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基本信息

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教育背景

- ▣ 1999年-2002年，中国科学院自动化研究所，获博士学位
- ▣ 1991年-1994年，山东矿业学院，采矿系，获工学硕士学位
- ▣ 1987年-1991年，淮南矿业学院，采矿系，获工学学士学位

研究方向

- ⊕ 控制理论及应用、机器人、机器人视觉

代表论著

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- [8] Hua Xiong, Jian-Qiang Yi, Guo-Liang Fan, Fengshui Jing, Ru-Yi Yuan, "Autolanding of Unmanned Aerial Vehicles based on Active Disturbance Rejection Control," Proc. IEEE International Conference on Intelligent Computing and Intelligent Systems (ICIS 2009), Shanghai, China, 2009, pp. 772-776.
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主要学术成就

- ▶ 谭民, 景奉水, 梁自泽, 李国亮, 王跃, “开放式工业机器人控制平台”, 发明专利, 专利号: ZL00129523.3, 2002.12 (已转让)
- ▶ 谭民, 景奉水, 梁自泽, 李国亮, 王跃, “开放式工业机器人控制平台”, 实用新型, 专利号: ZL00254080.0, 2001.9 (已转让)
- ▶ 谭民, 李国亮, 梁自泽, 景奉水, 王跃, “开放式工业机器人视觉控制平台”, 实用新型, 专利号: ZL01266175.9, 2002
- ▶ 梁自泽, 谭民, 李恩, 景奉水等, “高压输电线路自动巡检机器人单体”, 实用新型, 专利号: ZL200320116747.0, 2003
- ▶ 谭民, 徐德, 梁自泽, 景奉水, 顾农, 陈刚, 赵晓光, 涂志国, 具有视觉焊缝自动跟踪功能的弧焊机器人控制平台, 发明专利, 专利号: 02158340.4, 2005

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