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应用卡尔曼滤波的机载雷达跟踪系统

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AIRBORNE RADAR TRACKING SYSTEM BASED ON OPTIMAL FILTERING THEORY

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摘要

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摘要 本文论述将滤波理论应用于机载雷达中对单个目标进行距离、速度、方位角和高低角跟踪的多环反馈系统。首先根据目标和天线的相对运 动建立控制四坐标跟踪环所需的状态矢量微分方程,然后推导相应的非线性滤波算法。最后给出计算机的模拟结果。计算机模拟的结果清晰地说 明采用最佳滤波的系统性能比通常的有很大改善,并且这种瞄准轴坐标系的最佳系统对目标的随机机动是不灵敏的。 本文所讨论的方法和得出的 结论可以延用到地面雷达、舰载雷达以及其他有源和无源的跟踪系统。

## 关键词:

Abstract: In this paper, a filtering theory is applied to the multiple closed-loop feedback system for tracking a single target in range, velocity, azimuth and elevation in an airborne radar. First of all, according to relative motion between arget and antenna, the vector differential equation of the states used to control the four tracking loop is established. Then, the corresponding nonlinear filtering algorithm is derived. Finally, the results of computer simulation are given. The results of computer simulation show that in a wide range the time varying system using Kalman filter can keep better performance than the ordinary one without optimal filter. The system involving nonlinear filtering has a performance closed to the linear filtering one in steady-state response, but the former achieves performance improvement in transient response and in large error. Using Kalman filter, the tracking loops are coupled each other, and its performance is better than that of seperate loops. Finally, we show that a particular merit of this mathematical model, established in aim coordinate system, is less sensitive to target's manoeuvre. Therefore, the system performance is almost as good as an adoptive estimator, but which is sensitive to measurement noise. As the signal to noise ratio of radar varies in a wide range,we should take adaptive method in measuring noise.The technique used and results obtained are also available for ground radar,shipborne radar and other tracking systems,either active or passive. Keywords:

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