

本期目录 | 下期目录 | 过刊浏览 | 高级检索

[打印本页] [关闭]

微纳技术与精密机械

大行程转动柔性铰链性能测试方法及实验

裴旭,李远玥,侯振兴

北京航空航天大学

摘要：针对大行程柔性铰链运动范围较大，转动误差相对较小，实现其转动精度的测量比较困难的问题，提出了一种间接测量大行程柔性铰链转动精度的方法。首先对柔性铰链转动精度的衡量指标进行定义和比较；然后选择合适的指标，提出间接测量该柔性铰链转动中心漂移量和刚度的方法。该方法利用工具显微镜测量铰链运动刚体上的两个特征点在转动过程中的坐标值，从而解算出柔性铰链在不同转角时转动中心点的位置。由此不仅得到了转动中心漂移的大小，还可以得到轴漂的方向。基于该方法搭建了实验平台并对实验误差进行了分析，分析显示其误差主要为特征点坐标的测量误差。实验结果与有限元仿真对比表明，测量结果的误差小于0.006 mm，基本满足对大行程柔性铰链精度测试的要求。

关键词：大行程柔性铰链 转动精度 刚度 工具显微镜 间接测量

Performance measurement and experiment for rotational flexural joint with large-stroke

PEI Xu, LI Yuan-yue, HOU Zhen-xing

School of Mechanical Engineering and Automation, Beihang University

Abstract: A method to measure the rotational precision of a flexural joint with a large stroke was proposed to solve the problems that the flexural joint has relatively smaller rotational error and its rotational precision is difficult to be measured directly. Firstly, five kinds of criterions to evaluate the rotational precision were proposed and compared. Then, a proper criterion was chose, and an indirect method to measure the center-shift and stiffness of the flexural joint was developed according to the criterion. With the method, a measuring microscope was used to survey the coordinates of two mark points on the flexural joint, by which the rotational angle and the position of the real rotational center could be calculated, and the central shift of rotation and its shift direction also could be obtained. An experimental platform was built based on the method, and an isosceles trapezoidal flexural joint was used to validate the method. Experiments show that the rotational precision and the stiffness of the flexural joint can be measured at the same time in the experiment. The results are compared with the finite element analysis simulation and it indicates that the error of the experimental result is less than 0.006 mm, which satisfies the requirement of precision test for most common flexural joints with large-strokes.

Keywords: flexural joint with large-stroke rotational precision stiffness tool microscopes indirect measurement

收稿日期 2012-11-26 修回日期 2013-01-07 网络版发布日期 2013-04-20

基金项目：

大尺寸有障碍空间角度与基面位置测量的关键技术;大尺寸有障碍空间角度与基面位置测量的关键技术

通讯作者：裴旭

作者简介：裴旭（1979-），男，甘肃天水人，博士，讲师，2002年、2004年、2009年于北京航空航天大学分别获得学士、硕士、博士学位，主要研究方向为机器人机构学，柔性机构等。

作者Email: peixu@buaa.edu.cn

参考文献：

- [1]鲁亚飞, 范大鹏, 范世珣, 等. 快速反射镜两轴柔性支承设计[J]. 光学精密工程, 2010, 18(12): 2573-2582. LU Y F, FAN D P, FAN SH X, et al.. Design of two-axis elastic support for fast steering mirror [J]. Opt. Precision Eng., 2010, 18(12): 2573-2582. (in Chinese)
- [2]YU Y Q, FENG Z L, XU Q P. A pseudo-rigid-body 2R model of flexural beam in compliant mechanisms[J]. Mechanism and Machine Theory, 2012, 55(9): 18-33. [3]林雪松, 王淑荣, 李福田. 空间傅里叶变换红外光谱仪用全柔性机构的设计及研究[J]. 光学精密工程, 2005, 13(6): 691-696. LIN X S, WANG SH R, LI F T. Design and investigation of the precision scans structure of space infrared FTS [J]. Opt. Precision Eng., 2005, 13(6): 691-696. (in Chinese)
- [4]于靖军, 宗光华, 毕树生. 全柔性机构与MEMS[J]. 光学精密工程, 2001, 9(1): 1-5. YU J J, ZONG G H, BI SH SH. Fully compliant mechanisms and MEMS [J]. Opt. Precision Eng., 2001, 9(1): 1-5. (in Chinese)
- [5]李琳, 杨勇. 空间曲线切口式柔性铰的设计[J]. 光学精密工程, 2010, 18(10): 2192-2198. LI L, YANG Y. Design of flexure hinges with space curve notches[J]. Opt. Precision Eng., 2010, 18(10): 2192-2198. (in Chinese)
- [6]LI H, IBRAHIM R, CHENG K. Design and principles of an innovative compliant fast tool servo for precision engineering [J]. Mech. Sci., 2011, 2: 139-146. [7]CHEN G M, GOU Y J, ZHANG A M. Synthesis of compliant multistable mechanisms through use of a single bistable mechanism[J]. Journal of Mechanical Design, 2011, 133(8): 081007. [8]SUNG E, SLOCUM A H, MA R, et al.. Design of an ankle rehabilitation device using compliant mechanisms[J]. Journal of Medical Devices, 2011, 5(1), 011001. [9]ZELENKA S, BONA F D. Analytical and experimental characterization of high-precision flexural pivots subjected to lateral loads [J]. Journal of the International Societies for Precision Engineering and Nanotechnology, 2002, 26: 381-388. [10]SMITH S T. Flexures: Elements of Elastic Mechanisms[M]. New York: Gordon and Breach Science. 2000:153-230. [11]陈贵敏, 贾建援, 刘小院, 等. 柔性铰链精度特性研究[J]. 仪器仪表学报, 2004, 25(4): 107-109. CHEN G M, JIAN J Y, LIU X Y, et al.. Study on the accuracy of flexure hinges[J]. Chinese Journal of Scientific Instrument, 2004, 25(4): 107-109. (in Chinese)
- [12]HOWELL L L. Compliant Mechanisms [M]. New York: Wiley Press, 2001. [13]梁晋文, 陈林才. 何贡. 误差理论与数据处理[M]. 北京: 中国计量出版社. 2001. LIANG J W,

1. 李宗轩 张雷 姚劲松 解鹏 金光 孔林. Cartwheel型双轴柔性铰链设计[J]. 光学精密工程, 2013,21(9): 2317-2325
2. 刘双杰 郝永平. S型折叠式微悬臂梁刚度计算[J]. 光学精密工程, 2013,21(2): 388-393
3. 周京博 孙涛 侯国安. 双柔性支撑板快速伺服刀架优化设计及测试[J]. 光学精密工程, 2013,21(2): 349-355
4. 张飞虎, 付鹏强, 汪圣飞, 张强. 超精密机床径推一体式空气静压轴承的静态特性[J]. 光学精密工程, 2012,20(3): 607-615
5. 王超, 陈光焱, 吴嘉丽. 用于低 g_n 值微惯性开关的低刚度平面微弹簧设计与制作[J]. 光学精密工程, 2011,19(3): 620-627
6. 杨波, 王寿荣, 李坤宇, 朱熙, 曹慧亮. 利用负刚度效应调谐的硅调谐式陀螺仪[J]. 光学精密工程, 2010,18(11): 2398-2406
7. 李童杰, 刘云峰, 董景新, 范达. 力反馈式微机械加速度计刚度的自适应调整[J]. 光学精密工程, 2010,18(11): 2430-2436
8. 张雷, 贾学志. 大型离轴三反相机桁架式主支撑结构的设计与优化[J]. 光学精密工程, 2009,17(3): 603-608
9. 陈贵敏, 韩琪. 深切口椭圆柔性铰链[J]. 光学精密工程, 2009,17(3): 570-575
10. 陈长征. SiC和SiC/AI在TMA空间遥感器中的应用[J]. 光学精密工程, 2008,16(12): 2537-2543
11. 沈宏海^{1,2}; 刘晶红¹; 张 葆¹; 戴 明¹; 贾 平¹; 魏忠和¹; 熊经武¹. 航空光电成像平台角位置陀螺和 角速率陀螺的稳定效果分析[J]. 光学精密工程, 2007,15(8): 1293-1299
12. 王乐锋; 荣伟彬; 孙立宁. 三支链六自由度并联柔性铰链机器人的研究[J]. 光学精密工程, 2007,15(4): 529-534
13. 张志杰; 袁怡宝. 单边导角形柔性铰链的计算与性能分析[J]. 光学精密工程, 2007,15(3): 384-387
14. 马 立; 荣伟彬; 孙立宁. 三维纳米级微动工作台的设计与分析[J]. 光学精密工程, 2006,14(6): 1017-1024
15. 荣伟彬; 陈 涛; 陈立国; 孙立宁. 挠性陀螺十字铰链模型的建立与分析[J]. 光学精密工程, 2006,14(5): 864-869