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Volume XXXVIII-5/W12

Int. Arch. Photogramm. Remote Sens. Spatial Inf. Sci., XXXVIII-5/W12, 13-18, 2011 www.int-arch-photogramm-remote-sens-spatial-inf-sci.net/XXXVIII-5-W12/13/2011/ doi:10.5194/isprsarchives-XXXVIII-5-W12-13-2011 © Author(s) 2011. This work is distributed under the Creative Commons Attribution 3.0 License.

HEURISTICAL FEATURE EXTRACTION FROM LIDAR DATA AND THEIR VISUALIZATION

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Keywords: LIDAR, segmentation, feature extraction, visualization

Abstract. Extraction of landscape features from LiDAR data has been studied widely in the past few years. These feature extraction methodologies have been focussed on certain types of features only, namely the bare earth model, buildings principally containing planar roofs, trees and roads. In this paper, we present a methodology to process LiDAR data through DBSCAN, a density based clustering method, which extracts natural and man-made clusters. We then develop heuristics to process these clusters and simplify them to be sent to a visualization engine.

Conference Paper (PDF, 3821 KB)

Citation: Ghosh, S. and Lohani, B.: HEURISTICAL FEATURE EXTRACTION FROM LIDAR DATA AND THEIR VISUALIZATION, Int. Arch. Photogramm. Remote Sens. Spatial Inf. Sci., XXXVIII-5/W12, 13-18, doi:10.5194/isprsarchives-XXXVIII-5-W12-13-2011, 2011.

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