subset \tilde{\Omega}_{\tau^{\prime} \cap \Delta}} c_{\alpha^{\prime}}^{2}\right]^{\frac{q}{4}}  \tag{6.10}\\
& \lesssim K^{3} K_{1}^{2 q}\left(\frac{K}{K_{1}}\right)^{\left(\frac{q}{2}-1\right)}\left[\sum c_{\alpha}^{q}\right]  \tag{6.16}\\
& <K_{1}^{\frac{3 q}{2}+1} K^{\frac{q}{2}-1} \sum_{\alpha} \int\left[\int_{B(a, K)}\left|T_{\alpha} f(x-z)\right|^{q} d x\right] \zeta_{K}(z) d z .
\end{align*}
$$

Summing over the balls $B(a, K)$ implies an estimate

$$
\begin{equation*}
K_{1}^{\frac{3}{2}+\frac{1}{q}} K^{\frac{1}{2}-\frac{1}{q}}\left(\sum_{\alpha}\left\|T_{\alpha} f\right\|_{L^{q}\left(B_{R}\right)}^{q}\right)^{\frac{1}{q}}<K_{1}^{\frac{3}{2}+\frac{1}{q}} K^{5 / q-3 / 2} Q_{R / K} \tag{6.17}
\end{equation*}
$$

Collecting contributions (4.1), (5.7), (6.7), (6.3), (6.17) implies that

$$
\begin{equation*}
Q_{R} \lesssim C(K) R^{\varepsilon}+K_{1}^{-2\left(1-\frac{3}{q}\right)} Q_{R / K_{1}}+K^{-2} Q_{R / K}+K_{1}^{\frac{3}{2}+\frac{1}{q}} K^{\frac{5}{q}-\frac{3}{2}} Q_{R / K} \tag{6.18}
\end{equation*}
$$

and hence an appropriate choice of $K_{1}, K$ shows that

$$
\begin{equation*}
Q_{R} \ll R^{\varepsilon} \text { for } q>\frac{10}{3} \tag{6.19}
\end{equation*}
$$

Remark. The use of different scales in previous analysis (and even more so in $\S 3$ ) is reminiscent of the 'induction on scales' approach form [Wo2] and [T1], although the present argument is considerably simpler. In particular, it suffices to take $K, K_{1}$ to be large constants, rather than $R$-dependent (i.e. $R^{\varepsilon}$-factors), though this point is inessential.
(7). One may also consider the hyperbolic case, for instance

$$
\begin{equation*}
\phi(x, y)=x_{1} y_{1}+x_{2} y_{2}+x_{3} y_{1} y_{2} \tag{7.1}
\end{equation*}
$$

The hyperbolic case was studied by Vargas in [V], adapting the bilinear method. She proved the same estimates in the hyperbolic case that Tao proved in the elliptic case - in particular that the restriction operator is bounded from $L^{\infty}$ into $L^{p}$ for $p>10 / 3$. Our method gives nearly the same estimate, losing a factor of $R^{\epsilon}$.

The preceding may be repeated verbatim, except for the analysis of (6.13'). The condition becomes $\left(v_{1}^{2}+v_{2}^{2}=1\right)$

$$
\begin{equation*}
\left|v_{1}\right|\left|v_{2}\right|\left|t_{1}^{2}-t_{2}^{2}-\left(t_{1}^{\prime}\right)^{2}+\left(t_{1}^{\prime}\right)^{2}\right| \lesssim C \frac{K_{1}}{K} \tag{7.2}
\end{equation*}
$$

and the case where $v_{1}$ or $v_{2}$ is small has to be treated separately.
Suppose $\left|v_{2}\right|<\frac{1}{K_{1}}$. Let $\Omega=\bigcup_{1 \leq s \lesssim K_{1}} \omega_{s}$ be a partition in horizontal stripes of width $\frac{1}{K_{1}}$. Recalling (6.1)-(6.3), for $x \in B(a, R)$, the only significant contribution to $T f(x)$ is given by

$$
\begin{equation*}
2 \max _{s}\left|\int_{\omega_{s}} e^{i \phi(x, y)} f(y) d y\right| \lesssim\left[\sum_{s}\left|\int_{\omega_{s}} e^{i \phi(x, y)} f(y) d y\right|^{q}\right]^{\frac{1}{q}} \tag{7.3}
\end{equation*}
$$

since $\ell=b+t v=b+t e_{1}+0\left(\frac{1}{K_{1}}\right)$ by assumption on $v$.
The contribution of (7.3) is at most

$$
\begin{equation*}
K_{1}^{\frac{1}{q}} \cdot\left\|\int_{\omega} e^{i \phi(x, y)} f(y) d y\right\|_{L^{q}\left(B_{R}\right)} \tag{7.4}
\end{equation*}
$$

where $\omega=[0,1] \times\left[0, \frac{1}{K_{1}}\right]$.
A rescaling $(x, y) \mapsto\left(x_{1}, K_{1} x_{2}, K_{1} x_{3} ; K_{1} x_{3} ; y_{1}, \frac{1}{K_{1}} y_{2}\right)$ shows that

$$
\left\|\int_{\omega} e^{i \phi(x, y)} f(y) d y\right\|_{L^{q}\left(B_{R}\right)} \leq K_{1}^{-1+\frac{2}{q}} Q_{R}
$$

which in (6.18) gives an extra term $K_{1}^{-1+\frac{3}{q}} Q_{R}$.

## §3. Higher Dimensional Restriction Estimates

The method presented in $\S 2$ easily generalizes to arbitrary dimension, considering the Fourier restriction/extension problem for a smooth, compact hyper-surface $S$ in $\mathbb{R}^{n}$ with positive definite second fundamental form. For $x \in S$, denote $x^{\prime} \in S^{(n-1)}$ the normal vector at the point $x$ and let ${ }^{\sim}: S^{(n-1)} \rightarrow S$ be the Gauss map. Thus $\widetilde{x^{\prime}}=x$.

In this section, we establish Theorem $1^{\prime}$, implying in turn Theorem 1 by the ' $\varepsilon$ removal lemma' presented in the Appendix.

1. Let $U_{1}, \ldots, U_{n} \subset S$ be small caps such that $\left|x_{1}^{\prime} \wedge \cdots \wedge x_{n}^{\prime}\right|>c$ for $x_{i} \in U_{i}$.

Let $M$ be large and $\mathcal{D}_{i} \subset U_{i}(1 \leq i \leq n)$ discrete sets of $\frac{1}{M}$-separated points.
Let $B_{M} \subset \mathbb{R}^{n}$ be a ball of radius $M$. Then, for $q=\frac{2 n}{n-1}$

$$
\begin{equation*}
\int_{B_{M}} \prod_{i=1}^{n}\left|\sum_{\xi \in \mathcal{D}_{i}} a(\xi) e^{i x . \xi}\right|^{q / n} \ll M^{\varepsilon} \prod_{i=1}^{n}\left[\sum_{\xi \in \mathcal{D}_{i}}|a(\xi)|^{2}\right]^{\frac{q}{2 n}} \tag{1.1}
\end{equation*}
$$

## Proof.

This is just a discretized version of Theorem 1.16 in [BCT] as our assumption on $U_{1}, \ldots, U_{n}$ ensures the required transversality condition (see the discussion in the beginning of $\S 5)$.

We can assume $B_{M}$ centered at 0 . Introduce functions $g_{i}$ on $U_{i}$ defined by

$$
\left\{\begin{array}{l}
g_{i}(\zeta)=a(\xi) \text { if }|\zeta-\xi|<\frac{c}{M}, \xi \in \mathcal{D}_{i}  \tag{1.2}\\
g_{i}(\zeta)=0 \text { otherwise }
\end{array}\right.
$$

( $c>0$ a small constant). One may then replace $\sum_{\xi \in \mathcal{D}_{i}} a(\xi) e^{i x . \xi}$ by $c^{\prime} M^{n-1} \int_{S} g_{i}(\zeta) e^{i x . \zeta} \sigma(d \zeta)$ if $x \in B_{M}$. Hence

$$
\begin{align*}
& \int_{B_{M}} \prod_{i=1}^{n}\left|\sum_{\zeta \in \mathcal{D}_{i}} a(\xi) e^{i x . \xi}\right|^{q / n} d x \lesssim \\
& M^{(n-1) q} \int_{B_{M}} \prod_{i=1}^{n}\left|\int_{S} g_{i}(\zeta) e^{i x \zeta} \sigma(d \zeta)\right|^{q / n} d x \stackrel{[\mathrm{BCT}]}{\ll}  \tag{1.3}\\
& M^{(n-1) q+\varepsilon} \prod_{i=1}^{n}\left\|g_{i}\right\|_{L^{2}\left(U_{i}\right)}^{q / n} \sim M^{\frac{n-1}{2} q+\varepsilon} \prod_{i=1}^{n}\left[\sum_{\xi \in \mathcal{D}_{i}}|a(\xi)|^{2}\right]^{\frac{q}{2 n}} .
\end{align*}
$$

Since $\int_{B_{M}}$ refers to the average, (1.1) follows, since $q=\frac{2 n}{n-1}$.
2. Let $S \subset \mathbb{R}^{n}$ be as above and $2 \leq m \leq n$. Let $V$ be an $m$-dimensional subspace of $\mathbb{R}^{n}, P_{1}, \ldots, P_{m} \in S$ such that

$$
\begin{equation*}
P_{1}^{\prime}, \ldots, P_{m}^{\prime} \in V \text { and }\left|P_{1}^{\prime} \wedge \cdots \wedge P_{m}^{\prime}\right|>c \tag{2.1}
\end{equation*}
$$

and $U_{1}, \ldots, U_{m} \subset S$ sufficiently small neighborhoods of $P_{1}, \ldots, P_{m}$.
Let $M$ be large and $\mathcal{D}_{i} \subset U_{i}(1 \leq i \leq m)$ discrete sets of $\frac{1}{M}$-separated points $\xi \in S$ such that $\operatorname{dist}\left(\xi^{\prime}, V\right)<\frac{c}{M}$. Let $g_{i} \in L^{\infty}\left(U_{i}\right)(1 \leq i \leq m)$. Then letting $q=\frac{2 m}{m-1}$

$$
\begin{align*}
& f_{B_{M}} \prod_{i=1}^{m}\left|\sum_{\xi \in \mathcal{D}_{i}}\left(\int_{|\zeta-\xi|<\frac{c}{M}} g_{i}(\zeta) e^{i x \cdot \zeta} \sigma(d \zeta)\right)\right|^{q / m} d x \ll \\
& M^{\varepsilon}\left\{\int_{B_{M}} \prod_{i=1}^{m}\left[\sum_{\xi \in \mathcal{D}_{i}}\left|\int_{|\zeta-\xi|<\frac{c}{M}} g_{i}(\zeta) e^{i x \cdot \zeta} \sigma(d \zeta)\right|^{2}\right]^{1 / 2 m}\right\}^{q} . \tag{2.2}
\end{align*}
$$

## Proof.

Performing a rotation, we may assume $V=\left[e_{1}, \ldots, e_{m}\right]$ and denote $\tilde{V}$ the image of $V \cap S^{(n-1)}$ under the Gauss map. Let again $B_{M}$ be centered at 0 . For each $\xi \in \bigcup_{i=1}^{m} \mathcal{D}_{i}$ there is by assumption some $\hat{\xi} \in S \cap \tilde{V},|\xi-\hat{\xi}|<\frac{c}{M}$. Write

$$
\begin{equation*}
\int_{|\zeta-\xi|<\frac{c}{M}} g_{i}(\zeta) e^{i x \cdot \zeta} \sigma(d \zeta)=e^{i x \cdot \hat{\xi}} \int_{|\zeta-\xi|<\frac{c}{M}} g_{i}(\zeta) e^{i x .(\zeta-\hat{\xi})} \sigma(d \zeta) . \tag{2.3}
\end{equation*}
$$

Since in the second factor of (2.3), $|\zeta-\hat{\xi}|=o\left(\frac{1}{M}\right)$, we may view it as a constant $a(\xi)$ on $B_{M} \subset \mathbb{R}^{n}$.

Thus we need to estimate

$$
\begin{equation*}
\int_{B_{M}}\left\{\prod_{i=1}^{m}\left|\sum_{\xi \in \mathcal{D}_{i}} e^{i x \cdot \hat{\xi}^{\prime}} a(\xi)\right|^{q / m}\right\} d x \tag{2.4}
\end{equation*}
$$

Writing $x=(u, v) \in B_{M}^{(m)} \times B_{M}^{(n-m)},(2.4)$ may be bounded by

$$
\begin{equation*}
\max _{v \in B_{M}^{(n-m)}} \int_{B_{M}^{(m)}}\left\{\prod_{i=1}^{m}\left|\sum_{\xi \in \mathcal{D}_{i}} e^{i u . \pi_{m}(\hat{\xi})} a_{v}(\xi)\right|^{q / m}\right\} d u \tag{2.5}
\end{equation*}
$$

with $a_{v}(\xi)=e^{i v \cdot \hat{\xi}} a(\xi)$.
Since $S$ has positive definite second fundamental form, $\pi_{m}(S \cap \tilde{V}) \subset V=\left[e_{1}, \ldots, e_{m}\right]$ is a hypersurface in $V$ with same property and the normal vector at $\pi_{m}(\hat{\xi})=(\hat{\xi})^{\prime} \in V$. Since (2.1), application of (1.1) with $n$ replaced by $m$ and $\mathcal{D}_{i}$ by $\left\{\pi_{m} \hat{\xi} ; \xi \in \mathcal{D}_{i}\right\}$ gives the estimate on (2.5)

$$
\ll M^{\varepsilon} \prod_{i=1}^{m}\left[\sum_{\xi \in \mathcal{D}_{i}}|a(\xi)|^{2}\right]^{q / 2 m}
$$

and (2.2) follows.
3. Essential use is made of scaling.

Denote $Q_{R}^{(p)}$ a bound on

$$
\left\|\int_{S} g(\xi) e^{i x \cdot \xi} \sigma(d \xi)\right\|_{L^{p}\left(B_{R}\right)}
$$

with $g \in L^{\infty}(S),|g| \leq 1$ and with $S$ as specified in the beginning of $\S 3$.
Parametrize $S$ (locally) as

$$
\left\{\begin{array}{l}
\xi_{i}=y_{i} \quad(1 \leq i \leq n-1)  \tag{3.1}\\
\xi_{n}=y_{1}^{2}+\cdots+y_{n-1}^{2}+O\left(|y|^{3}\right)
\end{array}\right.
$$

with $y$ taken in a small neighborhood of 0 .
Let $U_{\rho}$ be a $\rho$-cap on $S$ and evaluate

$$
\left\|\int_{U_{\rho}} g(\xi) e^{i x \cdot \xi} \sigma(d \xi)\right\|_{L^{p}\left(B_{R}\right)}
$$

Thus in (3.1) we restrict $y$ to a ball $B(a, \rho) \subset \mathbb{R}^{n-1}$ and evaluate

$$
\begin{equation*}
\left\|\int_{B(a, \rho)} g(y) e^{i\left[x_{1} y_{1}+\cdots+x_{n-1} y_{n-1}+x_{n}\left(|y|^{2}+O\left(|y|^{3}\right)\right)\right]} d y\right\|_{L^{p}\left(B_{R}\right)} \tag{3.2}
\end{equation*}
$$

A shift $y \mapsto y-a$ and a change of variables $x_{i}^{\prime}=x_{i}+x_{n}\left(2 a_{i}+\cdots\right)(1 \leq i<n)$ permits to set $a=0$. Rescale $y=\rho y^{\prime}$ to obtain

$$
\rho^{n-1}\left\|\int_{B(0,1)} g\left(\rho y^{\prime}\right) e^{i\left[\rho x_{1} y_{1}^{\prime}+\cdots+\rho x_{n-1} y_{n-1}^{\prime}+\rho^{2} x_{n}\left(\left|y^{\prime}\right|^{2}+\rho O\left(\left|y^{\prime}\right|^{3}\right)\right)\right]} d y^{\prime}\right\|_{L^{p}\left(B_{R}\right)}
$$

and a further rescaling in $x, x_{i}^{\prime}=\rho x_{i}(1 \leq i \leq n-1), x_{n}^{\prime}=\rho^{2} x_{n}$, gives

$$
\begin{align*}
& \rho^{n-1-(n+1) / p}\left\|\int_{B(0,1)} g\left(\rho y^{\prime}\right) e^{i\left[x_{1}^{\prime} y_{1}^{\prime}+\cdots+x_{n-1}^{\prime} y_{n-1}^{\prime}+x_{n}^{\prime}\left(\left|y^{\prime}\right|^{2}+\rho O\left(\left|y^{\prime}\right|^{3}\right)\right)\right]} d y^{\prime}\right\|_{L^{p}\left(B_{\rho R}\right)}  \tag{3.3}\\
& \leq \rho^{n-1-(n+1) / p} Q_{\rho R}^{(p)}
\end{align*}
$$

4. Let $g \in L^{\infty}(S),|g| \leq 1$ and consider for $x \in B_{R}$

$$
\begin{equation*}
\int_{S} g(\xi) e^{i x . \xi} \sigma(d \xi) \tag{4.1}
\end{equation*}
$$

Let

$$
R^{\varepsilon} \gg K_{n} \gg K_{n-1} \gg \cdots \gg K_{1}
$$

be suitably chosen.
Start decomposing $S=\bigcup_{\alpha} U_{\alpha}\left(\frac{1}{K_{n}}\right)$ in caps of size $\frac{1}{K_{n}}$ and write

$$
(4.1)=\sum_{\alpha} \int_{U_{\alpha}\left(\frac{1}{K_{n}}\right)} g(\xi) e^{i x \cdot \xi} \sigma(d \xi)=\sum_{\alpha} c_{\alpha}(x)
$$

Fixing $x$, there are 2 possibilities
(4.2) There are $\alpha_{1}, \alpha_{2}, \ldots, \alpha_{n}$ such that

$$
\begin{equation*}
\left|c_{\alpha_{1}}(x)\right|, \ldots,\left|c_{\alpha_{n}}(x)\right|>K_{n}^{-n} \max _{\alpha}\left|c_{\alpha}(x)\right| \tag{4.3}
\end{equation*}
$$

and

$$
\begin{equation*}
\left|\xi_{1}^{\prime} \wedge \cdots \wedge \xi_{n}^{\prime}\right|>c\left(K_{n}\right) \text { for } \xi_{i} \in U_{\alpha_{i}} \tag{4.4}
\end{equation*}
$$

(4.5) The negation of (4.2), which implies that there is an $(n-1)$-dim subspace $V_{n-1}$ such that

$$
\left|c_{\alpha}(x)\right| \leq K_{n}^{-n} \max _{\alpha}\left|c_{\alpha}(x)\right| \quad \text { if } \quad \operatorname{dist}\left(U_{\alpha}, \tilde{V}_{n-1}\right) \gtrsim \frac{1}{K_{n}}
$$

If (4.2), clearly by (4.3)

$$
\left|\int_{S} g(\xi) e^{i x \cdot \xi} \sigma(d \xi)\right| \leq K_{n}^{n-1} \max \left|c_{\alpha}(x)\right| \leq K_{n}^{2 n-1}\left[\prod_{i=1}^{n}\left|c_{\alpha_{i}}(x)\right|\right]^{\frac{1}{n}}
$$

and

$$
\begin{equation*}
\int_{x(4.2)}\left|\int_{S} g(\xi) e^{i x \cdot \xi} \sigma(d \xi)\right|^{p} \lesssim K_{n}^{p(2 n-1)} \sum_{\substack{\alpha_{1}, \ldots, \alpha_{n} \\(4.4)}} \int_{B_{R}} \prod_{i=1}^{n}\left|\int_{U_{\alpha_{i}\left(\frac{1}{K_{n}}\right)}} g(\xi) e^{i x \cdot \xi} \sigma(d \xi)\right|^{\frac{p}{n}} \tag{4.6}
\end{equation*}
$$

In view of (4.4), the [BCT]-estimate applies to each (4.6) term. Thus

$$
\begin{equation*}
\int_{B_{R}} \prod_{i=1}^{n}\left|\int_{U_{\alpha_{i}\left(\frac{1}{K_{n}}\right)}} g(\xi) e^{i x \cdot \xi} \sigma(d \xi)\right|^{\frac{2}{n-1}} d x \ll C\left(K_{n}\right) R^{\varepsilon} \tag{4.7}
\end{equation*}
$$

Assuming

$$
\begin{equation*}
p \geq \frac{2 n}{n-1} \tag{4.8}
\end{equation*}
$$

we see that

$$
\begin{equation*}
(4.6)<C\left(K_{n}\right) R^{\varepsilon} \tag{4.9}
\end{equation*}
$$

(here and in the sequel, $C(K)$ refers to some power of $K$.)
Next consider the case (4.5). Thus

$$
\begin{aligned}
|(4.1)| & \leq\left|\int_{\operatorname{dist}\left(\xi, \tilde{V}_{n-1}\right) \lesssim \frac{1}{K_{n}}} g(\xi) e^{i x . \xi} \sigma(d \xi)\right|+\frac{1}{K_{n}} \max _{\alpha}\left|\int_{U_{\alpha}\left(\frac{1}{K_{n}}\right)} g(\xi) e^{i x . \xi} \sigma(d \xi)\right| \\
& =(4.10)+(4.11)
\end{aligned}
$$

where $V_{n-1}$ depends on $x$.
Note that, using the argument explained earlier in $\S 1$, we may view $\left|c_{\alpha}(x)\right|$ as essentially constant on balls of size $K_{n}$ (literally speaking, this is of course incorrect and what was done is a replacement of $\left|c_{\alpha}(x)\right|$ by a majorant $\left|c_{\alpha}\right| * \eta_{K_{n}}, \eta_{K}(x)=\frac{1}{K^{d}} \eta\left(\frac{x}{K}\right)$ and $\eta$ a suitable bump-function - we do not repeat these technicalities here.)

Thus the bound (4.10) + (4.11) may be considered valid on $B\left(x, K_{n}\right)$, with a same linear space $V_{n-1}$.

The contribution of (4.11) to $\left\|\int g(\xi) e^{i x . \xi} \sigma(d \xi)\right\|_{p}$ is bounded by

$$
\begin{align*}
\frac{1}{K_{n}}\left(\sum_{\alpha}\left\|\int_{U_{\alpha}} g(\xi) e^{i x \cdot \xi} \sigma(d \xi)\right\|_{p}^{p}\right)^{\frac{1}{p}} & \lesssim \frac{1}{K_{n}} \cdot K_{n}^{\frac{n-1}{p}} \cdot\left(\frac{1}{K_{n}}\right)^{n-1-\frac{n+1}{p}} Q_{R / K_{n}}^{(p)}  \tag{4.12}\\
& =\left(\frac{1}{K_{n}}\right)^{n\left(1-\frac{2}{p}\right)} Q_{R / K_{n}}^{(p)}<\frac{1}{K_{n}} Q_{R}^{(p)}
\end{align*}
$$

Consider the term (4.10). Proceeding similarly, write for $x \in B\left(\bar{x}, K_{n}\right)$

$$
\begin{align*}
& \int_{\text {dist }\left(\xi, \tilde{V}_{n-1}\right) \lesssim \frac{1}{K_{n}}} g(\xi) e^{i x \cdot \xi} \sigma(d \xi)= \\
& \sum_{\alpha} \int_{\left.U_{\alpha}\left(\frac{1}{K_{n-1}}\right) \cap\left[\operatorname{dist} \mid \xi, \tilde{V}_{n-1}\right) \lesssim \frac{1}{K_{n}}\right]} g(\xi) e^{i x \cdot \xi} \sigma(d \xi)=\sum_{\alpha} c_{\alpha}^{(n-1)}(x) \tag{4.13}
\end{align*}
$$

We distinguish the cases
(4.14) There are $\alpha_{1}, \ldots, \alpha_{n-1}$ such that

$$
\begin{equation*}
\left|c_{\alpha_{1}}^{(n-1)}(x)\right|, \ldots,\left|c_{\alpha_{n-1}}^{(n-1)}(x)\right|>K_{n-1}^{-(n-1)} \max _{\alpha}\left|c_{\alpha}^{(n-1)}(x)\right| \tag{4.15}
\end{equation*}
$$

and

$$
\begin{equation*}
\left|\xi_{1}^{\prime} \wedge \ldots \wedge \xi_{n-1}^{\prime}\right|>c\left(K_{n-1}\right) \text { for } \xi_{i} \in U_{\alpha_{i}}\left(\frac{1}{K_{n-1}}\right) \tag{4.16}
\end{equation*}
$$

(4.17) Negation of (4.14), implying that there is an $(n-2)$-dim subspace $V_{n-2} \subset$ $V_{n-1}$ (depending on $x$ ) such that

$$
\left|c_{\alpha}^{(n-1)}(x)\right|<K_{n-1}^{-(n-1)} \max _{\alpha}\left|c_{\alpha}^{(n-1)}(x)\right| \text { for dist }\left(U_{\alpha}, \tilde{V}_{n-2}\right) \gtrsim \frac{1}{K_{n-1}}
$$

This space $V_{n-2}$ can then again be taken the same on a $K_{n-1}$-neighborhood of $x$.
We analyze the contribution of (4.14). By (4.15)

$$
\begin{gather*}
|(4.13)|<K_{n-1}^{2 n-3}\left[\prod_{i=1}^{n-1}\left|c_{\alpha_{i}}^{(n-1)}(x)\right|\right]^{\frac{1}{n-1}}  \tag{4.18}\\
19
\end{gather*}
$$

and hence

$$
\left.\int_{\substack{B\left(\bar{x}, K_{n}\right) \\ x \text { satisfies }(4.14)}} \int_{\operatorname{dist}\left(\xi, \tilde{V}_{n-1}\right) \lesssim \frac{1}{K_{n}}} g(\xi) e^{i x . \xi} \sigma(d \xi)\right|^{p} \leq
$$

$$
\begin{equation*}
K_{n-1}^{p(2 n-3)} \sum_{\substack{\alpha_{1}, \ldots, \alpha_{n-1} \\(4.16)}} \int_{B\left(\bar{x}, K_{n}\right)}\left\{\prod_{i=1}^{n-1}\left|\int_{U_{\alpha_{i}}\left(\frac{1}{K_{n-1}}\right) \cap\left[\operatorname{dist}\left(\xi, \tilde{V}_{n-1}\right) \lesssim \frac{1}{K_{n}}\right]} g(\xi) e^{i x . \xi} \sigma(d \xi)\right|^{p / n-1}\right\} \tag{4.19}
\end{equation*}
$$

We use the bound (2.2) to estimate the individual integrals

Thus $m=n-1, V=V_{n-1}$ and $P_{i}$ is the center of $U_{\alpha_{i}}\left(\frac{1}{K_{n-1}}\right)$. Let $M=K_{n}$ and $\mathcal{D}_{i}$ the centers of a cover of $U_{\alpha_{i}}\left(\frac{1}{K_{n-1}}\right)$ by caps $U_{\alpha}\left(\frac{1}{K_{n}}\right)$.

By (2.2) we get an estimate

$$
\begin{equation*}
(4.20) \ll K_{n}^{\varepsilon} C\left(K_{n-1}\right)\left\{\int_{B\left(\bar{x}, K_{n}\right)} \prod_{i=1}^{n-1}\left[\sum_{\alpha}^{(i)}\left|\int_{U_{\alpha}\left(\frac{1}{K_{n}}\right)} g(\xi) e^{i x . \xi} \sigma(d \xi)\right|^{2}\right]^{\frac{1}{2(n-1)}}\right\}^{q} \tag{4.21}
\end{equation*}
$$

where in $\sum^{(i)}$ the sum is over those $\alpha$ such that $U_{\alpha}\left(\frac{1}{K_{n}}\right) \subset U_{\alpha_{i}}\left(\frac{1}{K_{n-1}}\right)$ and $U_{\alpha}\left(\frac{1}{K_{n}}\right) \cap \tilde{V}_{n-1} \neq \phi$. Clearly

$$
\begin{equation*}
(4.21) \ll K_{n}^{\varepsilon} C\left(K_{n-1}\right)\left\{\int_{B\left(\bar{x}, K_{n}\right)}\left[\sum_{U_{\alpha}\left(\frac{1}{K_{n}}\right) \cap \tilde{V}_{n-1} \neq \phi}\left|\int_{U_{\alpha}\left(\frac{1}{K_{n}}\right)} g(\xi) e^{i x \cdot \xi} \sigma(d \xi)\right|^{2}\right]^{\frac{1}{2}}\right\}^{q} \tag{4.22}
\end{equation*}
$$

If

$$
\begin{equation*}
p \geq \frac{2(n-1)}{n-2}=q \tag{4.23}
\end{equation*}
$$

the contribution of (4.15) may be estimated replacing $p$ by $q=\frac{2(n-1)}{n-2}$, and using the [BCT] bound (4.7) with $n$ replaced by $n-1$ and $K_{n}$ by $K_{n-1}$. This gives a bound $R^{\varepsilon}$.

Thus we assume

$$
\begin{equation*}
p<\frac{2(n-1)}{n-2} . \tag{4.24}
\end{equation*}
$$

Then

$$
\begin{equation*}
(4.19)^{1 / p} \ll C\left(K_{n-1}\right) K_{n}^{\varepsilon} \int_{B\left(\bar{x}, K_{n}\right)}\left[\sum_{U_{a}\left(\frac{1}{K_{n}}\right) \cap \tilde{V}_{n-1} \neq \phi}\left|\int_{U_{\alpha}\left(\frac{1}{K_{n}}\right)} g(\xi) e^{i x \cdot \xi} \sigma(d \xi)\right|^{2}\right]^{\frac{1}{2}} \tag{4.25}
\end{equation*}
$$

Note that $U_{\alpha}\left(\frac{1}{K_{n}}\right) \cap \tilde{V}_{n-1} \neq \phi$ for $\sim K_{n}^{n-2}$ values of $\alpha$.
Hence, by Hölder's inequality, the integrand in (4.25) is at most

$$
\begin{equation*}
K_{n}^{(n-2)\left(\frac{1}{2}-\frac{1}{p}\right)}\left[\sum_{\alpha}\left|\int_{U_{\alpha}\left(\frac{1}{K_{n}}\right)} g(\xi) e^{i x \cdot \xi} \sigma(d \xi)\right|^{p}\right]^{\frac{1}{p}} \tag{4.26}
\end{equation*}
$$

where $\alpha$ is unrestricted in the $\alpha$-summation. Substituting (4.26) in (4.25) gives

$$
(4.19) \ll C\left(K_{n-1}\right) K_{n}^{(n-2)\left(\frac{p}{2}-1\right)+\varepsilon} \int_{B\left(\bar{x}, K_{n}\right)}\left[\sum_{\alpha}\left|\int_{U_{\alpha}\left(\frac{1}{K_{n}}\right)} g(\xi) e^{i x \cdot \xi} \sigma(d \xi)\right|^{p}\right]
$$

and integrating over $B_{R}$ permits to bound the (4.14)-contribution by

$$
\begin{equation*}
C\left(K_{n-1}\right) K_{n}^{(n-2)\left(\frac{1}{2}-\frac{1}{p}\right)+\varepsilon}\left[\sum_{\alpha}\left\|\int_{U_{\alpha}\left(\frac{1}{K_{n}}\right)} g(\xi) e^{i x . \xi} \sigma(d \xi)\right\|_{L^{p}\left(B_{R}\right)}^{p}\right]^{1 / p} \tag{4.27}
\end{equation*}
$$

Invoking again the rescaling inequality (3.3), this gives

$$
\begin{equation*}
C\left(K_{n-1}\right) K_{n}^{(n-2)\left(\frac{1}{2}-\frac{1}{p}\right)+\frac{n-1}{p}-(n-1)+\frac{n+1}{p}+\varepsilon} Q_{R / K_{n}}=C\left(K_{n-1}\right) K_{n}^{\frac{n+2}{p}-\frac{n}{2}+\varepsilon} \tag{4.28}
\end{equation*}
$$

Taking $K_{n}$ sufficiently large compared with $K_{n-1}$, we see that the (4.14)-contribution is taken care of if either $p \geq \frac{2(n-1)}{n-2}$ or

$$
\begin{equation*}
p>2+\frac{4}{n} . \tag{4.29}
\end{equation*}
$$

Thus we impose

$$
\begin{equation*}
p>\min \left(\frac{2(n-1)}{n-2}, \frac{2(n+2)}{n}\right) \tag{4.30}
\end{equation*}
$$

Next we need to consider the contribution of (4.17).
The analysis is analogous to the preceding, replacing $n-1$ by $n-2$ and $K_{n}$ by $K_{n-1}$. More precisely, if

$$
\begin{equation*}
p<\frac{2(n-2)}{n-3} \tag{4.31}
\end{equation*}
$$

the local estimate (4.25) becomes

$$
\begin{equation*}
c\left(K_{n-2}\right) K_{n-1}^{\varepsilon} \int_{B\left(\bar{x}, K_{n-1}\right)}\left[\sum_{U_{\alpha}\left(\frac{1}{K_{n-1}}\right) \cap \tilde{V}_{n-2} \neq \phi}\left|\int_{U_{\alpha}\left(\frac{1}{\left.K_{n-1}\right)}\right.} g(\xi) e^{i x . \xi} \sigma(d \xi)\right|^{2}\right]^{\frac{1}{2}} \tag{4.32}
\end{equation*}
$$

and $U_{\alpha}\left(\frac{1}{K_{n-1}}\right) \cap \tilde{V}_{n-2} \neq \phi$ for $\sim K_{n-1}^{n-3}$ values of $\alpha$.
This leads to the condition on $p$

$$
\begin{equation*}
p>\min \left(\frac{2(n-2)}{n-3}, \frac{2(n+3)}{n+1}\right) . \tag{4.33}
\end{equation*}
$$

The continuation of the process is clear.
Eventually we see that the exponent $p$ needs to satisfy

$$
\begin{equation*}
p>2 \min \left\{\frac{k}{k-1}, \frac{2 n-k+1}{2 n-k-1}\right\} \text { for all } 2 \leq k \leq n \tag{4.34}
\end{equation*}
$$

Hence we obtain.

## Theorem 1'.

$Q_{R}^{(p)} \ll R^{\varepsilon}$ provided

$$
\begin{aligned}
p \geq 2 \frac{4 n+3}{4 n-3} & \text { if } n \equiv 0(\bmod 3) \\
p \geq \frac{2 n+1}{n-1} & \text { if } n \equiv 1(\bmod 3) \\
p \geq \frac{4(n+1)}{2 n-1} & \text { if } n \equiv 2(\bmod 3) .
\end{aligned}
$$

## $\S 4$ Improving Upon the Exponent in the 3D Restriction Problem

We consider the case of the paraboloid (though the argument generalizes).
Going back to the analysis in $\S 2$, the main idea is to collect the contributions obtained at different scales, rather than performing an induction on scale argument. This will allow us to bring into play also T. Wolff's $\frac{5}{2}$-bound for the Kakeya maximal function. (see [Wo1]).

## 1. Representation at scale 1

Fix large parameters $K \gg K_{1} \gg 1$


Recalling the analysis in $\S 2$, we have

$$
\begin{aligned}
|T f| & \leq C(K) \max _{\substack{i_{1}, i_{2}, i_{3} \\
\text { non-collinear }}}\left(\left|T f_{i_{1}}\right| \cdot\left|T f_{i_{2}}\right|\left|T f_{i_{3}}\right|\right)^{\frac{1}{3}}+\max _{\operatorname{dist}\left(\mathcal{L}^{\prime}, \mathcal{L}^{\prime \prime}\right)>\frac{1}{K_{1}}}\left|\sum_{i \in \mathcal{L}^{\prime}} T f_{i}\right|^{\frac{1}{2}}\left|\sum_{i \in \mathcal{L}^{\prime \prime}} T f_{i}\right|^{\frac{1}{2}} \\
& +\max _{a}\left|T\left(\left.f\right|_{B\left(a, \frac{1}{K_{1}}\right)}\right)\right| \\
& =(1.1)+(1.2)+(1.3) .
\end{aligned}
$$

Here $\mathcal{L}^{\prime}, \mathcal{L}^{\prime \prime} \subset \mathcal{L}$ are separated segments of a 'line' $\mathcal{L}$.


Since

$$
\left[\int_{B(a, K)}(1.2)^{4}\right]^{\frac{1}{4}} \leq C\left(K_{1}\right)\left(\sum_{i \in \mathcal{L}}\left|T f_{i}\right|^{2}\right)^{\frac{1}{2}}
$$

we may write

$$
(1.2)=\phi \cdot\left(\sum_{\substack{i \in \mathcal{L} \\ 23}}\left|T f_{i}\right|^{2}\right)^{\frac{1}{2}}
$$

with

$$
\left(\int_{B(a, K)}|\phi|^{4}\right)^{\frac{1}{4}}<c\left(K_{1}\right)
$$

and $\phi$ constant on balls of radius 1 .
In what follows, we identify small discs $\subset \Omega$ and the corresponding caps $\subset S$ obtained as image under the map $y \mapsto\left(y_{1}, y_{2}, y_{1}^{2}+y_{2}^{2}\right)$, which are both denoted by $\tau$.
2. Representation of $T f_{\tau}$ (by rescaling).

Let $\tau$ be a $\delta$-cap and rescale.
Up to linear transformation of the form

$$
\left\{\begin{array}{l}
x_{1}^{\prime}=x_{1}+a_{1} x_{3} \\
x_{2}^{\prime}=x_{2}+a_{2} x_{3} \\
x_{3}^{\prime}=x_{3}
\end{array}\right.
$$

and reduction to scale 1 by transformation

$$
\left\{\begin{array}{l}
x_{1}^{\prime}=\delta x_{1} \\
x_{2}^{\prime}=\delta x_{2} \\
x_{3}^{\prime}=\delta^{2} x_{3}
\end{array}\right.
$$

we obtain


Applying at unit scale the representation from (1) and scaling back, we obtain on the $\left(\frac{K}{\delta} \times \frac{K}{\delta} \times \frac{K}{\delta^{2}}\right)$-box


Given a $\delta$-cap $\tau$, denote $\stackrel{o}{\tau}$ the polar set

$$
\tau \rightarrow \stackrel{o}{\tau}=\left(\frac{1}{\delta} \times \frac{1}{\delta} \times \frac{1}{\delta^{2}}\right) \text { box }
$$



On every $K_{\tau}^{o}$-box $B, \phi_{\tau}$ satisfies

$$
\begin{align*}
\int_{B} \phi_{\tau}^{4} & =\frac{1}{|B|} \int_{B} \phi_{\tau}^{4} \\
& =\frac{\delta^{4}}{K^{3}} \cdot \delta^{-4} \int_{B(a, K)} \phi_{\tau}\left(\delta^{-1} x_{1}^{\prime}, \delta^{-1} x_{2}^{\prime}, \delta^{-2} x_{3}^{\prime}\right)^{4} d x_{1}^{\prime} d x_{2}^{\prime} d x_{3}^{\prime}  \tag{2.4}\\
& <C\left(K_{1}\right)
\end{align*}
$$

and $\phi_{\tau}$ is essentially constant on $\stackrel{o}{\tau}$-boxes.

## 3. Iteration

Apply the decomposition (2.1)-(2.3) to each $T f_{\tau_{i}}$ in (2.2) and $T f_{\tau^{\prime}}$ in (2.3).
Considering $T f_{\tau_{i}}$, let $\phi_{\tau_{i}}$ be the corresponding factor appearing in (2.2).
Thus $\phi_{\tau_{i}}$ is constant on $\stackrel{o}{\tau}_{i}$-boxes and $\int_{B^{\prime}} \phi_{\tau_{i}}^{4}<C\left(K_{1}\right)$ if $B^{\prime}$ is a $K{ }_{\tau_{i}}^{o}$-box.
Let $B^{\prime}$ be a $K_{\tau_{i}}^{o}$-box and subdivide $B^{\prime}$ as

$$
B^{\prime}=\bigcup B_{\alpha}^{\prime}
$$

with $B_{\alpha}^{\prime} \stackrel{o}{\tau}_{i}$-boxes. Then

$$
\begin{equation*}
\int_{B^{\prime}} \phi_{\tau}^{4} \phi_{\tau_{i}}^{4} \sim \sum_{\alpha}\left[\left.\phi_{\tau_{i}}\right|_{B_{\alpha}^{\prime}}\right]^{4} \int_{B_{\alpha}^{\prime}} \phi_{\tau}^{4} . \tag{3.1}
\end{equation*}
$$

Note that $\stackrel{o}{\tau}_{i}$ is an $\left[\frac{K}{\delta} \times \frac{K}{\delta} \times \frac{K^{2}}{\delta^{2}}\right]$-box in direction $\xi_{i}$-normal at $\tau_{i}$. Let $\xi$ be any normal for $\tau$. Thus $\measuredangle\left(\xi, \xi_{i}\right)<\delta$ and $K \tau$ is contained in $\left[2 \frac{K}{\delta} \times 2 \frac{K}{\delta} \times 2 \frac{K}{\delta^{2}}\right]$-box in direction $\xi_{i}$. It follows that $\stackrel{o}{\tau}_{i}$ may be partitioned in $K \underset{\tau}{\boldsymbol{\tau}}$-boxes $B$ and hence by (2.4)

$$
\begin{equation*}
\int_{B_{\alpha}^{\prime}} \phi_{\tau}^{4} \leq \max _{B} \int_{B} \phi_{\tau}^{4}<C\left(K_{1}\right) . \tag{3.2}
\end{equation*}
$$

Substituting (3.2) in (3.1) gives

$$
\begin{equation*}
C\left(K_{1}\right) \sum_{\alpha} \int_{B_{\alpha}^{\prime}} \phi_{\tau_{i}}^{4}=C\left(K_{1}\right) \int_{B^{\prime}} \phi_{\tau_{i}}^{4}<C\left(K_{1}\right)^{2}\left|B^{\prime}\right| . \tag{3.3}
\end{equation*}
$$

Note also that in (2.2) $\mathcal{L}$ consists of at most $K \frac{\delta}{K}$-discs. Iteration of (2.1)-(2.3), where we terminate the process for (2.1) and continue for (2.2), gives a representation

$$
\begin{align*}
& |T f| \leq \\
& R^{\varepsilon} \max _{1>\delta>\frac{1}{\sqrt{R}}} \max _{\mathcal{E}_{\delta}}\left[\sum_{\tau \in \mathcal{E}_{\delta}}\left(\phi_{\tau}\left|T f_{\tau_{1}}\right|^{1 / 3}\left|T f_{\tau_{2}}\right|^{1 / 3}\left|T f_{\tau_{3}}\right|^{1 / 3}\right)^{2}\right]^{\frac{1}{2}}  \tag{3.4}\\
& +\max _{\mathcal{E} \frac{1}{\sqrt{R}}}\left[\sum_{\tau \in \mathcal{E}}\left(\phi_{\tau}\left|T f_{\tau}\right|\right)^{2}\right]^{\frac{1}{2}} \tag{3.5}
\end{align*}
$$

where
(3.6) $\mathcal{E}_{\delta}$ consists of at most $\frac{1}{\delta}$ disjoint $\delta$-caps $\tau$
(3.7) $\tau_{1}, \tau_{2}, \tau_{3} \subset \tau$ are $\frac{1}{K \delta}$-size and non-collinear
(3.8) $\int_{B} \phi_{\tau}^{4}<C\left(K_{1}\right)^{\frac{\log \frac{1}{\delta}}{\log K}}<R^{\frac{\log C\left(K_{1}\right)}{\log K}} \ll R^{\varepsilon}$ if $B$ is a $\stackrel{o}{\tau}$-box.

Fix dyadic $1>\delta>\frac{1}{\sqrt{R}}$ and consider

$$
\begin{equation*}
\max _{\mathcal{E}_{\delta}}\left[\sum_{\tau \in \mathcal{E}_{\delta}}\left(\phi_{\tau}\left|T f_{\tau_{1}}\right|^{1 / 3}\left|T f_{\tau_{2}}\right|^{1 / 3}\left|T f_{\tau_{3}}\right|^{1 / 3}\right)^{2}\right]^{\frac{1}{2}} \tag{3.9}
\end{equation*}
$$

with $\mathcal{E}_{\delta}$ and $\tau_{1}, \tau_{2}, \tau_{3}$ as above.
In what follows, we will make several estimates on (3.9) considering various norms.
4. We assume $|f| \leq 1$. By rescaling, for $\tau_{1}, \tau_{2}, \tau_{3} \subset \tau$ as in (3.7),

$$
\begin{equation*}
\int_{B_{R}}\left|T f_{\tau_{1}}\right| \cdot\left|T f_{\tau_{2}}\right| \cdot\left|T f_{\tau_{3}}\right| \leq \delta^{2} \int_{B_{\delta R}}\left|T g_{U_{1}}\right|\left|T g_{U_{2}}\right|\left|T g_{U_{3}}\right| \tag{4.1}
\end{equation*}
$$

with $|g|<1$ and $U_{1}, U_{2}, U_{3} \subset B_{1}$ of size $\sim \frac{1}{K}$ and not collinear.
Hence, from $[\mathrm{BCT}]$

$$
\begin{equation*}
\int_{B_{\delta R}}\left|T g_{U_{1}}\right|\left|T g_{U_{2}}\right|\left|T g_{U_{3}}\right| \ll R^{\varepsilon} \tag{4.2}
\end{equation*}
$$

and

$$
\begin{equation*}
\int_{B_{R}}\left|T f_{\tau_{1}}\right| \cdot\left|T f_{\tau_{2}}\right| \cdot\left|T f_{\tau_{3}}\right| \ll \delta^{2} R^{\varepsilon} \tag{4.3}
\end{equation*}
$$

By (3.6) and Hölder

$$
\begin{align*}
& {\left[\sum_{\tau \in \mathcal{E}_{\delta}}\left(\phi_{\tau}\left|T f_{\tau_{1}}\right|^{\frac{1}{3}} \cdot\left|T f_{\tau_{2}}\right|^{\frac{1}{3}} \cdot\left|T f_{\tau_{3}}\right|^{\frac{1}{3}}\right)^{2}\right]^{\frac{1}{2}} \leq} \\
& \left|\mathcal{E}_{\delta}\right|^{\frac{1}{6}}\left[\sum_{\tau} \phi_{\tau}^{3}\left|T f_{\tau_{1}}\right| \cdot\left|T f_{\tau_{2}}\right| \cdot\left|T f_{\tau_{3}}\right|\right]^{\frac{1}{3}} \leq \\
& \quad \delta^{-\frac{1}{6}}\left[\sum_{\tau} \phi_{\tau}^{3}\left|T f_{\tau_{1}}\right|\left|T f_{\tau_{2}}\right|\left|T f_{\tau_{3}}\right|\right]^{1 / 3} \tag{4.4}
\end{align*}
$$

where in (4.4) $\tau$ ranges over a partition in $\delta$-discs (note that (4.4) does not depend on $\mathcal{E}_{\delta}$ anymore).

We obtain

$$
\begin{equation*}
\|(3.9)\|_{L^{3}\left(B_{R}\right)} \leq \delta^{-\frac{1}{6}}\left[\sum_{\tau} \int \phi_{\tau}^{3}\left|T f_{\tau_{1}}\right|\left|T f_{\tau_{2}}\right|\left|T f_{\tau_{3}}\right|\right]^{1 / 3} \tag{4.5}
\end{equation*}
$$

Consider a partition of $B_{R}$ in $\stackrel{o}{\tau}$-boxes $B$. Since $\left|T f_{\tau_{i}}\right|$ are $\approx$ constant on $\stackrel{o}{\tau_{i}}$-boxes, hence on each $B$,

$$
\begin{align*}
\int \phi_{\tau}^{3}\left|T f_{\tau_{1}}\right|\left|T f_{\tau_{2}}\right|\left|T f_{\tau_{3}}\right| & \left.\approx \sum_{B}\left(\left|T f_{\tau_{1}}\right|\left|T f_{\tau_{2}}\right|\left|T f_{\tau_{3}}\right|\right)\right|_{B}\left(\int_{B} \phi_{\tau}^{3}\right) \\
& \approx \sum_{B}\left[\int_{B}\left|T f_{\tau_{1}}\right| \cdot\left|T f_{\tau_{2}}\right| \cdot\left|T f_{\tau_{3}}\right|\right] \int_{B} \phi_{\tau}^{3} \\
& \stackrel{(3.8)}{<} R^{\varepsilon} \int_{B_{R}}\left|T f_{\tau_{1}}\right| \cdot\left|T f_{\tau_{2}}\right| \cdot\left|T f_{\tau_{3}}\right| \\
& \stackrel{(4.3)}{<} R^{\varepsilon} \delta^{2} . \tag{4.6}
\end{align*}
$$

Therefore

$$
\begin{equation*}
\|(3.9)\|_{L^{3}\left(B_{R}\right)} \ll R^{\varepsilon} \delta^{-\frac{1}{6}} \tag{4.7}
\end{equation*}
$$

which is our first bound.
5. Take $3 \leq p \leq 4$.

By Hölder again

$$
\begin{aligned}
(5.1)= & \max _{\mathcal{E}_{\delta}}\left[\sum_{\tau \in \mathcal{E}_{\delta}}\left(\phi_{\tau}\left|T f_{\tau_{1}}\right|^{1 / 3}\left|T f_{\tau_{2}}\right|^{1 / 3}\left|T f_{\tau_{3}}\right|^{1 / 3}\right)^{2}\right]^{1 / 2} \leq \\
& \left(\frac{1}{\delta}\right)^{\frac{1}{2}-\frac{1}{p}}\left[\sum_{\tau} \phi_{\tau}^{p}\left(\left|T f_{\tau_{1}}\right| \cdot\left|T f_{\tau_{2}}\right| \cdot\left|T f_{\tau_{3}}\right|\right)^{\frac{p}{3}}\right]^{\frac{1}{p}}
\end{aligned}
$$

implying

$$
\begin{equation*}
\|(5.1)\|_{p} \leq\left(\frac{1}{\delta}\right)^{\frac{1}{2}-\frac{1}{p}}\left[\sum_{\tau} \int_{B_{R}} \phi_{\tau}^{p}\left(\left|T f_{\tau_{1}}\right| \cdot\left|T f_{\tau_{2}}\right| \cdot\left|T f_{\tau_{3}}\right|\right)^{p / 3}\right]^{\frac{1}{p}} . \tag{5.2}
\end{equation*}
$$

As in (4.6)

$$
\begin{align*}
& \int_{B_{R}} \phi_{\tau}^{p}\left(\left|T f_{\tau_{1}}\right| \cdot\left|T f_{\tau_{2}}\right| \cdot\left|T f_{\tau_{3}}\right|\right)^{p / 3} \leq \\
& {\left[\max _{B}^{\stackrel{\sim}{\tau}-\text { box }}\right.} \\
& R^{\varepsilon}\left[\int_{B_{R}} \mid T f_{\tau}^{p}\right]\left[|\cdot| T f_{\mathcal{T}_{2}}|\cdot| T f_{\tau_{3}} \mid\right] \cdot \delta^{6\left(\frac{p}{3}-1\right)} \\
& \left.\left.\quad<R_{\tau_{1}}^{\varepsilon}|\cdot| T f_{\tau_{2}}|\cdot| T f_{\tau_{3}} \mid\right)^{p / 3}\right] \leq \tag{5.3}
\end{align*}
$$

by (3.8), (4.3) and since $\left\|T f_{\tau_{1}}\right\|_{\infty}<\delta^{2}$.
Substituting (5.3) in (5.2) gives

$$
\begin{equation*}
R^{\varepsilon}\left(\frac{1}{\delta}\right)^{\frac{1}{2}-\frac{1}{p}}\left(\frac{1}{\delta}\right)^{\frac{2}{p}} \delta^{2-\frac{4}{p}}=R^{\varepsilon} \delta^{\frac{3}{2}-\frac{5}{p}} \tag{5.4}
\end{equation*}
$$

Hence

$$
\begin{equation*}
\|(3.9)\|_{L^{p}\left(B_{R}\right)} \ll R^{\varepsilon} \text { for } p \geq \frac{10}{3}=p_{0} \tag{5.5}
\end{equation*}
$$

Returning to (5.1), let $0<\lambda<1$ be a parameter and denote

$$
\begin{equation*}
g_{\tau}=\left|T f_{\tau_{1}}\right|^{1 / 3} \cdot\left|T f_{\tau_{2}}\right|^{1 / 3} .\left|T f_{\tau_{3}}\right|^{1 / 3} \text { and } g_{\tau, \lambda}=g_{\tau} 1_{\left[g_{\tau} \sim \lambda \delta^{2}\right]} \tag{5.6}
\end{equation*}
$$

Then by (4.3)

$$
\begin{equation*}
\int_{B_{R}}\left[g_{\tau, \lambda}\right]^{p}<\left(\lambda \delta^{2}\right)^{p-3} \int_{B_{R}}\left(g_{\tau, \lambda}\right)^{3} \ll R^{\varepsilon} \lambda^{p-3} \delta^{2 p-4} \tag{5.7}
\end{equation*}
$$

and

$$
\begin{equation*}
\left\{\int_{B_{R}} \max _{\mathcal{E}_{\delta}}\left[\sum_{\tau \in \mathcal{E}_{\delta}}\left(\phi_{\tau} g_{\tau, \lambda}\right)^{2}\right]^{p_{0} / 2}\right\}^{1 / p_{0}} \ll R^{\varepsilon} \lambda^{1-\frac{3}{p_{0}}}=R^{\varepsilon} \lambda^{\frac{1}{10}} \tag{5.8}
\end{equation*}
$$

Let $1 \leq \mu<\infty$ be another parameter and decompose each $\phi_{\tau}$ as

$$
\begin{gather*}
\phi_{\tau}=\sum_{\mu \text { dyadic }} \phi_{\tau, \mu} \text { where } \\
\phi_{\tau, \mu}=\phi_{\tau} 1_{\left[\phi_{\tau} \sim \mu\right]}  \tag{5.9}\\
\phi_{\tau, 1}=\phi_{\tau} 1_{\left[\phi_{\tau} \leq 1\right]}
\end{gather*}
$$

If $B$ is a $\stackrel{o}{\tau}$-box, (3.8) implies for $\mu>1$

$$
\begin{equation*}
\int_{B} \phi_{\tau, \mu}^{p_{0}} \leq \mu^{-4+p_{0}} \int_{29} \phi_{\tau}^{4} \ll R^{\varepsilon} \mu^{-2 / 3} \tag{5.10}
\end{equation*}
$$

Hence, instead of (5.8), we obtain

$$
\begin{equation*}
\left\{\int_{B_{R}} \max _{\mathcal{E}_{\delta}}\left[\sum_{\tau \in \mathcal{E}_{\delta}}\left(\phi_{\tau, \mu} g_{\tau, \lambda}\right)^{2}\right]^{p_{0} / 2}\right\}^{1 / p_{0}} \ll R^{\varepsilon} \lambda^{\frac{1}{10}} \cdot \mu^{-\frac{1}{5}} \tag{5.11}
\end{equation*}
$$

Next, we perform a different type of estimate. Clearly

$$
\begin{equation*}
\max _{\mathcal{E}_{\delta}}\left[\sum_{\tau \in \mathcal{E}_{\delta}}\left(\phi_{\tau, \mu} g_{\tau, \lambda}\right)^{2}\right]^{\frac{1}{2}} \leq \mu\left(\sum_{\tau} g_{\tau, \lambda}^{2}\right)^{\frac{1}{2}} \tag{5.12}
\end{equation*}
$$

with $\tau$ ranging over a partition in $\delta$-caps.
We apply the usual procedure to bound (5.12) by a Kakeya maximal function.
Writing

$$
\left|T f_{\tau_{i}}\right| \lesssim\left|T f_{\tau_{i}}\right| *\left(\delta^{4} 1_{\tau}\right)
$$

we have

$$
\begin{align*}
g_{\tau}(x) & \lesssim \int\left\{\prod_{i=1}^{3}\left[\left|T f_{\tau_{i}}\right| *\left(\delta^{4} 1_{\tau}\right)\right]^{\frac{1}{3}}\right\}(z)\left(\delta^{4} 1_{\tau}\right)(x-z) d z \\
& =\int \omega(z)\left(\delta^{4} 1_{\tau}\right)(x-z) d z \tag{5.13}
\end{align*}
$$

and

$$
\begin{equation*}
g_{\tau, \lambda}^{2}(x) \lesssim \delta^{4} \int\left(\omega^{2} 1_{\left[\omega \gtrsim \lambda \delta^{2}\right]}\right)(z) 1_{\tau}(x-z) d z \tag{5.14}
\end{equation*}
$$

Further

$$
\begin{align*}
\int_{B_{R}} \omega^{2} 1_{\left[\omega \gtrsim \lambda \delta^{2}\right]} & \lesssim \frac{1}{\lambda \delta^{2}} \int \omega^{3} \\
& \lesssim \frac{1}{\lambda \delta^{2}} \int\left\{\int\left[\prod_{i=1}^{3}\left|T f_{\tau_{i}}\right|\left(x-\tau_{i}\right)\right]^{\frac{1}{3}} d x\right\}\left[\prod_{i=1}^{3}\left(\delta^{4} 1_{\tau}\right)\left(\tau_{i}\right)\right] d z_{1} d z_{2} d z_{3} \\
& \ll R^{\varepsilon} \lambda^{-1} \tag{5.15}
\end{align*}
$$

Hence, from (5.14), (5.15), we obtain a representation

$$
\begin{equation*}
g_{\tau, \lambda}^{2} \ll R^{\varepsilon} \delta^{4} \lambda^{-1} \int_{30} 1_{\tau}(\cdot-y) \mathbb{P}_{\tau}(d y) \tag{5.16}
\end{equation*}
$$

¿From (5.16) and convexity

$$
\begin{align*}
\|(5.12)\|_{L^{p_{0}}\left(B_{R}\right)} & \ll R^{\varepsilon} \lambda^{-\frac{1}{2}} \mu \delta^{2}\left\|\left[\sum_{\tau} 1_{\tau}\left(x-y_{\tau}\right)\right]^{\frac{1}{2}}\right\|_{L^{p_{0}}\left(B_{R}\right)} \\
& =R^{\varepsilon} \lambda^{-\frac{1}{2}} \mu \delta^{2}\left[\int\left[\sum_{\tau} 1_{\tau}\left(x-y_{\tau}\right)\right]^{5 / 3} d x\right]^{3 / 10} \tag{5.17}
\end{align*}
$$

for some choice of $\left\{y_{\tau}\right\}$-points in $\mathbb{R}^{3}$.
At this point we can invoke the $L^{5 / 2}$-bound for the $\mathbb{R}^{3}$-Kakeya maximal function. In its dual formulation, we have

$$
\begin{equation*}
\left\|\sum_{v \in \mathfrak{S}} 1_{T_{v}}\right\|_{L^{5 / 3}} \leq\left(\frac{1}{\kappa}\right)^{\frac{1}{5}+} \tag{5.18}
\end{equation*}
$$

where $T$ is a translate of a tube of width $\kappa$ and length 1 in direction $v \in \mathfrak{S} \subset S_{2}$, where $\mathfrak{S}$ consists of $\kappa$-separated points.

Rescaling by a factor $\delta^{2}$ and applying (5.18) with $\kappa=\delta$, it follows

$$
\begin{equation*}
\left\|\sum_{\tau} 1_{\tau}\left(\cdot-y_{\tau}\right)\right\|_{L^{5 / 3}} \ll \delta^{-\frac{19}{5}-} \tag{5.19}
\end{equation*}
$$

Hence

$$
\begin{equation*}
(5.17) \ll R^{\varepsilon} \lambda^{-\frac{1}{2}} \mu \delta^{\frac{1}{10}} \tag{5.20}
\end{equation*}
$$

which is our final estimate.
Summarizing (4.7), (5.11), (5.20), we have

$$
\begin{equation*}
\left\|\max _{\mathcal{E}_{\delta}}\left[\sum_{\tau \in \mathcal{E}_{\delta}}\left(\phi_{\tau} g_{\tau}\right)^{2}\right]^{\frac{1}{2}}\right\|_{L^{3}\left(B_{R}\right)} \ll R^{\varepsilon} \delta^{-\frac{1}{6}} \tag{5.21}
\end{equation*}
$$

and

$$
\begin{align*}
\left\|\max _{\mathcal{E}_{\delta}}\left[\sum_{\tau \in \mathcal{E}_{\delta}}\left(\phi_{\tau, \mu} g_{\tau, \lambda}\right)^{2}\right]^{\frac{1}{2}}\right\|_{L^{10 / 3}\left(B_{R}\right)} & \ll R^{\varepsilon} \min \left(\lambda^{\frac{1}{10}} \mu^{-\frac{1}{5}}, \lambda^{-\frac{1}{2}} \mu \delta^{\frac{1}{10}}\right) \\
& \ll R^{\varepsilon} \delta^{\frac{1}{60}} \tag{5.22}
\end{align*}
$$

Let

$$
q=\frac{33}{10}
$$

Interpolating between (5.12), (5.22), it follows that

$$
\begin{equation*}
\|(3.4)\|_{L^{q}\left(B_{R}\right)} \ll R^{\varepsilon} . \tag{5.23}
\end{equation*}
$$

6. Remains to bound $\|(3.5)\|_{q}$.

Estimate

$$
\begin{equation*}
\left\|\left[\sum_{\tau \in \mathcal{E}}\left(\phi_{\tau}\left|T f_{\tau}\right|\right)^{2}\right]^{\frac{1}{2}}\right\|_{L^{3}\left(B_{R}\right)} \leq(\sqrt{R})^{\frac{1}{6}}\left\{\sum_{\tau} \int_{B_{R}} \phi_{\tau}^{3}\left|T f_{\tau}\right|^{3}\right\}^{\frac{1}{3}} \tag{6.1}
\end{equation*}
$$

where in the second sum, $\tau$ ranges over a full position in $\frac{1}{\sqrt{R}}$-caps.
Since $\left|T f_{\tau}\right| \lesssim \frac{1}{R},(3.8)$ implies that

$$
\begin{equation*}
(6.1) \ll R^{\frac{1}{12}+\varepsilon} . \tag{6.2}
\end{equation*}
$$

On the other hand, using the decomposition (5.9), we obtain the following estimates on

$$
\begin{equation*}
\left\|\max _{\mathcal{E} \frac{1}{\sqrt{R}}}\left[\sum_{\tau \in \mathcal{E}}\left(\phi_{\tau, \mu}\left|T f_{\tau}\right|\right)^{2}\right]^{\frac{1}{2}}\right\|_{L_{B_{R}}^{p_{0}}} \tag{6.3}
\end{equation*}
$$

Using (5.10), we get

$$
\begin{align*}
(6.3) & \leq(\sqrt{R})^{\frac{1}{2}-\frac{1}{p_{0}}}\left(\sum_{\tau}\left\|\phi_{\tau, \mu}\left|T f_{\tau}\right|\right\|_{L_{B_{R}}^{p_{0}}}^{p_{0}}\right)^{\frac{1}{p_{0}}} \\
& \ll(\sqrt{R})^{\frac{1}{2}-\frac{1}{p_{0}}+\varepsilon} \mu^{-\frac{1}{5}} R^{\frac{1}{p_{0}}}(\sqrt{R})^{\frac{4}{p_{0}}-2} \ll R^{\varepsilon} \mu^{-1 / 5} . \tag{6.4}
\end{align*}
$$

Using the bound $\phi_{\tau, \mu} \lesssim \mu$ and the inequality

$$
\begin{equation*}
\left|T f_{\tau}\right|^{2} \lesssim \frac{1}{R^{2}} \int\left|T f_{\tau}\right|^{2}(y) 1_{\tau}(x-y) d y \tag{6.5}
\end{equation*}
$$

and

$$
\begin{equation*}
\int_{B_{R}}\left|T f_{\tau}\right|^{2} \lesssim 1 \tag{6.6}
\end{equation*}
$$

for $\tau \subset S_{2}$ a $\frac{1}{\sqrt{R}}$-cap, we obtain similarly to (5.17)

$$
\begin{align*}
&(6.3) \leq \mu\left\|\left(\sum_{\tau}\left|T f_{\tau}\right|^{2}\right)^{1 / 2}\right\|_{L_{B_{R}}^{p_{0}}} \\
& \ll \frac{\mu}{R}\left[\left\|\sum_{\tau} 1_{\tau}\left(\cdot-y_{\tau}\right)\right\|_{L_{B_{R}}^{5 / 3}}\right]^{\frac{1}{2}} \\
& \stackrel{(5.19)}{<} \frac{\mu}{R} R^{\frac{19}{20}}=\mu R^{-\frac{1}{20}+\varepsilon} .  \tag{6.7}\\
& 32
\end{align*}
$$

Hence, from (6.4), (6.7)

$$
\begin{equation*}
(6.3) \ll R^{\varepsilon} \min \left(\mu^{-\frac{1}{5}}, \mu R^{-\frac{1}{20}}\right) \ll R^{-\frac{1}{120}+\varepsilon} . \tag{6.8}
\end{equation*}
$$

Interpolation between (6.1), (6.8) implies

$$
\begin{equation*}
\|(3.5)\|_{L^{q}\left(B_{R}\right)} \ll R^{\varepsilon} . \tag{6.9}
\end{equation*}
$$

Hence, we proved
Theorem $2^{\prime}$.

$$
\begin{equation*}
\|T f\|_{L^{q}\left(B_{R}\right)} \ll R^{\varepsilon} \text { for } q \geq \frac{33}{10},|f| \leq 1 \tag{6.10}
\end{equation*}
$$

(implying Theorem 2).
7. One can check how the preceding argument improves if one had the optimal Kakeya maximal function bound at disposal, thus

$$
\begin{equation*}
\left\|\mathcal{M}_{\delta}\right\|_{3 \rightarrow 3} \ll\left(\frac{1}{\delta}\right)^{\varepsilon} \tag{7.1}
\end{equation*}
$$

Recall (5.11)

$$
\begin{equation*}
\left\{\int_{B_{R}} \max _{\mathcal{E}_{\delta}}\left[\sum_{\tau \in \mathcal{E}_{\delta}}\left(\phi_{\tau, \mu} g_{\tau, \lambda}\right)^{2}\right]^{5 / 3}\right\}^{3 / 10} \ll R^{\varepsilon} \lambda^{\frac{1}{10}} \mu^{-\frac{1}{5}} \tag{7.2}
\end{equation*}
$$

Next, apply (5.17) with $p_{0}=3$

$$
\begin{align*}
& \left\|\max _{\mathcal{E}_{\delta}}\left[\sum_{\tau \in \mathcal{E}_{\delta}}\left(\phi_{\tau, \mu} g_{\tau, \lambda}\right)^{2}\right]^{1 / 2}\right\|_{L^{3}\left(B_{R}\right)} \ll \\
& R^{\varepsilon} \lambda^{-\frac{1}{2}} \mu \frac{1}{R}\left[\int\left[\sum_{\tau} 1_{\tau}\left(x-y_{\tau}\right)\right]^{3 / 2} d x\right]^{1 / 3} \ll R^{\varepsilon} \lambda^{-\frac{1}{2}} \mu . \tag{7.3}
\end{align*}
$$

For the (3.5) contribution, recall (6.3), (6.4)

$$
\begin{equation*}
\left\|\max _{\mathcal{E} \frac{1}{\sqrt{R}}}\left[\sum_{\tau \in \mathcal{E}}\left(\phi_{\tau, \mu}\left|T f_{\tau}\right|\right)^{2}\right]^{\frac{1}{2}}\right\|_{L_{\left(B_{R}\right)}^{10 / 3}} \ll R^{\varepsilon} \mu^{-1 / 5} \tag{7.4}
\end{equation*}
$$

and using (6.5), (6.6), (7.1)

$$
\begin{equation*}
\|\cdots\|_{L_{\left(B_{R}\right)}^{3}} \ll R^{\varepsilon} \mu \tag{7.5}
\end{equation*}
$$

Interpolation between (7.2), (7.3) and (7.4), (7.5) gives

$$
\begin{equation*}
\|T f\|_{L^{q_{1}}\left(B_{R}\right)} \ll R^{\varepsilon} \text { for } q \geq \frac{36}{11}=3,27 \ldots \text { and }|f| \leq 1 \tag{7.6}
\end{equation*}
$$

This leads to an improved Theorem 2 with $3 \frac{3}{10}$ replaced by $\frac{36}{11}$.

## §5. The Variable Coefficient Case

We consider Hörmander type oscillatory integral operators of the form

$$
\begin{equation*}
\left(T_{\lambda} f\right)(x)=\int e^{i \lambda \psi(x, y)} f(y) d y \tag{5.1}
\end{equation*}
$$

with real analytic phase function $\psi$ of the form

$$
\begin{equation*}
\psi(x, y)=x_{1} y_{1}+\cdots+x_{d-1} y_{d-1}+x_{d}\left(\langle A y, y\rangle+O\left(|y|^{3}\right)\right)+O\left(|x|^{2}|y|^{2}\right) \tag{5.2}
\end{equation*}
$$

and $\langle A y, y\rangle$ a non-degenerate quadratic form.
Here $x$ (resp. $y$ ) are restricted to a neighborhood of $0 \in \mathbb{R}^{d}$ (resp. $0 \in \mathbb{R}^{d-1}$ ). In order to bring (5.1) in the format considered earlier, rescale $x \rightarrow \frac{x}{\lambda}$ to obtain a phase function

$$
\begin{equation*}
\phi(x, y)=x_{1} y_{1}+\cdots+x_{d-1} y_{d-1}+x_{d}\left(\langle A y, y\rangle+O\left(|y|^{3}\right)\right)+\lambda \phi_{\nu}\left(\frac{x}{\lambda}, y\right) \tag{5.3}
\end{equation*}
$$

and $\phi_{\nu}$ at least quadratic in both $x, y$. Thus (5.1) becomes

$$
\begin{equation*}
(T f)(x)=\int e^{i \phi(x, y)} f(y) d y \tag{5.4}
\end{equation*}
$$

with $x$ restricted to $|x|<o(\lambda)$. This formulation appears as a perturbation of the restriction problem and preceding analysis can be generalized to this setting.

First recall the [BCT] result in the variable coefficient case (see [BCT], Theorem 6.2 which treats the $d$-linear case, but generalizes to lower levels of multi-linearity as formulated in [BCT], (40) for $\phi$ linear in $x$ ).

Thus let $1<k \leq d$ and

$$
\begin{equation*}
\left(T_{i} f\right)(x)=\int_{U_{i}} e^{i \phi_{i}(x, y)} f(y) d y \quad(1 \leq i \leq k) \tag{5.5}
\end{equation*}
$$

with $\phi_{i}$ as in (5.3). We assume the transversality condition

$$
\begin{equation*}
\left|Z_{1}\left(x, y^{(1)}\right) \wedge \cdots \wedge Z_{k}\left(x, y^{(k)}\right)\right|>c \text { for all } x \text { and } y^{(i)} \in U_{i} \tag{5.6}
\end{equation*}
$$

where

$$
\begin{equation*}
Z(x, y)=\partial_{y_{1}}\left(\nabla_{x} \phi\right) \wedge \cdots \wedge \partial_{y_{d-1}}\left(\nabla_{x} \phi\right) \tag{5.7}
\end{equation*}
$$

Then

$$
\begin{equation*}
\left\|\left(\prod_{i=1}^{k}\left|T_{i} f_{i}\right|\right)^{\frac{1}{k}}\right\|_{q} \ll \lambda^{\varepsilon}\left(\prod_{1}^{k}\left\|f_{i}\right\|_{2}\right)^{\frac{1}{k}} \tag{5.8}
\end{equation*}
$$

with $q=\frac{2 k}{k-1}$ and $x$ restricted $|x|<o(|\lambda|)$.
Note that in the restriction problem, $Z(x, y)=Z(y)$ and (5.6) amounts to transversality of the normal vectors at the corresponding hypersurface $S$ which is the graph of $\frac{\partial \phi}{\partial x_{d}}$.

It turns out that the $\lambda^{\varepsilon}$-factor may be removed in (5.8) at the cost of increasing $q$ to $q_{1}>\frac{2 k}{k-1}$. Thus, as proven in Lemma A3 in the Appendix, under the assumptions (5.5)-(5.7), one has

$$
\left\|\left(\prod_{i=1}^{k}\left|T_{i} f_{i}\right|\right)^{\frac{1}{k}}\right\|_{q_{1}} \leq C_{q_{1}}\left(\prod_{1}^{k}\left\|f_{i}\right\|_{2}\right)^{1 / k} \text { for } q_{1}>\frac{2 k}{k-1}
$$

Using (5.8') instead of (5.8) in $\S 2, \S 3$ to bound global multilinear contributions, will eliminate the $R^{\varepsilon}$-factors (cf. $\S 3,(4.7)$ and (4.9) for instance), without the need for an $\varepsilon$-removal at the end (note that the $K^{\varepsilon}$-factors coming from a local application in $\S 3$, (1.1) and (2.2) are harmless).

Remark. We do not claim removal of the $\lambda^{\varepsilon}$-factor in Theorem 6.2 from [BCT], but only in its present application to the operators $T_{i}$ given by (5.5).

Returning to the analysis from $\S 2, \S 3$, also some adjustment is needed with respect to the parabolic rescaling argument that we discuss next.

Note that if we restrict $|y|<\frac{1}{K}$ and rescale, letting $y=\frac{y^{\prime}}{K} ; x_{1}=K x_{1}^{\prime}, \ldots, x_{d-1}=$ $K x_{d-1}^{\prime}$ and $x_{d}=K^{2} x_{d}^{\prime}$, we obtain

$$
\begin{equation*}
\int e^{i \phi^{\prime}\left(x^{\prime}, y^{\prime}\right)} f\left(\frac{y^{\prime}}{K}\right) d y^{\prime} \text { where }\left|x_{1}^{\prime}\right|, \ldots,\left|x_{d-1}^{\prime}\right|<\frac{\lambda}{K},\left|x_{d}^{\prime}\right|<\frac{\lambda}{K^{2}} \tag{5.9}
\end{equation*}
$$

and
$\phi^{\prime}\left(x^{\prime}, y^{\prime}\right)=x_{1}^{\prime} y_{1}^{\prime}+\cdots+x_{d-1}^{\prime} y_{d-1}^{\prime}+x_{d}^{\prime}\left(\left\langle A y^{\prime}, y^{\prime}\right\rangle+\frac{1}{K} O\left(\left|y^{\prime}\right|^{3}\right)\right)+\lambda \phi_{\nu}\left(\frac{K x_{1}^{\prime}}{\lambda}, \ldots, \frac{K x_{d-1}^{\prime}}{\lambda}, \frac{K^{2} x_{d}^{\prime}}{\lambda} ; \frac{y^{\prime}}{K}\right)$
with $x^{\prime}$ subject to the restrictions (5.9).
Compared with (5.4), we see that one needs to consider the more general setting of operators

$$
\begin{equation*}
(T f)(x)=\int e^{i \phi(x, y)} f(y) d y \text { restricting }\left|x_{1}\right|, \ldots,\left|x_{d-1}\right|<R_{1} \text { and }\left|x_{d}\right|<R \tag{5.11}
\end{equation*}
$$

( $R \leq R_{1}$ ), and

$$
\begin{equation*}
\phi(x, y)=x_{1} y_{1}+\cdots+x_{d-1} y_{d-1}+x_{d}\left(\langle A y, y\rangle+0\left(|y|^{3}\right)+R \phi_{\nu}\left(\frac{x_{1}}{R_{1}}, \ldots, \frac{x_{d-1}}{R_{1}}, \frac{x_{d}}{R} ; y\right)\right. \tag{5.12}
\end{equation*}
$$

(we use here that $\phi_{\nu}$ is at least quadratic in $y$ ).
It has to be shown that (5.8') remains valid. It turns out that the issue can be reduced to the $R=R_{1}$ case. We give the details. Let $q>\frac{2 k}{k-1}$.

Partition the region

$$
Q=\left[\left|x_{1}\right|, \ldots,\left|x_{d-1}\right|<R_{1}\right] \times\left[\left|x_{d}\right|<R\right]=\bigcup_{s \leq \frac{R_{1}}{R}} Q_{s}
$$

in $R$-cubes and write

$$
\begin{equation*}
\int_{Q}\left(\prod_{1}^{k}\left|T_{i} f_{i}\right|\right)^{q / k} d x=\sum_{s} \int_{Q_{s}}\left(\prod_{1}^{k}\left|T_{i} f_{i}\right|\right)^{q / k} d x \tag{5.13}
\end{equation*}
$$

Partition the $y$-domain $\Omega \subset \mathbb{R}^{d-1}$ in cubes $\Omega_{\alpha}$ of size $\sim \frac{1}{R}$ centered at $y_{\alpha}$ and write

$$
\left(T_{i} f_{i}\right)(x)=\sum_{\alpha}^{(i)} e^{i \phi\left(x, y_{\alpha}\right)}\left[\int_{\Omega_{\alpha}} f_{i}(y) e^{i\left[\phi(x, y)-\phi\left(x, y_{\alpha}\right)\right]} d y\right]
$$

Restricting $x \in Q_{s}$, the factors [ ] are approximatively constant

$$
c_{i, \alpha}=\int_{\Omega_{\alpha}} f_{i}(y) e^{i\left[\varphi(\bar{x}, y)-\varphi\left(\bar{x}, y_{\alpha}\right)\right]} d y
$$

where $\bar{x}$ is the center of $Q_{s}$. For $|z|<R$

$$
\left|T_{i} f_{i}\right|(\bar{x}+z) \approx\left|\sum_{\alpha}^{(i)} e^{i \eta\left(z, y_{\alpha}\right)} e^{i \phi\left(\bar{x}, y_{\alpha}\right)} c_{i, \alpha}\right|
$$

with $\eta\left(z, y_{\alpha}\right)=\phi\left(\bar{x}+z, y_{\alpha}\right)-\phi\left(\bar{x}, y_{\alpha}\right)$. Hence, defining

$$
g_{i}(y)=c_{i, \alpha} e^{i \phi\left(\bar{x}, y_{\alpha}\right)} \text { for } y \in \Omega_{\alpha}
$$

we have

$$
\left|T_{i} f_{i}\right|(\bar{x}+z) \approx R^{d-1}\left|\int e^{i \eta(z, y)} g_{i}(y) d y\right|
$$

¿From (5.8')

$$
\begin{aligned}
& \int_{B(0, R)}\left[\prod_{1}^{k}\left|T_{i} f_{i}\right|(\bar{x}+z)\right]^{\frac{q}{k}} \leq C R^{q(d-1)}\left(\prod_{1}^{k}\left\|g_{i}\right\|_{2}\right)^{\frac{q}{k}} \\
& \leq C R^{\frac{q(d-1)}{2}}\left[\prod_{1}^{k}\left(\sum_{\alpha}^{(i)}\left|c_{i, \alpha}\right|^{2}\right)^{\frac{1}{2}}\right]^{\frac{q}{k}} \\
& \leq C R^{\frac{q(d-1)}{2}}\left\{\prod_{1}^{k}\left[\sum_{\alpha}^{(i)}\left|\int_{\Omega_{\alpha}} f_{i}(y) e^{i \phi(\bar{x}, y)} d y\right|^{2}\right]^{\frac{1}{2}}\right\}^{\frac{q}{k}}
\end{aligned}
$$

Since $\bar{x}$ is any point in $Q_{s}$, we obtain

$$
\begin{equation*}
R^{\frac{q(d-1)}{2}-d} \int_{Q_{s}}\left\{\prod_{1}^{k}\left[\sum_{\alpha}^{(i)}\left|\int_{\Omega_{\alpha}} f_{i}(y) e^{i \phi(x, y)} d y\right|^{2}\right]^{\frac{1}{2}}\right\}^{\frac{q}{k}} \tag{5.14}
\end{equation*}
$$

Summing over $s$ gives

$$
\begin{equation*}
\int_{Q}\left[\prod_{1}^{k}\left|T_{i} f_{i}\right|\right]^{\frac{q}{k}}<C R^{\frac{q(d-1)}{2}-d} \int_{Q} \prod_{1}^{k}\left[\sum_{\alpha}^{(i)}\left|\int_{\Omega_{\alpha}} f_{i}(y) e^{i \phi(x, y)} d y\right|^{2}\right]^{\frac{q}{2 k}} \tag{5.15}
\end{equation*}
$$

Note that

$$
\begin{align*}
& \int_{Q}\left|\int_{\Omega_{\alpha}} f_{i}(y) e^{i \phi(x, y)} d y\right|^{2} \leq \\
& R . \max _{\left|x_{d}\right|<R} \int\left|\int_{\Omega_{\alpha}} f_{i}(y) e^{i\left[x_{1} y_{1}+\cdots+x_{d-1} y_{d-1}+R \phi_{\nu}\left(\frac{x_{1}}{R_{1}}, \cdots, \frac{x_{d-1}}{R_{1}}, \frac{x_{d}}{R} ; y\right)\right]} d y\right|^{2} d x_{1} \cdots d x_{d-1} \\
& \lesssim R \int_{\Omega_{\alpha}}\left|f_{i}\right|^{2} \tag{5.16}
\end{align*}
$$

using standard orthogonality considerations.

Also there is the trivial bound

$$
\begin{aligned}
\left|\int_{\Omega_{\alpha}} f_{i}(y) e^{i \phi(x, y)} d y\right| & \leq\left|\Omega_{\alpha}\right|^{\frac{1}{2}}\left(\int_{\Omega_{\alpha}}\left|f_{i}\right|^{2}\right)^{\frac{1}{2}} \\
& \leq R^{-\frac{d-1}{2}}\left(\int_{\Omega_{\alpha}}\left|f_{i}\right|^{2}\right)^{\frac{1}{2}}
\end{aligned}
$$

implying

$$
\begin{equation*}
\sum_{\alpha}\left|\int_{\Omega_{\alpha}} f_{i}(y) e^{i \phi(x, y)} d y\right|^{2} \lesssim R^{-(d-1)}\left\|f_{i}\right\|_{2}^{2} \tag{5.17}
\end{equation*}
$$

¿From (5.15), (5.16), (5.17) and Hölder's inequality, it follows that

$$
\begin{align*}
(5.15) & \leq C R^{q \frac{d-1}{2}-d}\left\{\prod_{1}^{k}\left(R^{1-\frac{d-1}{2}(q-2)}\left\|f_{i}\right\|_{2}^{q}\right)\right\}^{1 / k} \\
& \leq C\left(\prod_{1}^{k}\left\|f_{i}\right\|_{2}^{q}\right)^{1 / k} \tag{5.18}
\end{align*}
$$

as claimed.
We also observe that at suitable local scale, the phase function $\phi(x, y)$ given by (5.12) may be linearized in $x$, reducing to the restriction setting. Let $x=a+z \in B(a, \rho)$ and write

$$
\begin{equation*}
\phi(x, y)=\phi(a, y)+\psi(z, y)+\Omega(z, y) \tag{5.19}
\end{equation*}
$$

denoting

$$
\begin{array}{r}
\psi(z, y)=z_{1} y_{1}+\cdots+z_{d-1} y_{d-1}+z_{d}\left(\langle A y, y\rangle+0\left(|y|^{3}\right)\right)+ \\
\frac{R}{R_{1}}\left\langle z^{\prime}, \nabla_{x^{\prime}} \phi_{\nu}\left(\frac{a^{\prime}}{R_{1}}, \frac{a_{d}}{R} ; y\right)\right\rangle+z_{d} \partial_{x_{d}} \phi_{\nu}\left(\frac{a^{\prime}}{R_{1}}, \frac{a_{d}}{R} ; y\right) \tag{5.20}
\end{array}
$$

with $x=\left(x^{\prime}, x_{d}\right)$ and where

$$
\begin{equation*}
|\Omega(z, y)|=o(1) \text { provided } \rho=o(\sqrt{R}) . \tag{5.21}
\end{equation*}
$$

Since $\Omega$ does not oscillate on $B(a, \rho)$, it may be ignored in the phase function.
A suitable coordinate change in $y$ brings $\psi$ in the form

$$
\begin{equation*}
\psi(z, y)=z_{1} y_{1}+\cdots+z_{d-1} y_{d-1}+z_{d}\left(\left\langle A^{\prime} y, y\right\rangle+O\left(|y|^{3}\right)\right) \tag{5.22}
\end{equation*}
$$

with $A^{\prime}$ a perturbation of $A$, hence $A^{\prime}$ non-degenerate (and positive definite if $A$ is positive definite).

Using previous considerations, it is essentially straightforward to carry out the analysis from $\S 2$, $\S 3$ in the setting (5.11), (5.12), assuming again that $A$ is positive definite and using (5.8') to bound the global multilinear contributions.

Hence we obtain

Theorem 3. Consider the operator (5.1) with $\psi$ as in (5.2) and A positive definite. Then

$$
\begin{equation*}
\left\|T_{\lambda} f\right\|_{L_{\text {loc }}^{p}} \leq C_{p} \lambda^{-\frac{d}{p}}\|f\|_{\infty} \tag{5.23}
\end{equation*}
$$

provided

$$
\begin{array}{r}
p>2 \frac{4 d+3}{4 d-3} \quad \text { if } d \equiv 0(\bmod 3) \\
p>\frac{2 d+1}{d-1} \text { if } d \equiv 1(\bmod 3) \\
p>\frac{4(d+1)}{2 d-1} \text { if } d \equiv 2(\bmod 3)
\end{array}
$$

In particular, for $d=3$, we obtain the condition $p>\frac{10}{3}$. Interestingly, it turns out that this is the optimal exponent (as we will explain in the next section).

Without assuming $A$ positive definite, it is well-known that the condition

$$
\begin{equation*}
p \geq \frac{2(d+1)}{d-1} \tag{5.24}
\end{equation*}
$$

may be optimal range of validity for the inequality (5.19), when $d$ is odd (cf. [B]).
It was shown also in $[\mathrm{B}]$ that for $d$ even, there is some $p(d)<\frac{2(d+1)}{d-1}$ such that

$$
\begin{equation*}
\left\|T_{\lambda} f\right\|_{L_{\mathrm{loc}}^{p}} \lesssim \lambda^{-\frac{d}{p}}\|F\|_{\infty} \tag{5.25}
\end{equation*}
$$

The following statement makes this more precise

Theorem 4. Consider the operator (5.1) with $\psi$ as in (5.2) and A non-degenerate. For d even, one has the inequality

$$
\begin{equation*}
\left\|T_{\lambda} f\right\|_{L_{\text {loc }}^{p}} \leq C_{p} \lambda^{-\frac{d}{p}}\|f\|_{\infty} \text { for } p>\frac{2(d+2)}{d} \tag{5.26}
\end{equation*}
$$

(the exponent $\frac{2(d+2)}{d}$ was already known to be optimal).
Proof. (sketch)
We consider the setting (5.11), (5.12). Define the integer

$$
k=\frac{d}{2}+1 .
$$

Thus the condition on the exponent $q$ in (5.8') becomes $q>\frac{2(d+2)}{d}$.
Following the procedure from $\S 2$, $\S 3$, we fix a large parameter $K$ and restrict $x$ to a $K$-ball $B_{K}=B(a, K)$. Subdividing the $y$-domain $\Omega$ in balls $\Omega_{\alpha}$ of size $\frac{1}{K}$ and considering the operators

$$
\left(T_{\alpha} f\right)(x)=\int_{\Omega_{\alpha}} e^{i \phi(x, y)} f(y) d y
$$

we consider the following two alternatives.

Case 1. On $B_{K}$, we may estimate

$$
\begin{equation*}
|T f|<C(K)\left|T_{\alpha_{i}} f\right| \tag{5.27}
\end{equation*}
$$

for some $\alpha_{1}, \ldots, \alpha_{k}$ such that (5.6) holds for $y^{(1)} \in \Omega_{\alpha_{1}}, \ldots, y^{(k)} \in \Omega_{\alpha_{k}}$ (with constant $c \sim \frac{1}{K}$ ).

Case 2. Failure of Case 1. This implies that on $B_{K}$

$$
\begin{equation*}
|T f| \lesssim\left|\sum_{\alpha \in A} T_{\alpha} f\right|+\max _{\alpha}\left|T_{\alpha} f\right| \tag{5.28}
\end{equation*}
$$

where $\bigcup_{\alpha \in A} \Omega_{\alpha}$ is contained in an $\sim \frac{1}{K}$-neighborhood of the $(k-2)$-manifold, obtained by requiring $Z(a, y)$ given by (5.7) to belong to some $(k-1)$-dim linear space.

In particular,

$$
\begin{equation*}
\# A \lesssim K^{k-2} \tag{5.29}
\end{equation*}
$$

In Case 1, write on $B_{K}$

$$
\begin{equation*}
|T f| \leq C(K) \sum_{\substack{\alpha_{1}, \ldots, \alpha_{k} \\(5.6) \text { holds }}}\left(\prod_{1}^{k}\left|T_{\alpha_{i}} f\right|\right)^{\frac{1}{k}} \tag{5.30}
\end{equation*}
$$

The collected contribution may then be estimated using the $k$-linear bound and gives the estimate

$$
\begin{equation*}
\ll C(K) \tag{5.31}
\end{equation*}
$$

In Case 2, we proceed more crudely than in $\S 3$ (note that lower dimensional restriction of the $y$-variable may lead to degenerate phase functions if the quadratic form $\langle A y, y\rangle$ is not assumed definite.)
¿From (5.28)

$$
\begin{aligned}
\left(\int_{B_{K}}|T f|^{q}\right)^{\frac{1}{q}} & \leq\left(\int_{B_{K}}\left|\sum_{\alpha \in A} T_{\alpha} f\right|^{q}\right)^{\frac{1}{q}}+\left(\sum_{\alpha}\left|T_{\alpha} f\right|^{q}\right)^{\frac{1}{q}} \\
& =(5.32)+(5.33)
\end{aligned}
$$

Estimate

$$
\begin{aligned}
(5.32)^{q} & \leq\left[\int_{B_{K}}\left|\sum_{\alpha \in A} T_{\alpha} f\right|^{2}\right]\left[\sum_{\alpha \in A}\left|T_{\alpha} f\right|\right]^{q-2} \\
& \sim\left[\sum_{\alpha \in A}\left|T_{\alpha} f\right|^{2}\right]\left[\sum_{\alpha \in A}\left|T_{\alpha} f\right|\right]^{q-2} \quad \text { (using simple orthogonality) } \\
& <|A|^{1-\frac{2}{q}+(q-2)\left(1-\frac{1}{q}\right)} \sum_{\alpha}\left|T_{\alpha} f\right|^{q} .
\end{aligned}
$$

Recalling (5.29)

$$
\begin{equation*}
(5.32) \leq K^{(k-2)\left(1-\frac{2}{q}\right)}\left(\sum_{\alpha} \int_{B_{K}}\left|T_{\alpha} f\right|^{q}\right)^{1 / q} \tag{5.34}
\end{equation*}
$$

(that also captures (5.33)).
Thus the collected contribution over the $B_{K}$ is bounded by

$$
\begin{align*}
& K^{(k-2)\left(1-\frac{2}{q}\right)}\left(\sum_{\alpha}\left\|T_{\alpha} f\right\|_{q}^{q}\right)^{\frac{1}{q}} \\
& \leq K^{(k-2)\left(1-\frac{2}{q}\right)+\frac{d-1}{q}} \max _{\alpha}\left\|T_{\alpha} f\right\|_{q} \tag{5.35}
\end{align*}
$$

Rescaling gives the estimate

$$
\begin{equation*}
<K^{(k-2)\left(1-\frac{2}{q}\right)+\frac{d-1}{q}-(d-1)+\frac{d+1}{q}} Q_{\frac{R_{1}}{K}, \frac{R}{K^{2}}}^{(q)}=K^{\frac{d+2}{q}-\frac{d}{2}} Q \tag{5.36}
\end{equation*}
$$

(denoting $Q_{R_{1}, R}^{(p)}$ a bound on $T: L^{\infty} \rightarrow L_{\left|x^{\prime}\right|<R_{1},\left|x_{d}\right|<R}^{p}$ given by (5.11)).
Since $q>\frac{2(d+2)}{d}$, this concludes the argument.

## §6. Some Examples

We present in this section an example for $n=3$ that will illustrate the optimality of the exponent $\frac{10}{3}$ in Theorem 3. It will also explain the differences between the elliptic and hyperbolic cases.

Consider the following phase function

$$
\begin{equation*}
\phi(x, y)=-x_{1} y_{1}-x_{2} y_{2}+\frac{1}{2} x_{3} y_{1}^{2}+x_{3}^{2} y_{1} y_{2}+\frac{1}{2}\left(x_{3}+x_{3}^{3}\right) y_{2}^{2} . \tag{6.1}
\end{equation*}
$$

First analyze the $[\mathrm{BCT}]$ transversality condition. Thus

$$
\begin{gathered}
\nabla_{x} \phi=\left(-y_{1},-y_{2}, \frac{1}{2}\left(y_{1}^{2}+y_{2}^{2}\right)+2 x_{3} y_{1} y_{2}+\frac{3}{2} x_{3}^{2} y_{2}^{2}\right) \\
\left\{\begin{array}{l}
\partial_{y_{1}} \nabla_{x} \phi=\left(-1,0, y_{1}+2 x_{3} y_{2}\right) \\
\partial_{y_{2}} \nabla_{x} \phi=\left(0,-1, y_{2}+2 x_{3} y_{1}+3 x_{3}^{2} y_{2}\right)
\end{array}\right. \\
Z(\Phi)(y, x)=\partial_{y_{1}} \nabla_{x} \phi \wedge \partial_{y_{2}} \nabla_{x} \phi=\left(y_{1}+2 x_{3} y_{2}, y_{2}+2 x_{3} y_{1}+3 x_{3}^{2} y_{2}, 1\right) \\
=\left(A\binom{y_{1}}{y_{2}}, 1\right)
\end{gathered}
$$

where $A=A_{x}=\left(\begin{array}{cc}1 & 2 x_{3} \\ 2 x_{3} & 1+3 x_{3}^{2}\end{array}\right)$ is a perturbation of identity.
Concerning condition (40) in [BCT], if one fixes $x$ and restrict $y=\left(y_{1}, y_{2}\right)$ to noncollinear discs $U_{1}, U_{2}, U_{3} \subset \mathbb{R}^{2}$, clearly

$$
\operatorname{det}\left(Z(\phi)\left(y^{(1)}, x\right), Z(\phi)\left(y^{(2)}, x\right), Z(\phi)\left(y^{(3)}, x\right)\right) \neq 0
$$

for $y^{(i)} \subset V_{i}$.

Next, consider the Kakeya type sets associated with (6.1).

$$
\left\{\begin{array}{l}
\partial_{y_{1}} \phi=-x_{1}+x_{3} y_{1}+x_{3}^{2} y_{2}  \tag{6.2}\\
\partial_{y_{2}} \phi=-x_{2}+x_{3}^{2} y_{1}+\left(x_{3}+x_{3}^{3}\right) y_{2}
\end{array}\right.
$$

and

$$
\Gamma_{y} \text { is parametrized by }\left\{\begin{array}{l}
x_{1}=y_{1} x_{3}+y_{2} x_{3}^{2}  \tag{6.3}\\
x_{2}=y_{1} x_{3}^{2}+y_{2}\left(x_{3}+x_{3}^{3}\right) .
\end{array}\right.
$$

If we shift $\Gamma_{y}$ by $\left(y_{2}, 0,0\right)$, the tubes

$$
\left\{\begin{array}{l}
x_{1}=y_{1} x_{3}+y_{2} x_{3}^{2}+y_{2}  \tag{6.4}\\
x_{2}=y_{1} x_{3}^{2}+y_{2}\left(x_{3}+x_{3}^{3}\right)
\end{array}\right.
$$

are contained in the surface

$$
S: x_{1} x_{3}=x_{2}
$$

Thus one gets again 2D-compression, similar to the hyperbolic example

$$
\begin{equation*}
\psi(x, y)=-x_{1} y_{1}-x_{2} y_{2}+2 x_{3} y_{1} y_{2}+x_{3}^{2} y_{2}^{2} \tag{6.5}
\end{equation*}
$$

See also [Wi].

We try to exploit this compression as well as possible to make the oscillatory integral

$$
\begin{equation*}
\int e^{i \lambda \phi(x, y)} f(y) d y \tag{6.6}
\end{equation*}
$$

(with an appropriate $f$ ) large.
At this stage, there seems to be quite a difference between (6.1) and (6.5). For (6.5), just take

$$
\begin{equation*}
f(y)=e^{i y_{1}^{2}} \tag{6.7}
\end{equation*}
$$

Then

$$
\begin{equation*}
\int e^{i \lambda \psi(x, y)} f(y) d y=\int_{\mathrm{loc}} e^{i \lambda\left[\left(y_{1}+x_{3} y_{2}\right)^{2}-\left(x_{1} y_{1}+x_{2} y_{2}\right)\right]} d y \tag{6.8}
\end{equation*}
$$

and restricting $x$ to a $\frac{1}{\lambda}$-neighborhood of $S$

$$
(6.8) \approx \int_{\mathrm{loc}} e^{i \lambda\left[\left(y_{1}+x_{3} y_{2}\right)^{2}-x_{1}\left(y_{1}+x_{3} y_{2}\right)\right]} d y
$$

Setting $u=y_{1}+x_{3} y_{2}$, stationary phase implies

$$
|(6.8)| \sim \frac{1}{\sqrt{\lambda}}
$$

and hence

$$
\|(6.8)\|_{L_{x}^{q}} \sim \frac{1}{\sqrt{\lambda}}\left(\frac{1}{\lambda}\right)^{\frac{1}{q}} \lesssim\left(\frac{1}{\lambda}\right)^{\frac{3}{q}} \text { for } q \geq 4
$$

In the elliptic case, this type of construction seems impossible.
But one can make the following one, which will explain where the condition $q \geq \frac{10}{3}$ comes from.

Instead of (6.7), take in (6.6)

$$
\begin{equation*}
f(y)=\sum_{s<\sqrt{\lambda}} \sigma_{s} 1_{\left[\frac{s}{\sqrt{\lambda}}, \frac{s+c}{\sqrt{\lambda}}\right]}\left(y_{2}\right) e^{i \lambda \frac{s}{\sqrt{\lambda}} y_{1}} \tag{6.9}
\end{equation*}
$$

where $\sigma_{s}= \pm 1$ and $c>0$ is a small constant.
Hence

$$
\begin{equation*}
(6.6)=\sum_{s<\sqrt{\lambda}} \sigma_{s}\left\{\int_{\frac{s}{\sqrt{\lambda}}<y_{2}<\frac{s+c}{\sqrt{\lambda}}} e^{i \lambda\left[\phi(x, y)+\frac{s}{\sqrt{\lambda}} y_{1}\right]} d y\right\} . \tag{6.10}
\end{equation*}
$$

Denoting $R$ the region

$$
\begin{equation*}
R=\left[x_{3} \sim 1 \text { and }\left|x_{2}-x_{1} x_{3}\right|=o\left(\frac{1}{\sqrt{\lambda}}\right)\right] \tag{6.11}
\end{equation*}
$$

write

$$
\begin{equation*}
\int_{\text {loc }}|(6.6)|^{q} d x \geq \int_{R}|(6.10)|^{q} d x \tag{6.12}
\end{equation*}
$$

Averaging the right side of (6.12) over signs $\sigma_{s}= \pm 1$, we obtain clearly

$$
\begin{equation*}
\int_{R}\left\{\sum_{s<\sqrt{\lambda}}\left|\int_{\frac{s}{\sqrt{\lambda}}<y_{2}<\frac{s+c}{\sqrt{\lambda}}} e^{i \lambda\left[\phi(x, y)+\frac{s}{\sqrt{\lambda}} y_{1}\right]} d y\right|^{2}\right\}^{\frac{q}{2}} d x \tag{6.13}
\end{equation*}
$$

Since

$$
\phi(x, y)=\frac{1}{2} x_{3}\left[\left(y_{1}+x_{3} y_{2}-\frac{x_{1}}{x_{3}}\right)^{2}+\left(y_{2}+\frac{x_{1} x_{3}-x_{2}}{x_{3}}\right)^{2}\right]-\frac{1}{2}\left[\frac{x_{1}^{2}}{x_{3}}+\frac{\left(x_{1} x_{3}-x_{2}\right)^{2}}{x_{3}}\right]
$$

we have
$\phi(x, y)+\frac{s}{\sqrt{\lambda}} y_{1}=\frac{1}{2} x_{3}\left[\left(y_{1}+x_{3} y_{2}-\frac{x_{1}}{x_{3}}+\frac{s}{\sqrt{\lambda}} \frac{1}{x_{3}}\right)^{2}+\left(y_{2}-\frac{s}{\sqrt{\lambda}}+\frac{x_{1} x_{3}-x_{2}}{x_{3}}\right)^{2}\right]+\eta(x, s)$
Therefore, from definition of $R$

$$
\begin{equation*}
(6.13) \sim \int_{R}\left\{\sum_{s<\sqrt{\lambda}}\left|\int_{\frac{s}{\sqrt{\lambda}}<y_{2}<\frac{s+c}{\sqrt{\lambda}}} e^{i \frac{\lambda}{2} x_{3}\left(y_{1}+x_{3} y_{2}-\frac{x_{1}}{x_{3}}+\frac{s}{\sqrt{\lambda}} \frac{1}{x_{3}}\right)^{2}} d y\right|^{2}\right\}^{\frac{q}{2}} d x \tag{6.15}
\end{equation*}
$$

Stationary phase shows that for $\left|x_{1}\right|=o\left(x_{3}\right)$ and $s=o(\sqrt{\lambda})$, the inner integral in (6.15) is $O\left(\frac{1}{\lambda}\right)$.

Hence

$$
(6.13) \sim\left(\frac{1}{\lambda}\right)^{\frac{3 q}{4}}|R| \sim\left(\frac{1}{\lambda}\right)^{\frac{3 q+2}{4}}
$$

by (6.11), and

$$
\begin{equation*}
\|(6.6)\|_{q} \gtrsim\left(\frac{1}{\lambda}\right)^{\frac{3}{4}+\frac{1}{2 q}} \tag{6.16}
\end{equation*}
$$

Clearly (6.1) can only hold provided $q \geq \frac{10}{3}$.

## §7. Curved Kakeya Estimates

1. Let's begin by describing curved Kakeya problems in $\mathbb{R}^{n}$. We have a collection of tubes $T_{i}$. Each tube $T_{i}$ is the $\delta$-neighborhood of a curve $\Gamma_{i}$ in the unit ball in $\mathbb{R}^{n}$. The goal of the curved Kakeya problem is to assume some geometric information about the tubes $T_{i}$ and use it to prove estimates for the $L^{p}$ norms of $\sum_{i} \chi_{T_{i}}$ and/or for the volume of the union of tubes $\cup T_{i}$. Either kind of estimate is a way of measuring how much the tubes $T_{i}$ overlap.

Let $\delta>0$ be a small number.
We assume that each curve has $C^{2}$ norm $\lesssim 1$, and that each curve is an algebraic curve of degree $\lesssim 1$. We assume that each curve is contained in the unit ball. (I.e., $\Gamma_{i}$ is the restriction of an algebraic curve to the unit ball.) (i.e. $\Gamma_{i}$ is the restriction of an algebraic curve to the unit ball.)

We define $T_{i}$ to be the $\delta$-neighborhood of $\Gamma_{i}$. At each point $x \in T_{i}$, we can approximately define the tangent direction to the tube $T_{i}$ at $x$. Namely, pick any point $x^{\prime} \in \Gamma_{i} \cap B(x, \delta)$ and define $v_{i}(x)$ to be the unit tangent vector to $\Gamma_{i}$ at $x^{\prime}$. Since $\Gamma_{i}$ has $C^{2}$-norm $\lesssim 1$, choosing different points $x^{\prime}$ in $B(x, \delta)$ will lead to an ambiguity of size $\lesssim \delta$. So the function $v_{i}(x)$ is well-defined up to $O(\delta)$ on the tube $T_{i}$.
2. Assuming the $\Gamma_{i}$ algebraic, we prove the following slightly stronger version of the multilinear Kakeya estimate for curved tubes due to [BCT]. The next statement deals with the 3 -linear setting in $\mathbb{R}^{4}$ (for simplicity), but can be generalized to $k$-linear in $\mathbb{R}^{n}$.

## Theorem 6.

Suppose $\Gamma_{i}$ are algebraic curves restricted to the unit 4-ball with degree $\lesssim 1$ and $C^{2}$ norm $\lesssim 1$. Let $T_{i}$ denote the $\delta$-neighborhood of $\Gamma_{i}$. Define approximate tangent vectors $v_{i}(x)$ for $x \in T_{i}$ as above. Suppose that the number of tubes $T_{i}$ is $N$. Then the following estimate holds:

$$
\begin{equation*}
\int_{B^{4}}\left[\sum_{i=1}^{N} \chi_{T_{i}} \sum_{j=1}^{N} \chi_{T_{j}} \sum_{k=1}^{N} \chi_{T_{k}}\left|v_{i} \wedge v_{j} \wedge v_{k}\right|\right]^{1 / 2} \lesssim \delta^{4} N^{3 / 2} \tag{2.1}
\end{equation*}
$$

Choosing the curves $\Gamma_{i}$ in the subspace $\left[e_{1}, e_{2}, e_{3}\right]$ implies immediately the same statement in $\mathbb{R}^{3}$ with $\delta^{4}$ replaced by $\delta^{3}$ in (2.1).

Since we may repeat tubes $T_{i}$, we obtain also the weighted version from Theorem 6 .

The proof of the multilinear estimate follows the Dvir polynomial method, introduced for problems over finite fields in [D]. The polynomial method was applied to multilinear Kakeya problems in $\mathbb{R}^{n}$ in [G], and we will use results from there.

We will build an algebraic hypersurface $Z$ of controlled degree which is concentrated where the tubes $T_{i}$ overlap heavily, and we will study the intersections between $Z$ and the curves $\Gamma_{i}$.

Recall the definition of directed volume $V_{S}(v):=\int_{S}|v \cdot N| d v o l_{S}$, where $N$ denotes the normal vector to $S$. We need a curved version of the cylinder estimate, Lemma 2.1 in [G].

Lemma 2.2. If $Z$ is an algebraic surface in $\mathbb{R}^{4}$ of degree $D$, and if $\Gamma_{i}$ is a curve of degree $d$, and if $Q_{\alpha}$ are disjoint cubes of side length $\sim \delta$ which cover $T_{i}$, and if $x_{\alpha}$ is the center point of $Q_{\alpha}$, then the following inequality holds:

$$
\begin{equation*}
\sum_{\alpha} \delta^{-3} V_{Z \cap Q_{\alpha}}\left(v_{i}\left(x_{\alpha}\right)\right) \lesssim d D \tag{2.3}
\end{equation*}
$$

Proof. The idea of the proof is to interpret $\delta^{-3} V_{Z \cap Q_{\alpha}}\left(v_{i}\left(x_{\alpha}\right)\right)$ in a nice way: this quantity is roughly the average number of intersections of $Z \cap Q_{\alpha}$ with a translation of $\Gamma_{i}$ by a random vector $v$ of length $\lesssim \delta$. The total number of intersections of $Z$ with (almost every) translate of $\Gamma_{I}$ is at most $d D$ by Bezout's theorem.

The errors caused by $v_{i}(x)$ varying by $\sim \delta$ as $x$ varies in $Q_{\alpha}$ contribute about $\delta D$ per cube and so at most $D$ to the final answer.

In the paper [G], tubes had thickness 1 . Our tubes have thickness $\delta$, so it's convenient to re-normalize certain quantities. If $Q \subset \mathbb{R}^{4}$ is a cube of side length $\delta$, then

$$
\begin{equation*}
V_{Z \cap Q}^{\mathrm{ren}}(v):=\delta^{-3} V_{Z \cap Q}(v) \tag{2.4}
\end{equation*}
$$

We recall the notion of 'visibility' that plays a crucial role in [G].
The visibility of $Z \cap Q$ measures the directed volume of $Z \cap Q$ in various directions, and if there is even one direction where $Z \cap Q$ has low directed volume, the visibility goes down a lot. The renormalized visibility has the following definition.

$$
\begin{equation*}
\operatorname{Vis}^{\mathrm{ren}}[Z \cap Q]:=\operatorname{Vol}\left(\left\{v \text { such that }|v| \leq 1 \text { and } V_{Z \cap Q}^{\mathrm{ren}}(v) \leq 1\right\}\right)^{-1} \tag{2.5}
\end{equation*}
$$

As in [G], one needs to introduce modified versions $\bar{V} i s$ and $\bar{V}$ of $V i s$ and $V$, obtained by a suitable averaging over $Z$. They have all good properties of the originals and moreover depend continuously on $Z$. See [G] for details.

Next, we state a key result from [G] (see $\S 5, \mathrm{p} 14$ ), in our renormalized setting.

Lemma 2.6. Consider the standard $\delta$-lattice in $\mathbb{R}^{4}$. Let $M$ be a function from the set of 4-cubes $Q$ in this lattice to $\mathbb{Z}_{+} \cup\{o\}$. Then there is an algebraic hypersurface of degree $D$ such that

$$
\begin{equation*}
\bar{V} i s^{\mathrm{ren}}[Z \cap Q] \geq M(Q) \text { for all } Q \tag{2.7}
\end{equation*}
$$

and

$$
\begin{equation*}
D<C\left[\sum_{Q} M(Q)\right]^{1 / 4} \tag{2.8}
\end{equation*}
$$

Let $Q_{\alpha}$ be a set of $\delta$-cubes that cover the unit 4 -ball. For each cube, define

$$
F\left(Q_{\alpha}\right):=\sum_{T_{i}, T_{j}, \text { and } T_{k} \text { intersect } Q_{\alpha}}\left|v_{i} \wedge v_{j} \wedge v_{k}\right| .
$$

Here $v_{i}, v_{j}, v_{k}$ are evaluated at $x_{\alpha}$, the center of $Q_{\alpha}$.
Lemma 2.9. The sum $\sum_{\alpha} \delta^{4} F\left(Q_{\alpha}\right)^{1 / 2} \lesssim d^{3 / 2} \delta^{4} N^{3 / 2}$.
The sum on the left-hand side is very close to the integral over the 4 -ball we want to estimate:

$$
\begin{equation*}
\int_{B^{4}}\left[\sum_{i=1}^{N} \chi_{T_{i}} \sum_{j=1}^{N} \chi_{T_{j}} \sum_{k=1}^{N} \chi_{T_{k}}\left|v_{i} \wedge v_{j} \wedge v_{k}\right|\right]^{1 / 2} \sim \sum_{\alpha} \delta^{4} F\left(Q_{\alpha}\right)^{1 / 2} \tag{2.10}
\end{equation*}
$$

We compare our discrete sum and the integral below. First we prove the lemma.
Proof. We construct a surface of degree $\lesssim D$ (for a large $D$ ) so that for all $\alpha$

$$
\begin{equation*}
\bar{V} i s^{\mathrm{ren}}\left[Z \cap Q_{\alpha}\right] \geq D^{4} F\left(Q_{\alpha}\right)^{1 / 2}\left[\sum_{\alpha} F\left(Q_{\alpha}\right)^{1 / 2}\right]^{-1} \tag{2.11}
\end{equation*}
$$

(We can use any $D$, but we need $D$ big enough so that the RHS is at least 1 for all $\alpha$.)
The existence of $Z$ follows indeed from Lemma 2.6, taking for $M\left(Q_{\alpha}\right)$ the RHS of (2.11).

We show that

$$
\begin{equation*}
D\left[\sum_{\alpha} F\left(Q_{\alpha}\right)^{1 / 2}\right]^{2 / 3} \lesssim d D N \tag{2.12}
\end{equation*}
$$

which is equivalent with (2.9). Write using (2.11).

$$
D\left[\sum F\left(Q_{\alpha}\right)^{1 / 2}\right]^{2 / 3} \lesssim \sum F\left(Q_{\alpha}\right)^{1 / 3} \bar{V} i s^{r e n}\left(Q_{\alpha}\right)^{1 / 3} D^{-1 / 3} \lesssim
$$

$$
\begin{equation*}
=\sum_{\alpha}\left[D^{-1} \bar{V} i s^{r e n}\left(Q_{\alpha}\right) \sum_{T_{i}, T_{j}, T_{k} \operatorname{meet} Q_{\alpha}}\left|v_{i} \wedge v_{j} \wedge v_{k}\left(x_{\alpha}\right)\right|\right]^{1 / 3} \tag{2.13}
\end{equation*}
$$

Linear algebra lemma. For any three vectors $v_{i}, v_{j}, v_{k}$, the following inequality holds

$$
\begin{equation*}
\overline{V i s}^{r e n}\left[Z \cap Q_{\alpha}\right]\left|v_{i} \wedge v_{j} \wedge v_{k}\right| \lesssim D \bar{V}_{Z \cap Q_{\alpha}}^{r e n}\left(v_{i}\right) \bar{V}_{Z \cap Q_{\alpha}}^{r e n}\left(v_{j}\right) \bar{V}_{Z \cap Q_{\alpha}}^{r e n}\left(v_{k}\right) \tag{2.14}
\end{equation*}
$$

Proof. We abbreviate $\bar{V}_{Z \cap Q_{\alpha}}^{r e n}$ by $\bar{V}$ and $\overline{V i s}^{\text {ren }}$ by $\overline{V i s}$.
We use the following facts. The function $\bar{V}$ maps $\mathbb{R}^{4}$ to $\mathbb{R}$. It is non-negative. It scales by the formula $\bar{V}(\lambda v)=\lambda \bar{V}(v)$ for any $\lambda>0$ and $v \in \mathbb{R}^{4}$. It is convex. And finally $|v| \leq \bar{V}(v) \lesssim D|v|$ (where the lower bound is ensured by enlarging $Z$ with $\sim \frac{1}{\delta}$ hyperplanes.)

Now $\overline{V i s}$ is defined as $\operatorname{Vol}\left\{v \in B^{4} \mid \bar{V}(v) \leq 1\right\}^{-1}$. So we have to prove that

$$
\begin{equation*}
\operatorname{Vol}\left\{v \in B^{4} \mid \bar{V}(v) \leq 1\right\} \gtrsim\left|v_{i} \wedge v_{j} \wedge v_{k}\right| D^{-1} \bar{V}\left(v_{i}\right)^{-1} \bar{V}\left(v_{j}\right)^{-1} \bar{V}\left(v_{k}\right)^{-1} \tag{2.15}
\end{equation*}
$$

Let $v_{0}$ be a unit vector perpendicular to the plane spanned by $v_{i}, v_{j}, v_{k}$. Let $e_{0}=$ $v_{0} / D$. Then $\bar{V}\left(e_{0}\right) \leq 1$. Also, let $e_{i}:=v_{i} / \bar{V}\left(v_{i}\right)$, so that $\bar{V}\left(e_{i}\right)=1$. Define $e_{j}, e_{k}$ similarly. Since $\bar{V}(v) \geq|v|$, it follows that $\left|e_{i}\right| \leq 1$. Since $\bar{V}$ is convex, $\bar{V} \leq 1$ on the convex hull of the eight points $\pm e_{0}, \pm e_{i}, \pm e_{j}, \pm e_{k}$. This convex hull lies in $B^{4}$. Its volume is approximately $\left|e_{0} \wedge e_{i} \wedge e_{j} \wedge e_{k}\right|$. Since $e_{0}$ is perpendicular to the other vectors, this wedge is equal to $\left|e_{0}\right|\left|e_{i} \wedge e_{j} \wedge e_{k}\right|=D^{-1}\left|v_{i} \wedge v_{j} \wedge v_{k}\right| \bar{V}\left(v_{i}\right)^{-1} \bar{V}\left(v_{j}\right)^{-1} \bar{V}\left(v_{k}\right)^{-1}$. proving (2.15).
¿From (2.14)

$$
\begin{align*}
& \lesssim \sum_{\alpha}\left[\sum_{T_{i}, T_{j}, T_{k} m e e t Q_{\alpha}} \bar{V}_{Z \cap Q_{\alpha}}^{\text {ren }}\left(v_{i}\right) \bar{V}_{Z \cap Q_{\alpha}}^{r e n}\left(v_{j}\right) \bar{V}_{Z \cap Q_{\alpha}}^{\text {ren }}\left(v_{k}\right)\right]^{1 / 3}=  \tag{2.13}\\
& =\sum_{\alpha} \sum_{T_{i} \text { meets } Q_{\alpha}} \bar{V}_{Z \cap Q_{\alpha}}^{\text {ren }}\left(v_{i}\right)=\sum_{i=1}^{N} \sum_{Q_{\alpha} \text { meets } T_{i}} \bar{V}_{Z \cap Q_{\alpha}}^{\text {ren }}\left(v_{i}\right) .
\end{align*}
$$

By the cylinder estimate, the last line is bounded $\lesssim N d D$ as required.
This proves Lemma 2.9.

Finally, we return to the integral and show that the error in our discrete approximation is not too big:

$$
\begin{array}{r}
\int_{B^{4}}\left[\sum_{i=1}^{N} \chi_{T_{i}} \sum_{j=1}^{N} \chi_{T_{j}} \sum_{k=1}^{N} \chi_{T_{k}}\left|v_{i}(x) \wedge v_{j}(x) \wedge v_{k}(x)\right|\right]^{1 / 2} d x= \\
=\sum_{\alpha} \int_{Q_{\alpha}}\left[\sum_{i=1}^{N} \chi_{T_{i}} \sum_{j=1}^{N} \chi_{T_{j}} \sum_{k=1}^{N} \chi_{T_{k}}\left|v_{i} \wedge v_{j} \wedge v_{k}\right|\right]^{1 / 2} d x \\
\leq \sum_{\alpha} \int_{Q_{\alpha}}\left[\sum_{T_{i}, T_{j}, T_{k} \text { meet } Q_{\alpha}}\left|v_{i}(x) \wedge v_{j}(x) \wedge v_{k}(x)\right|\right]^{1 / 2} d x \\
\leq \sum_{\alpha} \int_{Q_{\alpha}}\left[\sum_{T_{i}, T_{j}, T_{k}} \operatorname{meet} Q_{\alpha}\right.  \tag{2.16}\\
\left.\left|v_{i}\left(x_{\alpha}\right) \wedge v_{j}\left(x_{\alpha}\right) \wedge v_{k}\left(x_{\alpha}\right)\right|\right]^{1 / 2}+\text { Error }
\end{array}
$$

where

$$
\begin{gather*}
\text { Error } \lesssim \sum_{\alpha} \int_{Q_{\alpha}}\left[\sum_{i, j, k} \chi_{\tilde{T}_{i}} \chi_{\tilde{T}_{j}} \chi_{\tilde{T}_{k}}\left|v_{i} \wedge v_{j}\right| \delta\right]^{1 / 2} \lesssim \\
\lesssim \delta^{1 / 2}\left(\int_{B^{4}} \sum_{i, j} \chi_{T_{i}} \chi_{T_{j}}\left|v_{i} \wedge v_{j}\right| d x\right)^{1 / 2}\left(\int_{B^{4}} \sum \chi_{T_{k}}\right)^{1 / 2} \sim \\
N^{1 / 2} \delta^{2}\left(\int_{B^{4}} \sum_{i, j} \chi_{T_{i}} \chi_{T_{j}}\left|v_{i} \wedge v_{j}\right| d x\right)^{1 / 2} . \tag{2.17}
\end{gather*}
$$

By Lemma 2.9, the first term in (2.16) is bounded by C. $\delta^{4} d^{3 / 2} N^{3 / 2}$.
In (2.17) we encounter a 2-linear version of our original 3-linear integral.
This can be estimated by a much easier argument in the same spirit.
We show that

$$
\begin{equation*}
\int_{B^{4}} \mathcal{X}_{T_{i}} \mathcal{X}_{T_{j}}\left|v_{i} \wedge v_{j}\right|<C \delta^{4} d^{2} \tag{2.18}
\end{equation*}
$$

Hence $(2.17)<C N^{3 / 2} \delta^{4} d$ and this completes the proof of Theorem 8.
It remains to justify (2.18). Thus

Lemma 2.19. Suppose that $\Gamma_{1}$ and $\Gamma_{2}$ are degree d algebraic curves in $B^{4}$ and $C^{2}$ curves of norm $\lesssim 1$, and $T_{i}$ are $\delta$ tubes around $\Gamma_{i}$.

Then

$$
\begin{equation*}
\int_{B^{4}} \chi_{T_{1}} \chi_{T_{2}}\left|v_{1}(x) \wedge v_{2}(x)\right| d x \lesssim d^{2} \delta^{4} \tag{2.19}
\end{equation*}
$$

Proof. (sketch) (This is an easier version of the 3-linear estimate (2.1)).
Cut the unit ball into $\delta$ cubes $Q_{\alpha}$.
Pick $D$ a large degree. Choose $Z$ a degree $D$ hypersurface so that $\bar{V}_{Z \cap Q_{\alpha}}^{r e n}(x) \geq|x|$ and

$$
\begin{equation*}
\overline{V i s}^{r e n}\left[Z \cap Q_{\alpha}\right] \gtrsim D^{4}\left|v_{1} \wedge v_{2}\left(x_{\alpha}\right)\right|\left[\sum_{\alpha}\left|v_{1} \wedge v_{2}\left(x_{\alpha}\right)\right|\right]^{-1} \tag{2.20}
\end{equation*}
$$

Now our integral is roughly

$$
\begin{equation*}
\delta^{4} \sum_{Q_{\alpha} \subset T_{1} \cap T_{2}}\left|v_{1} \wedge v_{2}\left(x_{\alpha}\right)\right| . \tag{2.21}
\end{equation*}
$$

The error in this approximation is $\delta \operatorname{Vol}\left(T_{1} \cap T_{2}\right) \lesssim d \delta^{4}$ which is not larger than the main term.

It suffices to prove

$$
\begin{equation*}
\sum_{\alpha}\left|v_{1} \wedge v_{2}\right| \lesssim d^{2} \tag{2.22}
\end{equation*}
$$

Manipulating (2.20), we see that

$$
\sum_{\alpha}\left|v_{1} \wedge v_{2}\right| \lesssim D^{-4}\left[\sum_{\alpha} \overline{\operatorname{Vis}}^{r e n}\left[Z \cap Q_{\alpha}\right]^{1 / 2}\left|v_{1} \wedge v_{2}\right|^{1 / 2}\right]^{2} \leq
$$

(by a linear algebra lemma like the one above)

$$
\begin{aligned}
& \lesssim D^{-2}\left[\sum \bar{V}^{r e n}\left(v_{1}\right)^{1 / 2} \bar{V}^{r e n}\left(v_{2}\right)^{1 / 2}\right]^{2} \leq \\
& \leq D^{-2}\left(\sum_{\alpha} \bar{V}^{r e n}\left(v_{1}\right)\right)\left(\sum_{\alpha} \bar{V}^{r e n}\left(v_{2}\right)\right) .
\end{aligned}
$$

Now the first term in parentheses is essentially the average number of intersections between $Z$ and $\Gamma_{i}$ after translating $\Gamma_{i}$ by a random vector of length $\lesssim \delta$, and so it has
size at most $d D$ by Bezout's theorem. (Compare the cylinder estimate above.) The same applies to the second term. So the whole expression is bounded $\lesssim d^{2}$.

## 3. Application to curved Kakeya sets

Again we restrict ourselves to $n=4$ but the result generalize to even dimension $n$ (the exponent $\frac{3}{2}$ in Theorem 7 below is then replaced by $1+\frac{2}{n}$.)

Let the curves $\left\{\Gamma_{i}\right\}$ be as specified in the beginning of $\S 7$. We also make an 'angle assumption' for pairs of curves, as follows.

The index set $\{i\}$ is given a geometric structure. For each curve $i$, we associate a point $y_{i}$ in $B^{n-1}(1)$. We assume that the points $y_{i}$ are $\delta$-separated. We make the following crucial geometric assumption. If a point $x$ lies in $T_{i}$ and in $T_{j}$, then the angle between $v_{i}(x)$ and $v_{j}(x)$ is $\gtrsim\left|y_{i}-y_{j}\right|$. This assumption prevents too many near-tangencies in the overlaps of the tubes.

Theorem 7. Under the hypotheses above, for all $p>3 / 2$,

$$
\begin{equation*}
\left\|\sum_{i} \chi_{T_{i}}\right\|_{p} \lesssim \delta^{-3+4 / p} \tag{3.1}
\end{equation*}
$$

Hence, any curved Kakeya set in $\mathbb{R}^{4}$ (defined from algebraic curves of controlled degree and controlled $C^{2}$ norm) has Minkowski dimension at least 3.(*)

Examples (cf. [B2]) show that the statement in Theorem 7 is best possible.
The proof of Theorem 7 uses an inductive argument, where we assume that a good estimate holds for a partial sums $\sum_{y_{i} \in \text { small ball }} \chi_{T_{i}}$ and then we prove that a good estimate holds for a partial sum on $y_{i}$ in a larger ball.

Theorem 7'. Let $T_{i}$ obey the hypotheses from Theorem 7. Suppose that $p>3 / 2$. Suppose that $\rho$ is a scale in the range $\delta \leq \rho \leq 1$. Let $B_{\rho}$ denote any ball of radius $\rho$ in $B^{3}(1)$. Then the following estimate holds.

$$
\begin{equation*}
\left\|\sum_{y_{i} \in B_{\rho}} \chi_{T_{i}}\right\|_{p} \lesssim \delta^{-3+\frac{4}{p}} \rho^{3-\frac{1}{p}} . \tag{3.2}
\end{equation*}
$$

When $\rho=1$, Theorem $7^{\prime}$ implies Theorem 7. When $\rho=\delta$, Theorem $7^{\prime}$ is trivial. We will prove Theorem $7^{\prime}$ by induction on $\rho$. So we are allowed to assume that Theorem $7^{\prime}$ holds for all $\bar{\rho}<\rho / 2$. In other words, we know

$$
\begin{equation*}
\left\|\sum_{y_{i} \in B_{\bar{\rho}}} \chi_{T_{i}}\right\|_{p} \leq \alpha \delta^{-3+4 / p} \bar{\rho}^{3-1 / p} . \tag{3.3}
\end{equation*}
$$

[^0]In this equation $\alpha$ is a large constant that we will choose later. Assuming (3.3), we will prove that the same estimate holds for balls of radius $\rho$, with the same constant $\alpha$. In other words, we will prove

$$
\begin{equation*}
\left\|\sum_{y_{i} \in B_{\rho}} \chi_{T_{i}}\right\|_{p} \leq \alpha \delta^{-3+4 / p} \rho^{3-1 / p} . \tag{3.4}
\end{equation*}
$$

Once we have proven (3.4), the inductive argument shows that Theorem $7^{\prime}$ holds for all $\rho$, and we are done. The idea of the proof is as follows. We cover $B_{\rho}$ with smaller balls, and then write $\sum_{y_{i} \in B_{\rho}}$ as a sum of contributions from the smaller balls. To bound the $L^{p}$ norm of this sum, we use a combination of two tools. First, (3.3) bounds the $L^{p}$ norms of the contributions from each smaller ball. By itself, this is not enough, but it shows that for (3.4) to fail, we need to have points where many smaller balls are contributing. The size of this effect is controlled by the multilinear estimate.

Let $K$ be a large constant to be determined later. We cover $B_{\rho}$ by $K^{3}$ smaller balls, each of radius at most $10 \rho / K$. We call each of these smaller balls a "clump". Hence our set of tubes is divided into $\sim K^{3}$ clumps.

We divide $B^{4}$ into two regions, depending on how the tubes through $x$ are divided among the clumps. We call a point $x \in B^{4}$ "narrow" if there exist $<10^{4} K$ clumps which contain half of the tubes through the point $x$. We call $x$ "broad" if it is not narrow. Let $N \subset B^{4}$ be the set of narrow points, and $N^{c} \subset B^{4}$ the set of broad points.

Our inductive hypothesis directly controls $\left\|\sum_{y_{i} \in B_{\rho}} \chi_{T_{i}}\right\|_{L^{p}(N)}$.
Lemma 3.5. Let $p>3 / 2$. Assuming (3.3), and assuming that $K=K(p)$ is sufficiently large, the following estimate holds:

$$
\begin{equation*}
\int_{\text {Narrow }}\left[\sum_{y_{i} \in B_{\rho}} \chi_{T_{i}}\right]^{p} d x \leq(1 / 2) \alpha^{p} \delta^{4-3 p} \rho^{3 p-1} \tag{3.6}
\end{equation*}
$$

More explicitly, we say that $K$ is sufficiently large if $\left[2 \cdot 10^{7}\right]^{p} K^{-2 p+3}<1 / 2$. Notice that this condition depends only on $p$.

Proof. Fix $x \in$ Narrow. We divide the sum $\sum_{y_{i} \in B_{\rho}} \chi_{T_{i}}(x)$ into clumps:

$$
\begin{equation*}
\sum_{y_{i} \in B_{\rho}} \chi_{T_{i}}(x) \leq \sum_{j=1}^{K^{3}}\left[\sum_{y_{i} \in \operatorname{clump}(j)} \chi_{T_{i}}(x)\right] . \tag{3.7}
\end{equation*}
$$

Now since $x$ is narrow, the sum on the right-hand side is controlled by the sum from only $10^{4} \mathrm{~K}$ clumps. In other words, we can pick a set $C(x)$ of at most $10^{4} \mathrm{~K}$ clumps so that

$$
\begin{equation*}
(3.7) \leq 2 \sum_{j \in C(x)}\left[\sum_{y_{i} \in \operatorname{clump}(j)} \chi_{T_{i}}(x)\right] . \tag{3.8}
\end{equation*}
$$

Now by Holder's inequality, this last sum is dominated by

$$
(3.8) \leq 2\left[\sum_{j \in C(x)}\left(\sum_{y_{i} \in \operatorname{clump}(j)} \chi_{T_{i}}(x)\right)^{p}\right]^{1 / p}\left[10^{4} K\right]^{\frac{p-1}{p}} .
$$

Putting together the string of inequalities we just proved, we see that for each $x \in$ Narrow,

$$
\left[\sum_{y_{i} \in B_{\rho}} \chi_{T_{i}}(x)\right]^{p} \leq 2^{p}\left[10^{4} K\right]^{p-1} \sum_{j=1}^{K^{3}}\left(\sum_{y_{i} \in \operatorname{clump}(j)} \chi_{T_{i}}(x)\right)^{p} .
$$

Now integrating over the narrow set, we get

$$
\begin{equation*}
\int_{\text {Narrow }}\left[\sum_{y_{i} \in B_{\rho}} \chi_{T_{i}}(x)\right]^{p} d x \leq 2^{p}\left[10^{4} K\right]^{p-1} \sum_{j=1}^{K^{3}} \int_{B^{4}}\left(\sum_{y_{i} \in \operatorname{clump}(j)} \chi_{T_{i}}(x)\right)^{p} d x \tag{3.9}
\end{equation*}
$$

But by induction (3.3), the integral involving each smaller clump in (3.9) is controlled

$$
\int_{B^{4}}\left(\sum_{y_{i} \in \operatorname{clump}(j)} \chi_{T_{i}}(x)\right)^{p} d x \leq \alpha^{p} \delta^{4-3 p}(10 \rho / K)^{3 p-1}
$$

Plugging this estimate into (3.8), we get

$$
\begin{equation*}
\int_{\text {Narrow }}\left[\sum_{y_{i} \in B_{\rho}} \chi_{T_{i}}(x)\right]^{p} d x \leq 2^{p}\left[10^{4} K\right]^{p-1} K^{3} \alpha^{p} \delta^{4-3 p}(10 \rho / K)^{3 p-1} \tag{3.10}
\end{equation*}
$$

Grouping terms in the right-hand side, we get

$$
\leq\left[2 \cdot 10^{4} \cdot 10^{3}\right]^{p} K^{-2 p+3} \alpha^{p} \delta^{4-3 p} \rho^{3 p-1} .
$$

We choose $K=K(p)$ sufficiently large so that

$$
\left[2 \cdot 10^{7}\right]^{p} K^{-2 p+3}<1 / 2
$$

Since $p>3 / 2$, we can choose $K$ sufficiently large to make this inequality hold. This proves Lemma 3.5.

At this point we fix $K=K(p)$.
Next we have to control the contribution from the broad points in $B^{4}$. We do this using the multilinear estimate.

Lemma 3.11. Let Broad $\subset B^{4}$ denote the set of broad points.

$$
\begin{equation*}
\int_{\text {Broad }}\left|\sum_{y_{i} \in B_{\rho}} \chi_{T_{i}}\right|^{\frac{3}{2}} \leq C(K) \delta^{-1 / 2} \rho^{7 / 2} \tag{3.12}
\end{equation*}
$$

Proof. Let $x \in B^{4}$ be a broad point. The broadness of $x$ leads to the following estimate:

$$
\begin{equation*}
\left|\sum_{y_{i} \in B_{\rho}} \chi_{T_{i}}(x)\right|^{3} \leq \rho^{-2} C(K) \sum_{y_{i} \in B_{\rho}} \chi_{T_{i}}(x) \sum_{y_{j} \in B_{\rho}} \chi_{T_{j}}(x) \sum_{y_{k} \in B_{\rho}} \chi_{T_{k}}(x)\left|v_{i}(x) \wedge v_{j}(x) \wedge v_{k}(x)\right| . \tag{3.13}
\end{equation*}
$$

This holds because most triples of tubes through a broad point lie in clumps that fail to be coplanar, and so we have $\left|v_{i}(x) \wedge v_{j}(x) \wedge v_{k}(x)\right| \geq \rho^{2} / C(K)$.

Taking the square root of (3.13) and integrating, we get

$$
\begin{gather*}
\int_{\text {Broad }}\left|\sum_{y_{i} \in B_{\rho}} \chi_{T_{i}}\right|^{\frac{3}{2}} \leq \\
\leq C(K) \rho^{-1} \int_{B^{4}}\left[\sum_{y_{i} \in B_{\rho}} \chi_{T_{i}}(x) \sum_{y_{j} \in B_{\rho}} \chi_{T_{j}}(x) \sum_{y_{k} \in B_{\rho}} \chi_{T_{k}}(x)\left|v_{i}(x) \wedge v_{j}(x) \wedge v_{k}(x)\right|\right]^{1 / 2} d x . \tag{3.14}
\end{gather*}
$$

But the right-hand side is controlled by the Multilinear Estimate. The number of points $y_{i} \in B_{\rho}$ is $\leq 100[\rho / \delta]^{3}$. According to Theorem 6 , the right-hand side is bounded above by

$$
(3.14) \lesssim K \rho^{-1} \delta^{4}[\rho / \delta]^{9 / 2}=\delta^{-1 / 2} \rho^{7 / 2}
$$

proving Lemma 3.11.
The estimate in Lemma 3.11 controls the $L^{3 / 2}$ norm of $\sum \chi_{T_{i}}$ on the broad set. There is an obvious estimate for the $L^{\infty}$ norm, and by combining them we can estimate the $L^{p}$ norm for our choice of $p>3 / 2$.

We clearly have the $L^{\infty}$ bound

$$
\begin{equation*}
\sup _{x}\left|\sum_{y_{i} \in B_{\rho}} \chi_{T_{i}}\right| \lesssim \rho^{3} \delta^{-3} . \tag{3.15}
\end{equation*}
$$

Since our $p>3 / 2$, we see that

$$
\int_{\text {Broad }}\left|\sum_{y_{i} \in B_{\rho}} \chi_{T_{i}}\right|^{p} d x \lesssim\left[\rho^{3} \delta^{-3}\right]^{p-3 / 2} \int_{\text {Broad }}\left|\sum_{y_{i} \in B_{\rho}} \chi_{T_{i}}\right|^{3 / 2} d x
$$

Applying Lemma 3.11 to bound the last integral, we see that

$$
\begin{equation*}
\int_{\text {Broad }}\left|\sum_{y_{i} \in B_{\rho}} \chi_{T_{i}}\right|^{p} d x \leq C(K) \rho^{3 p-1} \delta^{4-3 p} \tag{3.16}
\end{equation*}
$$

Now we choose $\alpha$ large enough that $C(K) \leq(1 / 2) \alpha^{p}$. (So $\alpha$ depends on $K$ and $p$.) Now we know that

$$
\begin{equation*}
\int_{\text {Broad }}\left|\sum_{y_{i} \in B_{\rho}} \chi_{T_{i}}\right|^{p} d x \leq(1 / 2) \alpha^{p} \rho^{3 p-1} \delta^{4-3 p} \tag{3.17}
\end{equation*}
$$

and (3.6), (3.17) imply (3.4).
This concludes the proof of Theorem $7^{\prime}$ and hence Theorem 7.

## 4. Estimates for $C^{k}$ curves

We can prove estimates for $C^{k}$ curved Kakeya sets by approximating the $C^{k}$ curves using polynomials. This idea was suggested to us by Alex Nabutovsky. He referred us to Jackson's theorem in approximation theory and related results.

The results in this section look far from optimal, but we wanted to show that something can be done for non-algebraic curves as well with these methods.

Jackson type theorem. If $f:[0,1] \rightarrow \mathbb{R}$ has $C^{k}$ norm 1, then we can approximate $f$ by a degree d polynomial $P$ so that

$$
\begin{equation*}
|f(x)-P(x)| \lesssim d^{-k} \text { for all } x \in[0,1] . \tag{4.1}
\end{equation*}
$$

In particular, we may approximate a $C^{k}$ curve $\Gamma_{i}$ by a degree $d$ algebraic curve with the same $\delta$-tube and with $d \lesssim \delta^{-1 / k}$.
Remark. This algebraic curve will be just the graph of a degree $d$ polynomial. There are many more algebraic curves and so one may hope for a better estimate, but it would take some more sophisticated approximation theory.

Tracking the dependence on degree in Theorem 7, the following estimate is gotten.
Theorem $7^{\prime \prime}$. Under the hypotheses in section 3, for all $p>3 / 2$,

$$
\begin{equation*}
\left\|\sum_{i} \chi_{T_{i}}\right\|_{p} \lesssim d^{\frac{3}{2 p}} \delta^{-3+4 / p} \tag{4.2}
\end{equation*}
$$

Hence we get the following estimate for $C^{k}$ curves $\Gamma_{i}$ with $k \geq 2$ obeying the angle condition:

Theorem 8. Under the hypotheses above, for all $p>3 / 2$,

$$
\begin{equation*}
\left\|\sum_{i} \chi_{T_{i}}\right\|_{p} \lesssim_{k} \delta^{-3+\frac{4}{p}-\frac{3}{2 p k}} . \tag{4.3}
\end{equation*}
$$

In particular, for $C^{\infty}$ curves we have essentially the same estimate that we had for algebraic curves.

An immediate consequence of Theorem 8 is the following result on the Minkowski dimension of curved Kakeya sets.

Theorem 9. Any curved Kakeya set in $4 D$ associated to $C^{\infty}$-curves obeying the angle condition, has Minkowski dimension at least 3.

The method described in $\S 7$ can be generalized to higher dimension. In particular, for $n$ even, smooth curved Kakeya sets in $\mathbb{R}^{n}$ have Minkowski dimension at least $\frac{n}{2}+1$. This statement, which in some sense is the companion to Theorem 4 , is the sharp version of a phenomenon first observed in [B2]. Note that for $n$ odd, (algebraic) curved Kakeya sets may have Minkowski dimension $\frac{n+1}{2}$ (cf. [B2]).

## $\S$ 8. Further Comments

It is not quite clear at this point what is the exact potential of the method introduced in this paper (when the optimal result is not attained) and we have not tried to push the techniques to their limit. In particular, further improvements in Theorem 2 are not out of question and one could also explore if the more refined strategy used to obtain Theorem 2 in 3D has a higher dimensional counterpart (possibly improving upon Theorem 1).

Returning to inequality $\left(5.8^{\prime}\right)$ in $\S 5$, we present next an alternative proof for $n=3$ of the following statement (which suffices for the application to Theorem 3 when $n=3$ ).

Proposition 8.1. Under the transversality assumption (5.6), (5.7) from $\S 5$ one has the 3-linear estimate in $3 D$

$$
\begin{equation*}
\left\|\prod_{i=1}^{3}\left(T_{\lambda}^{(i)} f_{i}\right)\right\|_{L^{q / 3}}<\lambda^{-\frac{9}{q}} \prod_{i=1}^{3}\left\|f_{i}\right\|_{2} \text { for } q>\frac{10}{3} \tag{8.2}
\end{equation*}
$$

where the operators $T_{\lambda}^{(i)}$ are given by (5.1), (5.2) with positive definite quadratic form and the phase functions are assumed algebraic of bounded degree.

Proposition 8.1 is weaker then $\left(5.8^{\prime}\right)$ in $\S 5$, but may be obtained directly without the need for an $\varepsilon$-removal lemma; hence this argument may have some interest.

Returning to the argument in [BCT] (which is similar to the one in [B1]) there are basically two steps, that will be suitably modified.

1. The first step in the approach involves the 'intermediate scale' $|x|<\frac{1}{\sqrt{\lambda}}$. At this scale, as explained in (5.19)-(5.23) from $\S 5$, the problem may be linearized in $x$. This allows to derive a trilinear bound from the bilinear $2 \times 2 \rightarrow \frac{q}{2}$ estimate for $q>\frac{2(d+1)}{d}=\frac{10}{3}$ due to [T1] in the restriction theory rather than relying on a bootstrap. We point out that the linear result from [T1] for the paraboloid and, more generally, smooth hypersurfaces with positive definite second fundamental form, may fail without this last hypothesis (for instance for a hyperbolic paraboloid, cf. [V]), if no additional assumptions.
2. At the second stage of the argument, the issue is the 3-linear Kakeya estimate (in the curved case), which is Proposition 6.8 in [BCT]. Here another factor $\lambda^{\varepsilon}$ enters in their argument. However, Theorem 6 of the paper may be used, since it immediately implies (by lowering the dimension from $\mathbb{R}^{4}$ to $\mathbb{R}^{3}$ ).

Proposition 8.3. Denoting $\left\{\tau_{i}\right\} \delta$-neighborhoods of a family $\left\{\Gamma_{i}\right\}$ of smooth algebraic curves of degree $\lesssim 1$ in $B(0,1) \subset \mathbb{R}^{3}$ and $v_{i}$ the tangent vector at a given point $p \in \Gamma_{i}$, one has

$$
\int\left[\sum_{i, j, k} \lambda_{i} \mu_{j} \eta_{k} \mathcal{X}_{\tau_{i} \wedge \tau_{i} \wedge \tau_{k}}\left|v_{i} \wedge v_{j} \wedge v_{k}\right|\right]^{1 / 2}<C \delta^{3}\left(\sum\left|\lambda_{i}\right|\right)^{1 / 2}\left(\sum\left|\mu_{j}\right|\right)^{1 / 2}\left(\sum\left|\eta_{k}\right|\right)^{1 / 2}
$$

## Proof of Proposition 8.1

Rescaling $x \rightarrow \frac{x}{\lambda}$, we obtain the phase function

$$
\phi(x, y)=\lambda \phi\left(\frac{x}{\lambda}, y\right) \text { where }|x|=o(\lambda)
$$

Partition the $y$-domain $\Omega$ in boxes $\Omega_{\alpha}$ of size $\frac{1}{\sqrt{\lambda}}$ centered at points $y_{\alpha}$. Write for $y \in \Omega_{\alpha}$

$$
\phi(x, y)=\phi\left(x, y_{\alpha}\right)+\left\langle\nabla_{y} \phi\left(x, y_{\alpha}\right)\right\rangle_{O}\left(\lambda\left|y-y_{\alpha}\right|^{2}\right)
$$

where the last term may be dropped.

$$
\begin{equation*}
T_{\alpha} f(x)=\int_{\Omega_{\alpha}} e^{i\left\langle\nabla_{y} \phi\left(x, y_{\alpha}\right), y-y_{\alpha}\right\rangle} f(y) d y \tag{8.4}
\end{equation*}
$$

and write

$$
\begin{equation*}
T f(x)=\sum_{\alpha} e^{i \phi\left(x, y_{\alpha}\right)}\left(T_{\alpha} f\right)(x) \tag{8.5}
\end{equation*}
$$

Next, introduce a variable $z \in B(0, \sqrt{\lambda})$, writing

$$
\begin{equation*}
T f(x+z) \sim \sum_{\alpha} e^{i \phi\left(x+z, y_{\alpha}\right)}\left(T_{\alpha} f\right)(x) \tag{8.6}
\end{equation*}
$$

Returning to (8.2), write

$$
\begin{equation*}
\int_{B(0, \lambda)}\left[\prod_{i=1}^{3}\left|T^{(i)} f_{i}\right|\right]^{\frac{q}{3}} \sim \lambda^{-\frac{3}{2}} \int_{B(0, \lambda)}\left\|\prod_{i=1}^{3}\left(T^{(i)} f_{i}\right)(x+z)\right\|_{L^{q / 3}(|z|<\sqrt{\lambda})}^{q / 3} d x \tag{8.7}
\end{equation*}
$$

with $T^{(i)} f_{i}(x+z)$ replaced by (8.6).
Estimate $\left\|\prod_{i=1}^{3}\right\|_{\frac{q}{3}} \leq\left\|\prod_{i=1,2}\right\|_{\frac{q}{2}}^{\frac{1}{2}}\left\|\prod_{i=2,3}\right\|_{\frac{q}{2}}^{\frac{1}{2}}\left\|\prod_{i=3,1}\right\|_{\frac{q}{2}}^{\frac{1}{2}}$.
Denoting

$$
\eta(z, y)=\phi(x+z, y)-\phi(x, y) \quad(x \text { fixed })
$$

we bound

$$
\begin{equation*}
\int_{B(0, \sqrt{\lambda})}\left|\sum_{\alpha} e^{i \eta\left(z, y_{\alpha}\right)}\left(T_{\alpha}^{(1)} f_{1}\right)(x)\right|^{\frac{q}{2}}\left|\sum_{\beta} e^{i \eta\left(z, y_{\beta}\right)}\left(T_{\beta}^{(2)} f_{2}\right)(x)\right|^{\frac{q}{2}} d z \tag{8.8}
\end{equation*}
$$

Define functions $g_{1}, g_{2}$ by

$$
\begin{equation*}
g_{1}(y)=e^{i \eta\left(z, y_{\alpha}\right)}\left(T_{\alpha}^{(1)} f_{1}\right)(x) \text { for } y \in \Omega_{\alpha} \tag{8.9}
\end{equation*}
$$

and similarly for $g_{2}$.
Clearly

$$
\begin{equation*}
(8.8) \sim \lambda^{q} \int_{B(0, \sqrt{\lambda})}\left|\int e^{i \eta(z, y)} g_{1}(y) d y\right|^{\frac{q}{2}}\left|\int e^{i \eta(z, y)} g_{2}(y) d y\right|^{\frac{q}{2}} d z \tag{8.10}
\end{equation*}
$$

Since, following (5.19)-(5.22) in $\S 5, \eta$ has the form

$$
\begin{equation*}
\eta(z, y)=z_{1} y_{1}+z_{2} y_{2}+z_{3}\left(\langle A y, y\rangle+O\left(|y|^{3}\right)\right)+O\left(|z| \frac{|x|}{\lambda}|y|^{2}\right)+O\left(\frac{|z|^{2}}{\lambda}|y|^{2}\right) \tag{8.11}
\end{equation*}
$$

the last term in (8.11) may be dropped for $|z|<\sqrt{\lambda}$. Hence $\eta(z, y)$ may be viewed as linear in $z$, of the form

$$
\begin{equation*}
z_{1} y_{1}+z_{2} y_{2}+z_{3}\left\langle A_{58}^{\prime} y, y\right\rangle+O\left(|z||y|^{3}\right) \tag{8.12}
\end{equation*}
$$

with $A^{\prime}$ positive definite.
Applying the bilinear $2 \times 2 \rightarrow \frac{q}{2}$ bound from [T1], it follows that

$$
\begin{align*}
(8.10) & \lesssim \lambda^{q}\left\|g_{1}\right\|_{2}^{\frac{q}{2}}\left\|g_{2}\right\|_{2}^{\frac{q}{2}} \\
& \sim \lambda^{q / 2}\left[\sum_{\alpha}\left|\left(T_{\alpha}^{(1)} f_{1}\right)(x)\right|^{2}\right]^{\frac{q}{4}}\left[\sum_{\beta}\left|\left(T_{\beta}^{(2)} f_{2}\right)(x)\right|^{2}\right]^{\frac{q}{4}} \tag{8.13}
\end{align*}
$$

¿From (8.13), the following bound on (8.7) is obtained

$$
\begin{equation*}
\lambda^{\frac{1}{2}(q-3)} \int_{B(0, \lambda)}\left\{\prod_{i=1}^{3}\left[\sum_{\alpha}\left|\left(T_{\alpha}^{(i)} f_{i}\right)(x)\right|^{2}\right]^{\frac{q}{6}}\right\} d x \tag{8.14}
\end{equation*}
$$

The next step is to capture the factors in (8.14) by curved Kakeya maximal functions. ¿From definition of $T_{\alpha}$

$$
\begin{equation*}
\left|T_{\alpha} f\right|^{2}(x)=\left|\hat{f}_{\alpha}\right|^{2}\left(\nabla_{y} \phi\left(x, y_{\alpha}\right)\right) \text { where } f_{\alpha}=\left.f\right|_{\Omega_{\alpha}} \tag{8.15}
\end{equation*}
$$

Let $b$ be a standard bumpfunction on $\mathbb{R}^{d-1}$. Then $\left|\hat{f}_{\alpha}\right|^{2}$ may be recovered by an average of translates $b\left(\frac{\xi-\cdot}{\sqrt{\lambda}}\right)$ with averaging weight $\lambda^{-1}\left\|f_{\alpha}\right\|_{2}^{2}$.

Denoting

$$
c_{\alpha}^{(i)}=\left\|f_{i, \alpha}\right\|_{2}^{2} \quad(i=1,2,3)
$$

satisfying

$$
\begin{equation*}
\sum_{\alpha} c_{\alpha}^{(i)}=\left\|f_{i}\right\|_{2}^{2} \tag{8.16}
\end{equation*}
$$

we obtain therefore

$$
\begin{equation*}
\sum_{\alpha}\left|\left(T_{\alpha}^{(i)} f_{i}\right)(x)\right|^{2} \lesssim \lambda^{-1} \sum_{\alpha, \nu}^{(i)} b\left(\lambda^{-\frac{1}{2}}\left(\nabla_{y} \phi\left(x, y_{\alpha}\right)-\xi_{\alpha, \nu}\right)\right) \cdot c_{\alpha, \nu}^{(i)} \tag{8.17}
\end{equation*}
$$

where $c_{\alpha, \nu}^{(i)}>0, \sum_{\nu} c_{\alpha, \nu}^{(i)}=c_{\alpha}^{(i)}$ and

$$
\begin{equation*}
\sum_{\alpha, \nu} c_{\alpha, \nu}^{(i)}=\left\|f_{i}\right\|_{2}^{2} \tag{8.18}
\end{equation*}
$$

Substituting (8.17) in (8.14), one gets

$$
\lambda^{-\frac{3}{2}} \int_{B(0, \lambda)}\left\{\prod_{i=1}^{3}\left[\sum_{\alpha, \nu}^{(i)} b\left(\lambda^{-\frac{1}{2}}\left(\nabla_{y} \phi\left(x, y_{\alpha}\right)-\xi_{\alpha, \nu}\right)\right) c_{\alpha, \nu}^{(i)}\right]^{\frac{q}{6}}\right\} d x
$$

$$
\begin{equation*}
=\lambda^{\frac{3}{2}} \int_{B(0,1)}\left\{\prod_{i=1}^{3}\left[\sum_{\alpha, \nu}^{(i)} c_{\alpha, \nu}^{(i)} b\left(\lambda^{-\frac{1}{2}}\left(\nabla_{y} \phi\left(\lambda x^{\prime}, y_{\alpha}\right)-\xi_{\alpha, \nu}\right)\right)\right]^{\frac{q}{6}}\right\} d x^{\prime} \tag{8.19}
\end{equation*}
$$

We may now apply Proposition 8.3. In the present trilinear setting, $\left|v_{i} \wedge v_{j} \wedge v_{k}\right|>c$ and hence

$$
\begin{equation*}
\left\|\prod_{i=1}^{3}\left[\sum_{s} \lambda_{s}^{(i)} \mathcal{X}_{\tau_{s}}{ }^{(i)}\right]\right\|_{L^{1 / 2}} \leq c \delta^{6} \prod_{i=1}^{3}\left[\sum_{s}\left|\lambda_{s}^{(i)}\right|\right] \tag{8.20}
\end{equation*}
$$

where $\delta=\frac{1}{2}$ and the tubes $\tau$ of the form

$$
\begin{equation*}
\lambda^{-1}\left|\nabla_{y} \phi(\lambda x, y)-\xi\right|<\lambda^{-1 / 2} \tag{8.21}
\end{equation*}
$$

Interpolation of (8.20) with the obvious $L^{\infty}$-bound gives, for $r \geq \frac{1}{2}$

$$
\begin{equation*}
\left\|\prod_{i=1}^{3}\left[\sum_{s} \lambda_{s}^{(i)} \mathcal{X}_{\tau_{s}^{(i)}}\right]\right\|_{L^{r}} \leq c \delta^{\frac{3}{r}} \prod_{i=1}^{3}\left[\sum_{s} \mid \lambda_{s}^{(i)}\right] . \tag{8.22}
\end{equation*}
$$

Application of (8.22) to (8.19) with $r=\frac{q}{6}>\frac{5}{9}$ implies, by (8.18)

$$
\begin{equation*}
\text { (8.7), (8.14), (8.19)<C } \lambda^{3 / 2}\left(\frac{1}{\sqrt{\lambda}}\right)^{3} \prod_{i=1}^{3}\left\|f_{i}\right\|_{2}^{q / 3} \tag{8.23}
\end{equation*}
$$

and in view of the initial rescaling, (8.2) follows.

## Appendix: Upsilon Removal Lemmas

We consider first the restriction (or extension) problem.
What follows is basically a modification of Theorem 1.2 in [T2] on deriving global restriction estimates from local ones. A significant difference is that instead of considering bounds of the type $(\gamma>0)$

$$
\begin{equation*}
\left\|\left.\hat{f}\right|_{S}\right\|_{L^{p}(d \sigma)} \lesssim R^{\gamma}\|f\|_{L^{p}\left(B_{R}\right)} \tag{1}
\end{equation*}
$$

for $f \in L^{p}\left(\mathbb{R}^{n}\right)$, supp $f \subset B_{R}$, we start from a local inequality of the form

$$
\begin{equation*}
\left\|\left.\hat{f}\right|_{S}\right\|_{L^{1}(d \sigma)} \lesssim R^{\gamma}\|f\|_{L^{p}\left(B_{R}\right)} . \tag{2}
\end{equation*}
$$

Compared with the argument from [T2], this will require additional involvement of the Maurey-Nikishin factorization theorem.

Lemma A1. Assuming $1<p<2,0<\gamma \ll 1$ and (2). Then

$$
\begin{equation*}
\left\|\left.\hat{f}\right|_{S}\right\|_{L^{1}(d \sigma)} \lesssim\|f\|_{p_{1}} \tag{3}
\end{equation*}
$$

for $f \in L^{p_{1}}\left(\mathbb{R}^{n}\right)$ and

$$
\begin{equation*}
\frac{1}{p_{1}}>\frac{1}{p}+\frac{C}{\log \frac{1}{\gamma}} \tag{4}
\end{equation*}
$$

In particular, if (1) holds for arbitrary small $\gamma>0$, the global inequality (3) will hold for any $p_{1}<p$.

We start by dualizing (2), implying that the operator

$$
T: L^{\infty}(S, d \sigma) \rightarrow L^{p^{\prime}}\left(B_{R}\right):\left.\varphi \rightarrow \widehat{\varphi \sigma}\right|_{B_{R}} \quad\left(p^{\prime}=\frac{p}{p-1}\right)
$$

satisfies $\|T\|<R^{\gamma}$. Hence, from the theory of absolutely summary operators, fixing any $r>p^{\prime}>2$, there is a probability measure $\mu$ on $S$, such that

$$
\begin{equation*}
\|\widehat{\varphi \sigma}\|_{L^{p^{\prime}}\left(B_{R}\right)} \lesssim R^{\gamma}\|\varphi\|_{L^{r}(d \mu)} \tag{5}
\end{equation*}
$$

There is no harm to assume $\frac{d \mu}{d \sigma}>\frac{1}{2}$.
We first enforce some smoothness for the density. Let $\tau: S \rightarrow S$ be any diffeomorphism that is $\frac{1}{R}$-close to the identity. Then, for $|x|<R$, a change of variables gives

$$
\begin{align*}
(\widehat{\varphi \circ \tau)} \sigma(x) & =\int \varphi(\tau(\xi)) e(x . \xi) \sigma(d \xi)= \\
& \int \varphi\left(\xi^{\prime}\right) e\left(x \cdot \tau^{-1}\left(\xi^{\prime}\right)\right) \Delta\left(\xi^{\prime}\right) \sigma\left(d x^{\prime}\right) \quad \text { where }|1-\Delta| \lesssim \frac{1}{R} \\
& =\int(\Delta \varphi)\left(\xi^{\prime}\right) e\left(x \cdot \xi^{\prime}\right) \sigma\left(d \xi^{\prime}\right)  \tag{6}\\
& +O\left\{\sum_{j \geq 1} \frac{1}{j!}\left|\int\left(\Delta \psi_{j} \varphi\right)\left(\xi^{\prime}\right) e\left(x \xi^{\prime}\right) \sigma\left(d \xi^{\prime}\right)\right|\right\} \tag{7}
\end{align*}
$$

where (7) is obtained by Taylor expansion of $e\left(x \cdot\left(\tau^{-1}\left(\xi^{\prime}\right)-\xi^{\prime}\right)\right)$ and $\left|\psi_{j}\left(\xi^{\prime}\right)\right|<\left(R\left|\tau^{-1}\left(\xi^{\prime}\right)-\xi^{\prime}\right|\right)^{j}<1$ by assumption on $\tau$. Hence

$$
|T(\varphi \circ \tau)| \leq|T(\varphi \Delta)|+\sum_{j \geq 1} \frac{1}{j!}\left|T\left(\Delta \psi_{j} \varphi\right)\right|
$$

and applying (5)

$$
\|T(\varphi \circ \tau)\|_{L^{p^{\prime}}\left(B_{R}\right)} \lesssim R^{\gamma}\|\varphi\|_{L^{r}(d \mu)}
$$

Replacing $\varphi$ by $\varphi \circ \tau^{-1}$, we obtain

$$
\|T \varphi\|_{p^{\prime}} \lesssim R^{\gamma}\left\|\varphi \circ \tau^{-1}\right\|_{L^{r}(d \mu)}=R^{\gamma}\|\varphi\|_{L^{r}\left(d \mu_{\tau}\right)}
$$

with $\mu_{\tau}=\left(\tau^{-1}\right)_{*}[\mu]$. Averaging over $\tau$ as above allows us to smoothen out $\mu$ at scale $\frac{1}{R}$ and replace $\mu$ by a probability measure $\mu^{\prime}$ on $S, \mu \ll \sigma$ and $\frac{d \mu^{\prime}}{d \sigma}=\rho \geq \frac{1}{2}$ with $\rho$ smooth at scale $\frac{1}{R}$. Thus we have

$$
\begin{equation*}
\|\widehat{\varphi \sigma}\|_{L^{p^{\prime}\left(B_{R}\right)}} \leq R^{\gamma}\left\|\varphi \rho^{1 / r}\right\|_{L^{r}(d \sigma)} \tag{8}
\end{equation*}
$$

and dualizing

$$
\left\|\left.\hat{f} \rho^{-1 / r}\right|_{S}\right\|_{L^{r^{\prime}}(d \sigma)} \leq R^{\gamma}\|f\|_{p} \text { if } \operatorname{supp} f \subset B_{R}
$$

In what preceeds, we fixed $R \geq 1$. Note that $\rho$ depends on $R$.
Following [T2], define a finite collection of balls $\left\{B\left(a_{\alpha}, R\right)\right\}_{\alpha=1}^{N}$ in $\mathbb{R}^{n}$ as 'sparse' if for $\alpha \neq \alpha^{\prime}$

$$
\begin{equation*}
\left|a_{\alpha}-a_{\alpha^{\prime}}\right|>(N R)^{C} \tag{9}
\end{equation*}
$$

( $C$ some constant to specify).
Let now supp $f \subset \bigcup_{\alpha} B\left(a_{\alpha}, R\right)$, i.e.

$$
f=\sum_{\alpha=1}^{N} f_{\alpha}\left(x-a_{\alpha}\right) \text { with } \operatorname{supp} f_{\alpha} \subset B_{R}
$$

Hence

$$
\hat{f}(\xi)=\sum e\left(a_{\alpha} \cdot \xi\right) \hat{f}_{\alpha}(\xi)
$$

and since $\|\varphi\|_{1}=1$

$$
\begin{equation*}
\left\|\left.\hat{f}\right|_{S}\right\|_{L^{1}(d \sigma)} \leq\left\|\left[\sum e\left(a_{\alpha} \cdot \xi\right) \hat{f}_{\alpha}(\xi)\right] \rho^{-\frac{1}{r}}(\xi)\right\|_{L^{r^{\prime}}(d \sigma)} \tag{10}
\end{equation*}
$$

Note that by our construction of $\rho$, the function $g_{\alpha}=\left.\hat{f}_{\alpha} \cdot \rho^{-\frac{1}{r}}\right|_{S}$ is smooth at scale $\frac{1}{R}$. The sparsity of $\left\{a_{\alpha}\right\}$ allows then to estimate

$$
\begin{equation*}
\left\|\sum_{1}^{N} e\left(a_{\alpha} \cdot \xi\right) g_{\alpha}(\xi)\right\|_{L^{r^{\prime}}(d \sigma)} \leq 2\left(\sum\left\|g_{\alpha}\right\|_{L^{r^{\prime}}(d \sigma)}^{r^{\prime}}\right)^{1 / r^{\prime}} \tag{11}
\end{equation*}
$$

This is basically Lemma 3.2 in [T2] and we include the argument for completeness sake.

Establish (11) by interpolation.
More precisely, the claim will follow from an inequality for $1 \leq s \leq 2$

$$
\begin{equation*}
\left\|\left.\sum_{1}^{N} e\left(a_{\alpha} \cdot \xi\right)\left(\tilde{\varphi}_{\alpha} * P_{\frac{1}{R}}\right)(\xi)\right|_{S}\right\|_{L^{s}(d \sigma)} \lesssim\left(\sum\left\|\varphi_{\alpha}\right\|_{L^{s}(d \sigma)}^{s}\right)^{\frac{1}{s}} \tag{12}
\end{equation*}
$$

where $\left\{\varphi_{\alpha}\right\}$ are arbitrary functions in $L^{s}(S, d \sigma), \sim$ denotes a well-behaved extension operator from $L^{*}(S) \rightarrow L^{*}\left(\mathbb{R}^{n}\right)$ (take for instance the harmonic extension) and $P_{\frac{1}{R}}$ is an $\frac{1}{R}$-approximate identity.

For $s=1$, (12) is trivial from triangle inequality and since $\left\|\left.\left(\tilde{\varphi} * P_{\frac{1}{R}}\right)\right|_{S}\right\|_{1} \lesssim\|\varphi\|_{1}$.
For $s=2$, we obtain for the square of the left side of (12)

$$
\begin{equation*}
\sum_{1}^{N}\left\|\varphi_{\alpha}\right\|_{2}^{2}+\sum_{\alpha \neq \alpha^{\prime}}\left|\int e\left(\left(a_{\alpha}-a_{\alpha^{\prime}}\right) \cdot \xi\right)\left(\tilde{\varphi}_{\alpha} * P_{\frac{1}{R}}\right)(\xi) \cdot \overline{\left(\tilde{\varphi}_{\alpha^{\prime}} * P_{\frac{1}{R}}\right)}(\xi) \sigma(d \xi)\right| \tag{13}
\end{equation*}
$$

and show that the contribution of the off-diagonal is small.
Denoting $\Phi_{\alpha}=\tilde{\varphi}_{\alpha} * P_{\frac{1}{R}}$, we may assume supp $\hat{\Phi}_{\alpha} \subset B_{R}$ so that clearly, invoking the decay of $\hat{\sigma}$ and the fact that $\left|a_{\alpha}-a_{\alpha^{\prime}}\right| \gg R$

$$
\begin{aligned}
& \left|\int e\left(\left(a_{\alpha}-a_{\alpha^{\prime}}\right) \cdot \xi\right) \Phi_{\alpha}(\xi) \overline{\Phi_{\alpha^{\prime}}}(\xi) \sigma(d \xi)\right| \lesssim \\
& \frac{1}{\left|a_{\alpha}-a_{\alpha^{\prime}}\right|^{\frac{n-1}{2}}}\left\|\hat{\phi}_{\alpha}\right\|_{1}\left\|\hat{\phi}_{\alpha^{\prime}}\right\|_{1} \lesssim \frac{R^{n}}{\left|a_{\alpha}-a_{\alpha^{\prime}}\right|^{\frac{n-1}{2}}}\left\|\phi_{\alpha}\right\|_{2}\left\|\phi_{\alpha^{\prime}}\right\|_{2} \\
& \lesssim \frac{R^{n}}{\left|a_{\alpha}-a_{\alpha^{\prime}}\right|^{\frac{n-1}{2}}}\left\|\varphi_{\alpha}\right\|_{2}\left\|\varphi_{\alpha^{\prime}}\right\|_{2}
\end{aligned}
$$

Consequently, the second term in (13) is bounded by the first, provided

$$
\max _{\alpha} \sum_{\alpha^{\prime} \neq \alpha} \frac{1}{\left|a_{\alpha}-a_{\alpha^{\prime}}\right|^{\frac{n-1}{2}}}<R^{-n}
$$

This will be ensured if we require for $\alpha \neq \alpha^{\prime}$

$$
\begin{equation*}
\left|a_{\alpha}-a_{\alpha^{\prime}}\right|>N^{\frac{n+1}{n(n-1)}} R^{\frac{2 n}{n-1}} \tag{14}
\end{equation*}
$$

as implied by (9) for $C$ large enough. Then (12) will hold for $s=2$ and hence for $1 \leq s \leq 2$. Thus we proved (11).

Application of (11) with $g_{\alpha}=\left.\hat{f}_{\alpha} \cdot \rho^{-\frac{1}{r}}\right|_{S}$ and invoking (8') implies that

$$
\begin{equation*}
\left\|\left.\hat{f}\right|_{S}\right\|_{L^{1}(d \sigma)} \lesssim R^{\gamma}\left(\sum_{\alpha=1}^{N}\left\|f_{\alpha}\right\|_{p}^{r^{\prime}}\right)^{\frac{1}{r^{\prime}}} \lesssim R^{\gamma} N^{\frac{1}{r^{\prime}}-\frac{1}{p}}\|f\|_{p} \tag{15}
\end{equation*}
$$

(recall that $r>p^{\prime}$ is arbitrary).
Thus inequality (15) holds provided supp $f$ is contained in a sparse collection of $N$ balls of radius $R$.

The next ingredient is the following covering lemma (Lemma 3.3) from [T2].
Lemma A2. Suppose $E \subset \mathbb{R}^{n}$ is a finite union of 1 -cubes and take $0<\delta<1$. Then there exist $O\left(\frac{1}{\delta}|E|^{\delta}\right)$ sparse collections of balls that cover $E$, such that the balls in each collection have radius at most $O\left(|E|^{C^{1 / \delta}}\right)$.

Of course the number of balls in each collection is trivially bounded by $|E|$.
Assume supp $f \subset E$ and apply Lemma A2 to $E$ (assumed a union of 1-cubes). Hence

$$
E \subset \bigcup_{j \lesssim \frac{1}{\delta}|E|^{\delta}} \bigcup_{a \in \mathcal{E}_{j}} B\left(a, R_{j}\right)
$$

with $R_{j} \lesssim|E|^{C^{1 / \delta}}$ and $\left\{B\left(a, R_{j}\right) ; a \in \mathcal{E}_{j}\right\}$ sparse for each $j ; \# \mathcal{E}_{j} \leq N=|E|$.
Writing $f=\sum f_{j}, f_{j}=\left.f\right|_{\cup_{a \in \mathcal{E}_{j}} B\left(a, R_{j}\right)}$, application of inequality (15) to each $f_{j}$ implies

$$
\begin{equation*}
\left\|\left.\hat{f}\right|_{S}\right\|_{L^{1}(d \sigma)} \lesssim \frac{1}{\delta}|E|^{\gamma C^{1 / \delta}+\delta} N^{\frac{1}{r^{\prime}}-\frac{1}{p}}\|f\|_{p} \tag{16}
\end{equation*}
$$

Taking $\delta \sim \frac{1}{\log \frac{1}{\gamma}}$ and $r<p^{\prime}+\frac{1}{\log \frac{1}{\gamma}}$, we conclude that

$$
\begin{equation*}
\left\|\left.\hat{f}\right|_{S}\right\|_{L^{1}(d \sigma)} \lesssim \gamma|E|^{\frac{C}{\log \frac{1}{\gamma}}}\|f\|_{p} \tag{17}
\end{equation*}
$$

Let $p_{1}<p$ and $f \in L^{p_{1}}\left(\mathbb{R}^{n}\right),\|f\|_{p_{1}} \leq 1$, which we assume constant on $c$-cubes $(c \sim 1)$.
Decompose in level sets

$$
f=\left.\sum_{k \geq 0} f\right|_{\left[2^{-k-1} \leq|f|<2^{-k}\right]}=\sum f_{k}
$$

with $\operatorname{supp} f_{k}=E_{k}, E_{k}$ a union of $N_{k} c$-cubes and $2^{-k p_{1}} N_{k} \lesssim 1$.
¿From (17)

$$
\left\|\left.\hat{f}_{k}\right|_{S}\right\|_{L^{1}(d \sigma)} \lesssim N_{k}^{\frac{c}{\log \frac{1}{\gamma}}}\left\|f_{k}\right\|_{p} \lesssim 2^{k\left[\frac{c p_{1}}{\log \frac{1}{\gamma}}+\frac{p_{1}}{p}-1\right]}
$$

and therefore

$$
\begin{equation*}
\left\|\left.\hat{f}\right|_{S}\right\|_{L^{1}(d \sigma)}<C_{\gamma} \tag{18}
\end{equation*}
$$

provided

$$
\begin{equation*}
\frac{C}{\log \frac{1}{\gamma}}<1-\frac{p_{1}}{p} \tag{19}
\end{equation*}
$$

which amounts to condition (4).
Arguing like in [T2], we showed that (18) holds for any function $f \in L^{p_{1}}\left(\mathbb{R}^{n}\right)$ of the form $f=\sum_{\xi \in \mathcal{L}} \lambda_{\xi} 1_{B(\xi, c)}$ with $\sum\left|\lambda_{\xi}\right|^{p_{1}} \leq 1$ and $\mathcal{L}$ a (shifted) 1-lattice. Taking $c>0$ a sufficiently small constant as to ensure that $\widehat{1_{B_{(0, c)}}}$ is positive on $S$, it follows that

$$
\begin{equation*}
\left\|\left.\left[\sum_{\xi \in \mathcal{L}} \lambda_{\xi} e(x . \xi)\right]\right|_{S}\right\|_{L^{1}(d \sigma)}<C\left(\sum\left|\lambda_{\xi}\right|^{p_{1}}\right)^{\frac{1}{p_{1}}} \tag{20}
\end{equation*}
$$

Another averaging over translates $\mathcal{L}$ of the $\mathbb{Z}^{n}$-lattice gives (3).
This completes the proof of Lemma A1.

Next, we prove the upsilon-removal lemma in the variable coefficient multilinear case. Recall the setting.

Consider $T_{\lambda}$ and in (1.4), (1.5) with fixed, large $\lambda$ and define

$$
\begin{equation*}
(T f)(x)=\int e^{i \phi(x, y)} f(y) d y \tag{21}
\end{equation*}
$$

with

$$
\begin{equation*}
\phi(x, y)=x_{1} y_{1}+\cdots+x_{n-1} y_{n-1}+x_{n}\left(\langle A y, y\rangle+O\left(|y|^{3}\right)\right)+\lambda \phi_{\nu}\left(\frac{x}{A}, y\right) \tag{22}
\end{equation*}
$$

as in $\S 5$, where $|x|=o(\lambda),|y|=o(1)$ and $A$ non-degenerate.
Let $2 \leq k \leq n$ and $U_{1}, \ldots, U_{k}$ fixed balls in $y$-space satisfying the transversality condition (5.6). For $j=1, \ldots k$, denote

$$
\begin{equation*}
T_{j} f=\int_{U_{j}} e^{i \phi(x, y)} f(y) d y \tag{23}
\end{equation*}
$$

Clearly the [BCT] result implies that if $1<R<o(\lambda)$, then

$$
\begin{equation*}
\left\|\left(\prod_{j=1}^{k}\left|T_{j} f_{j}\right|\right)^{\frac{1}{k}}\right\|_{L^{q}\left(B_{R}\right)} \ll R^{\varepsilon}\left(\prod_{j=1}^{k}\left\|f_{j}\right\|_{2}\right)^{1 / k} \tag{24}
\end{equation*}
$$

with $q=\frac{2 k}{k-1}$ and $B_{R}=B(0, R)$. This statement is also easily seen to imply (24) with $B_{R}=B(a, R)$ any $R$-ball with $|a|=o(\lambda)$.

Our aim is to remove the $R^{\varepsilon}$-factor at the cost of increasing slightly the exponent $q$. Thus

Lemma A3. Under the above assumptions and taking $q_{1}>\frac{2 k}{k-1}$, we have an inequality

$$
\begin{equation*}
\left\|\left(\prod_{j=1}^{k}\left|T_{j} f_{j}\right|\right)^{\frac{1}{k}}\right\|_{q_{1}} \leq C_{n, k, q_{1}}\left(\prod_{j=1}^{k}\left\|f_{j}\right\|_{2}\right)^{1 / k} \tag{25}
\end{equation*}
$$

(Note that we do not claim removal of the $\lambda^{\varepsilon}$-factor in Theorem 6.2 from [BCT], as the context of our Lemma A3 is more restrictive, since the $T_{j}$-operators are given by (22), (23))

Let $\left\|f_{j}\right\|_{2}=1$ and $F=\left(\prod_{1}^{k}\left|T_{j} f_{j}\right|\right)^{\frac{1}{k}}$.
Let $E \subset \mathbb{R}^{d}$ be obtained as union of a sparse collection of $R$-balls $B\left(a_{\alpha}, R\right),\left|a_{\alpha}\right|=$ $o(\lambda)$ with $\alpha=1, \ldots, N$. We will show that

$$
\begin{equation*}
\left\|\left.F\right|_{E}\right\|_{q}<C_{\varepsilon} R^{\varepsilon} . \tag{26}
\end{equation*}
$$

Using Lemma A2, this will imply that for $E^{\prime} \subset \mathbb{R}^{n}$ any finite union of 1-cubes we have

$$
\begin{equation*}
\left\|\left.F\right|_{E^{\prime}}\right\|_{q}<\frac{1}{\delta} C_{\varepsilon}\left|E^{\prime}\right|^{\delta+\varepsilon C^{1 / \delta}} \tag{27}
\end{equation*}
$$

with $\delta>0$ a parameter. Hence, for all $\varepsilon<0$

$$
\begin{equation*}
\left\|\left.F\right|_{E^{\prime}}\right\|_{q}<C_{\varepsilon}^{\prime}\left|E^{\prime}\right|^{\varepsilon} \tag{28}
\end{equation*}
$$

from where one easily deduces that $\|F\|_{q_{1}}<C_{q_{1}}$ for $q_{1}>q$.
Let $E=\bigcup B\left(a_{\alpha}, R\right)$ be as above and fix $\alpha$. Write for $x \in B\left(a_{\alpha}, R\right)$

$$
\begin{equation*}
(T f)(x)=\int e^{i\left[\phi(x, y)-\phi\left(a_{\alpha}, y\right)\right]}\left(e^{i \phi\left(a_{\alpha}, y\right)} f(y)\right) \omega_{j}(y) d y \tag{29}
\end{equation*}
$$

with $\omega_{j}$ a smooth localization on $U_{j}$.
Denoting $g(y)=e^{i \phi\left(a_{\alpha}, y\right)} f(y)$,

$$
\begin{equation*}
(29)=\int\left[\int e^{i\left[\phi(x, y)-\phi\left(a_{\alpha}, y\right)+\xi y\right]} \omega_{j}(y) d y\right] \hat{g}(\xi) d \xi \tag{30}
\end{equation*}
$$

Since $\left|\nabla_{y}\left[\phi(x, y)-\phi\left(a_{\alpha}, y\right)\right]\right| \lesssim\left|x-a_{\alpha}\right| \lesssim R$, we may clearly replace in (30) the function $g$ by $P_{R_{1}} g=\left(\hat{g} \eta_{R_{1}}\right)^{\vee}$, denoting $\eta_{R_{1}}(z)=\eta\left(\frac{z}{R_{1}}\right)$ where $0 \leq \eta \leq 1$ is a smooth bumpfunction with $\eta(0)=1$, and taking say

$$
\begin{equation*}
R_{1}=100 N R \tag{31}
\end{equation*}
$$

The remaining contribution to (30) will then indeed by $L^{\infty}$-bounded by $0\left((N R)^{-C}\right)$. Defining

$$
f_{\alpha}=e^{-i \phi\left(a_{\alpha}, y\right)} P_{R_{1}}\left(e^{i \phi\left(a_{\alpha}, y\right)} f\right)
$$

we can thus replace $T f$ by $T f_{\alpha}$ on $B\left(a_{\alpha}, R\right)$. Note that $\left|f_{j, \alpha}\right| \leq\left|f_{j}\right| *\left|\stackrel{\vee}{\eta}_{R_{1}}\right|$ may clearly be assumed supported by $U_{j}$.

Estimate

$$
\begin{align*}
\left\|\left.F\right|_{E}\right\|_{q}^{q} & =\sum_{\alpha}\left\|\left.F\right|_{B\left(a_{\alpha}, R\right)}\right\|_{q}^{q} \\
& =\sum_{\alpha}\left\|\left(\prod_{j}\left|T_{j}\left(f_{j, \alpha}\right)\right|\right)^{\frac{1}{k}}\right\|_{L^{q}\left(B\left(a_{\alpha}, R\right)\right)}^{q}+o(1) \\
& \leq C_{\varepsilon} R^{q \varepsilon} \sum_{\alpha}\left(\prod_{j}\left\|f_{j, \alpha}\right\|_{2}\right)^{q / k}+o(1) \\
& <C_{\varepsilon} R^{q \varepsilon} \max _{j}\left[\sum_{\alpha}\left\|f_{j, \alpha}\right\|_{2}^{q}\right]+o(1) . \tag{32}
\end{align*}
$$

Since $q>2$,

$$
\begin{equation*}
\left(\sum_{\alpha}\left\|f_{\alpha}\right\|_{1}^{q}\right)^{\frac{1}{q}} \leq\left(\sum\left\|f_{\alpha}\right\|_{2}^{2}\right)^{\frac{1}{2}}=\left(\sum_{\alpha}\left\|P_{R_{1}}\left(e^{i \phi\left(a_{\alpha, y}\right)} f\right)\right\|_{2}^{2}\right)^{1 / 2} \tag{33}
\end{equation*}
$$

To bound (33), take functions $\left\{\zeta_{\alpha}\right\}$ such that $\operatorname{supp} \hat{\zeta}_{\alpha} \subset B\left(0, R_{1}\right)$ and $\sum_{\alpha}\left\|\zeta_{\alpha}\right\|_{2}^{2}=1$ and evaluate

$$
\begin{equation*}
\sum_{\alpha}\left\langle e^{i \phi\left(a_{\alpha}, \cdot\right)} f, \zeta_{\alpha}\right\rangle \leq\left\|\sum_{\alpha} e^{i \phi\left(a_{\alpha}, y\right)} \zeta_{\alpha}(y)\right\|_{2}\|f\|_{2} \tag{34}
\end{equation*}
$$

For the off-diagonal terms $\alpha \neq \beta$

$$
\begin{equation*}
\left|\left\langle e^{i \phi\left(a_{\alpha}, \cdot\right)} \zeta_{\alpha}, e^{i \phi\left(a_{\beta}, \cdot\right)} \zeta_{\beta}\right\rangle\right|=\left|\int e^{i\left[\phi\left(a_{\alpha}, y\right)-\phi\left(a_{\beta}, y\right)\right]}\left(\zeta_{\alpha} \bar{\zeta}_{\beta}\right)(y) d y\right| \tag{35}
\end{equation*}
$$

where

$$
\begin{aligned}
\phi(a, y)-\phi\left(a^{\prime}, y\right) & =\left(a_{1}-a_{1}^{\prime}\right) y_{1}+\cdots+\left(a_{d-1}-a_{d-1}^{\prime}\right) y_{d-1}+\left(a_{d}-a_{d^{\prime}}\right)\left(\langle A y, y\rangle+O\left(|y|^{3}\right)\right) \\
& +\lambda\left[\phi_{\nu}\left(\frac{a}{\lambda}, y\right)-\phi_{\nu}\left(\frac{a^{\prime}}{\lambda}, y\right)\right]
\end{aligned}
$$

satisfies either

$$
\left|\nabla_{y}\left[\phi(a, y)-\phi\left(a^{\prime}, y\right)\right]\right| \gtrsim\left|a-a^{\prime}\right|
$$

or

$$
\left|\operatorname{det} D_{y}^{2}\left[\phi(a, y)-\phi\left(a^{\prime}, y\right)\right]\right| \gtrsim\left|a-a^{\prime}\right|^{n-1}
$$

Hence, recalling the sparsity assumption $\left|a_{\alpha}-a_{\beta}\right|>(N R)^{C} \gg R_{1}$, it follows that

$$
\begin{equation*}
(34) \lesssim\left|a_{\alpha}-a_{\beta}\right|^{-\frac{n-1}{2}}\left\|\hat{\zeta}_{\alpha}\right\|_{1}\left\|\hat{\zeta}_{\beta}\right\|_{1} \lesssim R_{1}^{n-1}(N R)^{-C}\left\|\zeta_{\alpha}\right\|_{2}\left\|\zeta_{\beta}\right\|_{2} \tag{36}
\end{equation*}
$$

Therefore $(34) \leq 2\left(\sum\left\|\zeta_{\alpha}\right\|_{2}^{2}\right)^{1 / 2} \leq 2$ and (33) is bounded. Inequality (26) now follows from (32), completing the proof of Lemma A3.

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[^0]:    ${ }^{(*)}$ We will indicate later on in this section how to generalize this last claim to $C^{\infty}$-curves.

