THE DARBOUX COORDINATES FOR A NEW FAMILY OF HAMILTONIAN OPERATORS AND LINEARIZATION OF ASSOCIATED EVOLUTION EQUATIONS

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ABSTRACT. A. de Sole, V. G. Kac, and M. Wakimoto have recently introduced a new family of compatible Hamiltonian operators of the form $H^{(N,0)} = D^2 \circ ((1/u) \circ D)^{2n} \circ D$, where N = 2n+3, n = 0, 1, 2, ..., u is the dependent variable and D is the total derivative with respect to the independent variable. We present a differential substitution that reduces any linear combination of these operators to an operator with constant coefficients and linearizes any evolution equation which is bi-Hamiltonian with respect to a pair of any nontrivial linear combinations of the operators $H^{(N,0)}$. We also give the Darboux coordinates for $H^{(N,0)}$ for any odd $N \ge 3$.

1. INTRODUCTION

The Hamiltonian evolution equations are well known to play an important role in modern mathematical physics. Indeed, a Hamiltonian operator maps the variational derivatives of the conserved quantities into symmetries; this plays an important role in the theory of integrable systems which often turn out to be *bi*-Hamiltonian, see e.g. [5, 6, 8, 13] and references therein. It is thus no wonder that the study and, in particular, the classification of Hamiltonian operators is a subject of ongoing interest, see for instance [1, 3, 7, 6, 11, 12] and the works cited there.

Recently A. de Sole, V. G. Kac, and M. Wakimoto have made a major advance in this area. Namely, in [4] they gave a conjectural classification of Poisson vertex algebras in one differential variable, i.e., of scalar Hamiltonian operators. *Inter alia*, they have come up with a new infinite family of compatible Hamiltonian operators $H^{(N,0)} = D^2 \circ ((1/u) \circ D)^{2n} \circ D$, where N = 2n + 3, n = 0, 1, 2, ..., and Ddenotes the total derivative with respect to the space variable.

Although it is well known [15, 16] that there is no proper counterpart of the Darboux theorem on canonical forms of finite-dimensional Poisson structures for Hamiltonian operators associated with evolutionary PDEs, it is often possible to find new variables in which a Hamiltonian operator takes a simpler form. One such form is the Gardner operator D; in analogy with the finite-dimensional case the associated new variables are often called the Darboux coordinates, see e.g. [3, 15]. Bringing a Hamiltonian operator into the Gardner form enables one e.g. to render the associated Hamiltonian systems into the canonical Hamiltonian form and construct Lagrangian representations (modulo potentialization) for these systems [16].

In this paper we present the transformations that bring the operators $H^{(N,0)}$ into the Gardner form, see Corollary 1 below. Moreover, in Theorem 1 we give a differential substitution which *simultaneously* turns the operators $H^{(N,0)}$ for all odd $N \ge 3$ into the operators with constant coefficients $\tilde{H}^{(N,0)} = -D^{2n+1}$.

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These results could be employed e.g. for the study of (co)homology of the Poisson complexes associated with the operators $H^{(N,0)}$. The cohomologies in question play an important role e.g. in finding all Hamiltonian operators compatible with a given Hamiltonian operator and the associated multi-Hamiltonian systems, see for example [10, 14, 17] and references therein. Another possible application of the results in question is e.g. the construction of new integrable systems in spirit of [9] in the new variables from Theorem 1 or Corollary 1 with the subsequent pullback to the original variables. Last but not least, the differential substitution from Theorem 1 linearizes any evolution equation which is bi-Hamiltonian with respect to a pair of any nontrivial linear combinations of the operators $H^{(N,0)}$, thus exhibiting a broad class of somewhat unusual (in that they are *C*-integrable rather than *S*-integrable) integrable bi-Hamiltonian systems; see Corollary 2 for details.

2. Preliminaries

In what follows we deal with Hamiltonian operators and associated Hamiltonian evolution equations involving a single spatial variable x and a single dependent variable u. An evolution equation of this kind has the form

$$u_t = K[u] = K(x, u, u_x, u_{xx}, \dots),$$

where the square brackets indicate that K is a *differential function* in the sense of [13], meaning that it depends on x, u, and finitely many derivatives of u with respect to the space variable x. Recall (see e.g. [5, 6, 13] for details) that an evolution equation is said to be *Hamiltonian* with respect to the Hamiltonian operator \mathcal{D} if it can be written in the form

$$u_t = \mathcal{D}\delta_u \mathfrak{I}[u],$$

where $\Im = \int T[u] dx$ is the Hamiltonian functional, and δ_u denotes the variational derivative with respect to u.

Lemma 1 ([11]). Let L_1 be a Hamiltonian operator in the variables x, u. Under the transformation

$$x = \varphi(y, v, v_y, \dots, v_m), \quad u = \psi(y, v, v_y, \dots, v_n), \tag{1}$$

where $v_j = D_y^j(v)$, where D_y is the total derivative with respect to y, the operator L_1 goes into the Hamiltonian operator L_2 defined by the formula

$$\overline{L}_1 = (D_y(\varphi))^{-1} K^* \circ L_2 \circ K,$$
(2)

where \overline{L}_1 is obtained from L_1 under the substitution (1) and upon setting $D_x = (D_y(\varphi))^{-1}D_y$,

$$K = \sum_{i=0}^{\max(m,n)} (-1)^i D_y^i \circ \left(\frac{\partial \psi}{\partial v_i} D_y(\varphi) - \frac{\partial \varphi}{\partial v_i} D_y(\psi) \right),$$

and K^* is the formal adjoint of K.

Remark 1. Note that in general the operator L_2 may contain nonlocal terms unless (1) is a contact transformation, cf. e.g. [1, 4, 11].

3. The main result

Theorem 1. The transformation x = v, $u = 1/v_y$ turns the Nth order Hamiltonian operator $H^{(N,0)} = D_x^2 \circ ((1/u) \circ D_x)^{2n} \circ D_x$, where N = 2n+3, n = 0, 1, 2, ..., into the Hamiltonian operator with constant coefficients $\widetilde{H}^{(N,0)} = -D_y^{2n+1}$.

The proof is obtained by a straightforward application of Lemma 1. Even though the transformation from Theorem 1 is not contact, in the particular case under study the transformed operators $\tilde{H}^{(N,0)}$ happen to be free of nonlocal terms (cf. Remark 1).

Using Lemma 1 we can further amplify the result of Theorem 1 by providing the Darboux coordinates (cf. Introduction) for the operators $H^{(N,0)}$.

Corollary 1. The transformation $x = (-1)^{\frac{n+1}{2}} w_n$, $u = (-1)^{\frac{n+1}{2}} / w_{n+1}$, where $w_k = D_z^k(w)$, and z is the new independent variable, maps the Hamiltonian operator $H^{(N,0)} = D_x^2 \circ ((1/u) \circ D_x)^{2n} \circ D_x$ to the first-order Gardner operator D_z for any odd $N \ge 3$.

Remark 2. The inverse of the transformation x = v, $u = 1/v_y$ is nothing but the extended hodograph transformation in the sense of [2]. Let us stress that, unlike the original transformation, the said inverse is not a differential substitution, i.e., it cannot be written in the form $y = \xi(x, u, u_x, \dots, u_q)$, $v = \chi(x, u, u_x, \dots, u_p)$.

Note that the transformation x = v, $u = 1/v_y$ can be written as the composition of x = z, $u = w_z$ and of the hodograph transformation z = v, w = y. The first of these is nothing but introduction of the potential w for u. It is readily seen that a bi-Hamiltonian evolution equation

$$u_t = H_1 \delta_u \mathfrak{T}_1 = H_2 \delta_u \mathfrak{T}_2, \tag{3}$$

where $H_i = \sum_{j=1}^{k_i} c_{ij} H^{(N_{ij},0)}$, $i = 1, 2, k_i$ are arbitrary natural numbers, and c_{ij} are arbitrary constants, is nothing but the pullback of the bi-Hamiltonian equation

$$w_t = \dot{H}_1 \delta_w \mathfrak{T}_1 = \dot{H}_2 \delta_w \mathfrak{T}_2, \tag{4}$$

where $\check{H}_i = \sum_{j=1}^{k_i} c_{ij} \check{H}^{(N_{ij},0)}, \ i = 1, 2,$

$$\check{H}^{(N,0)} = -D_z \circ \left(\frac{1}{w_z} D_z\right)^{2n}$$

and \check{T}_i are obtained from T_i using the substitution x = z, $u = w_z$. It is natural to refer to (4) as to the potential form of (3).

Proposition 1. The transformation z = v, w = y, where y is the new independent variable, linearizes the potential form (4) of the bi-Hamiltonian evolution equation (3).

Before proving this let us point out the following important consequence of this result.

Corollary 2. The differential substitution x = v, $u = 1/v_y$ relates any equation of the form (3) to a linear evolution equation with constant coefficients.

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Informally, this just means that the inverse of the transformation x = v, $u = 1/v_y$ linearizes (3), but this statement should be treated with some care, as this transformation is not uniquely invertible, and the inverse is not a differential substitution, cf. Remark 2 and [18].

Proof of Proposition 1. The hodograph transformation z = v, w = y sends (4) into

$$v_t = \widetilde{H}_1 \delta_v \widetilde{\mathfrak{T}}_1 = \widetilde{H}_2 \delta_v \widetilde{\mathfrak{T}}_2,$$

where $\widetilde{H}_i = \sum_{j=1}^{k_i} c_{ij} \widetilde{H}^{(N_{ij},0)} = -\sum_{j=1}^{k_i} c_{ij} D_y^{N_{ij}-2}$ are linear differential operators with constant coefficients, and $\widetilde{\Upsilon}_i$ are obtained from $\check{\Upsilon}_i$ using the transformation in question.

Lemma 2. Let $v_t = K[v]$ be an nth order evolution equation which is bi-Hamiltonian with respect to a pair of Hamiltonian operators with constant coefficients. Then $v_t = K[v]$ is necessarily a linear equation with constant coefficients, i.e., we have $v_t = \sum_{i=0}^{n} c_i v_i$, where $c_i = \text{const.}$

Proof of the lemma. Denote the Hamiltonian operators in question by \mathcal{D}_i , i = 1, 2. Since $v_t = K[v]$ is bi-Hamiltonian with respect to these operators by assumption, their ratio $\mathcal{R} = \mathcal{D}_2 \circ \mathcal{D}_1^{-1}$ is a (formal) recursion operator for this equation, that is (see e.g. [13] for details),

pr
$$\mathbf{v}_K(\mathcal{R}) - [\mathbf{D}_K, \mathcal{R}] = 0,$$

where $D_K = \sum_{i=0}^n (\partial K/\partial u_i) D^i$ is the Fréchet derivative of K and pr \mathbf{v}_K is the prolongation of the evolutionary vector field \mathbf{v}_K with the characteristic K. Since \mathcal{D}_i , i = 1, 2, have constant coefficients by assumption, we have pr $\mathbf{v}_K(\mathcal{D}_i) = 0$, and therefore pr $\mathbf{v}_K(\mathcal{R}) = 0$, so D_K commutes with \mathcal{R} , whence it readily follows that D_K has constant coefficients (recall that K is independent of t by assumption) and therefore K indeed is a linear combination of v_i with constant coefficients.

The desired result now readily follows from the above lemma.

Example 1. Consider a bi-Hamiltonian evolution equation

$$u_t = D_x^3 \left(u^{-2} \right) = H^{(3,0)} \delta_u \mathfrak{T}_1 = H^{(5,0)} \delta_u \mathfrak{T}_2, \tag{5}$$

where $\mathfrak{T}_1 = -\int dx/u$ and $\mathfrak{T}_2 = \int x^2 u dx$.

The potential form (4) of (5) reads

$$w_t = D_z^2 \left(w_z^{-2} \right) = \check{H}^{(3,0)} \delta_w \check{\mathcal{T}}_1 = \check{H}^{(5,0)} \delta_w \check{\mathcal{T}}_2.$$
(6)

Recall that $u = w_z$ and x = z; we have $\check{H}^{(3,0)} = -D_z$, $\check{H}^{(5,0)} = -D_z \circ ((1/w_z)D_z)^2$, $\check{\Upsilon}_1 = -\int dz/w_z$, and $\check{\Upsilon}_2 = \int z^2 w_z dz$. Note that (6) has, up to a rescaling of t, the form (2.31) from [2].

In perfect agreement with Proposition 1 (cf. also Proposition 2.2 in [2]) the hodograph transformation z = v, w = y linearizes (6) into a (trivially) bi-Hamiltonian equation

$$v_t = -2v_{yyy} = \widetilde{H}^{(3,0)} \delta_v \widetilde{\mathfrak{T}}_1 = \widetilde{H}^{(5,0)} \delta_v \widetilde{\mathfrak{T}}_2, \tag{7}$$

where $\widetilde{H}^{(3,0)} = -D_y$, $\widetilde{H}^{(5,0)} = -D_y^3$, $\widetilde{\mathfrak{T}}_1 = -\int v_y^2 dy$, and $\widetilde{\mathfrak{T}}_2 = \int v^2 dy$.

The transformation x = v, $u = 1/v_y$ relates (7) to (5), cf. Corollary 2, so (5) provides an explicit example of a *C*-integrable (rather than *S*-integrable) bi-Hamiltonian system, just as discussed in Introduction.

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