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Towards More Capable and Less Invasive Robotic Surgery in Orthopaedics

R. O'Toole, <u>David Simon</u>, <u>Branislav Jaramaz</u>, <u>Omar Ghattas</u>, <u>Mike Blackwell</u>, L. Kallivokas, F. Morgan, C. Visnic, <u>Anthony M. Di Gioia</u>, and <u>Takeo Kanade</u>

Proceedings of the First International Conference on Computer Vision, Virtual Reality, and Robotics in Medicine (CVRMed '95), April, 1995.

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Notes

- Associated Center(s) / Consortia: Medical Robotics Technology Center
- Associated Lab(s) / Group(s): Medical Robotics and Computer Assisted Surgery
- Associated Project(s): <u>Joint Replacement Biomechanics</u>

Text Reference

R. O'Toole, <u>David Simon</u>, <u>Branislav Jaramaz</u>, <u>Omar Ghattas</u>, <u>Mike Blackwell</u>, L. Kallivokas, F. Morgan, C. Visnic, <u>Anthony M. Di Gioia</u>, and <u>Takeo Kanade</u>, "Towards More Capable and Less Invasive Robotic Surgery in Orthopaedics," *Proceedings of the First International Conference on Computer Vision, Virtual Reality, and Robotics in Medicine (CVRMed '95)*, April, 1995.

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The <u>Robotics Institute</u> is part of the <u>School of Computer Science</u>, <u>Carnegie Mellon University</u>.

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