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Research Article

Machine Learning of the Reactor Core Loading Pattern Critical Parameters

Krešimir Trontl,¹ Dubravko Pevec,¹ and Tomislav Šmuc²

¹Department of Applied Physics, Faculty of Electrical Engineering and Computing, University of Zagreb, Bijenicka 3, 10000 Zagreb, Croatia

²Division of Electronics, Ruđer Bošković Institute, Bijenička 54, 10000 Zagreb, Croatia

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Abstract

The usual approach to loading pattern optimization involves high-order polynomial models, an optimization algorithm, and a computer code used for solving the optimization problem. In this paper, the applicability of a machine learning model which combines a recently introduced machine learning technique, support vector machine (SVM) kernel based, nonlinear modeling paradigm, in which model parameters are optimized using quadratic optimization problem. The main objective of the work is to investigate the applicability of applying SVR method for reactor core loading pattern modeling and to discuss its applicability, that is, complexity, speed, and accuracy.

1. Introduction

Decrease of the fuel cycle costs is an important factor in nuclear power cycle. Nuclear power cycle can strongly benefit from the optimization of the reactor core loading pattern. The amount of enriched uranium and burnable absorbers placed in the reactor core affects its operational and safety characteristics.

The usual approach to loading pattern optimization involves high rules, an optimization algorithm, and a reactor physics computer c Since the loading pattern optimization problem is of combinator numbers of core modeling calculations (e.g., genetic algorithms or for one full optimization run is essentially determined by the com pattern.

The aim of the work reported in this paper was to investigate the loading pattern evaluation. We employed a recently introduced ma (SVR), which has a strong theoretical background in statistical lea in which model parameters are automatically determined by solvin

This paper reports on the possibility of applying SVR method for r of the learning data set, as a function of targeted accuracy, influen definition were studied.

In Section 2, the support vector regression method is discussed optimization as well as the methodology applied for the investig loading pattern evaluation are presented in Section 3. Results and 5 the conclusions based on this work are drawn.

2. Support Vector Regression

Machine learning is, by its definition, a study of computer algorithm One of machine learning techniques is the support vector machin background in statistical learning theory [1]. The method pro classification and regression problems. Although, historically sp classification problems [2, 3], in the last decade, the applicati noticeable in different fields of science and technology [4 - 10 generalization properties of the method.

In the upcoming paragraphs, we will give a short introduction int only the most important theoretical and practical aspects of the referenced literature.

In general, the starting point of the machine learning problem is a model (training set) and a separate set to test the learned model regression model, we will consider a training data set, as well input/output pairs, representing the experimental relationship bet output value (y_i):

$$\{(\vec{x}_1, y_1), (\vec{x}_2, y_2), \dots, (\vec{x}_n, y_n)$$

In our case, the input vector defines the characteristics of the load as a target value, denotes the parameter of interest.

The modeling objective is to find a function $y = f(\vec{x})$ such that it acc (y) corresponding to a new input vector (\vec{x}), yet unseen by the particular input vector) [11].

Due to the high complexity of underlying physical process that

expected to have high nonlinear properties. In the support vector machine (SVM) technique, the input data is first mapped into a higher dimensional feature space F using a nonlinear mapping function. The SVM is then performed in that space. Therefore, a problem of nonlinear regression is transformed into a linear regression problem in high-dimensional feature space.

The SVR technique considers the following linear estimation function

$$f(\vec{x}) = \langle \vec{w}, \Phi(\vec{x}) \rangle + b$$

where \vec{w} denotes the weight vector, b is a constant known as bias. The SVM is then performed in that space. Therefore, a problem of nonlinear regression is transformed into a linear regression problem in high-dimensional feature space. The SVM is then performed in that space. Therefore, a problem of nonlinear regression is transformed into a linear regression problem in high-dimensional feature space.

$$R_{\text{reg}}[f] = \sum_{i=1}^M C(f(\vec{x}_i) - y_i)$$

where $R_{\text{reg}}[f]$ denotes regression risk (possible test set error), b is a constant known as bias, C is a cost function determined on the points of the training set, and Φ is a nonlinear mapping function. Minimization task thus involves simultaneous minimization of the regression risk and the complexity of the model. Most commonly used cost function (loss function) is the "ε insensitive loss function":

$$C(f(\vec{x}_i) - y_i) = \begin{cases} \|f(\vec{x}_i) - y_i\| - \varepsilon, & \text{if } \|f(\vec{x}_i) - y_i\| > \varepsilon \\ 0, & \text{otherwise} \end{cases}$$

where ε is a parameter representing radius of the tube around the regression function, as depicted in Figure 1 [7], and y_i are the calculated values (y) lie inside this tube. The deviations of the predicted values from the target values are penalized in the optimization through their positive slack variables.

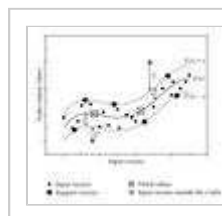


Figure 1: The schematic illustration of the SVR model.

It was shown that the following function minimizes the regularized

$$f(\vec{x}, \vec{w}) = f(\vec{x}, \vec{a}, \vec{a}^*) = \sum_{i=1}^n (a_i^* - a_i)$$

where a_i^* and a_i are Lagrange multipliers describing \vec{w} , and are estimated using a quadratic programming algorithm, and $K(\vec{x}_i, \vec{x})$ is a so called kernel function in feature space. A number of kernel functions exist [13]. Kernel function details in the following section.

Due to the character of the quadratic optimization, only some of the corresponding input vectors \vec{x} are called *support vectors* (SVs). They are positioned inside the ε tolerance tube and are therefore, not interested vectors that are determined in the training (optimization) phase.

the information content of the training set. In most of the SVR for by the user: C -cost of the penalty for data-model deviation, and the chosen form of the kernel function and its corresponding parameters. The performance of the regression model.

3. Methodology

One of the key processes of both, safe and economical operations to be more precise, fuel loading pattern determination and optimization tasks, whether genetic algorithms, or a combination of stated approaches, require evaluation. The evaluation is normally performed using a more or such codes is time consuming. Therefore, in this work, we are involved as a fast tool for loading pattern evaluation.

However, taking into account that the SVR method is to be used, creating a model. The first is the setting of the loading pattern to which the experimental data points are to be generated, the defined target values. The second is the choice of the kernel function and parameters. Finally, SVR modeling tools have to be addressed.

3.1. Computational Experiment Setup

Taking into account the preliminary and inquiring characteristics of inventory for a single loading pattern optimization as a basis for Krško Cycle 22 loading pattern has been used as a reference on were used for core loading in Cycle 22 have been used for generating loading patterns, which were then divided into training and development process. The global core calculations of each of the MCRAC code of the FUMACS code package, which also include: preparation [14]. The calculation is based on quarter core symmetry concentration curve.

The generation phase, that is, the definition of the loading pattern order to narrow the investigated input space as much as possible, of available fuel assemblies per batch, we introduced a limitation for it can be placed: fuel assemblies originally placed on axes position and vice versa. The central location fuel assembly was fixed for even

The most important issue in the regression model development is model development. Since in a quarter core symmetry setup, the and having in mind the inquiring nature of the work, we decided to core symmetry, resulting in 21 fuel assemblies defining the core enrichment, number of IFBAs, and reactor history, or at least but number of potential parameters defining the input space is 63. This increases the number of training points and time required for the properties. Therefore, we decided to reduce the number of parameters cycle as a new parameter and representing fuel assembly only by 64, 92, and 116 for fresh fuel). Thus, the final number of parameters

The SVR model would eventually be used in an optimization algorithm. Therefore, the target parameters which we want to model should be

evaluation is based. In this work, we used the global core effective end of the cycle (k_{effBOC} and k_{effEOC}), as well as power peak separate SVR models were built.

3.2. Kernel Functions

The idea of the kernel function is to enable mathematical operator high-dimensional feature space [15]. The theory is based upon rep

A number of kernel functions have been proposed in the literature be used for mapping nonlinear input data into a linear feature space representing the problem. It is up to the modeller to select the appropriate kernel function. Two widely used kernel functions, namely, radial basis polynomial function (RBF), which are defined by (6)

$$K_{\text{RBF}}(\vec{x}_i, \vec{x}_j) = \exp\left(-\frac{\|\vec{x}_i - \vec{x}_j\|^2}{\sigma^2}\right)$$

$$K_{\text{PF}}(\vec{x}_i, \vec{x}_j) = (\vec{x}_i^T \vec{x}_j)^g$$

In the case of RBF kernel, parameter σ represents the radius of the kernel, and g represents the degree of the polynomial kernel.

As already mentioned, the behaviour of the SVR technique strongly depends on its corresponding parameters, and general SVR “free” parameters were determined by a combination of engineering judgement and genetic algorithms [17].

3.3. SVR Modeling Tools

Excellent results in SVR application to a wide range of classification science and technology, initiated creation of a number of implemented some of which are freely available software packages. In this work SVMTool [18], LIBSVM [19], and WEKA [20].

As stated in the previous subsection, RBF and PF kernel functions given in (6). However, practical parameterisation of the functions, from code to code. For example, parameter g in LIBSVM notation comparison of codes has been performed, general kernel parameters were modified to reflect on these values.

4. Results and Discussion

4.1. Comparison of Code Packages

The comparison of three code packages for SVR modeling, was conducted using a maximum training set size of 15 000 data points. The number of data points for learning models is typically enlarged are achieved. In this subsection, only the results of final models co

Preliminary analyses revealed that preprocessing of the input data fast operation of all SVR code packages. Mainly, due to the fact that scaling of the input data has been performed, including the scaling one of LIBSVM codes: SVMSCALE.

Models for three target values (k_{effBOC} , k_{effEOC} and $F_{\Delta H}^N$) were implemented on a Pentium 4 Mobile CPU 1.7 GHz, 256 MB RAM. The support vectors as the measure of model generalization characteristic on 5000 data points. The accuracy of the model was determined by the average deviation (RAD) defined as

$$\text{RMSE} = \sqrt{\frac{\sum_{i=1}^n (y_i - f_i)^2}{n}}$$

$$\text{RAD} = \frac{\sum_{i=1}^n (|y_i - f_i| / y_i)}{n}$$

where f_i stands for predicted value corresponding to the target percentage of tested data points which had the predicted value dev

$$\frac{|y_i - f_i|}{y_i} \times 100\% > 2$$

In the case of RBF kernel function, the initial values of free parameters on the LIBSVM code. The ranges for every parameter (C , ϵ , and σ) to 1000 for C and 0.001 to 2.0, and 1 to $7.07 (\sqrt{50})$ for ϵ and populations each consisting of 100 members. The training set consisted of 500 data points. The best result was obtained for $C = 371.725$, $\epsilon = 1$

In the case of the PF kernel function, we decided to set the d parameter for simplicity reasons C and ϵ were set to 371.725 and 0.05154, respectively. The comparison results for PF kernel function are given in Table 1 while in Table 2 comparison results for PF kernel

Table 1: Comparison of results for RBF kernel

Table 2: Comparison results for PF kernel function

The results of preliminary tests suggest that appropriate regression models can be developed for all target values regardless of the applied code package. The on-line model to be developed. The implementation or deployment time (seconds for 5000 calculations) is not the issue. The accuracy for the model is high while additional effort has to be placed on developing the $F_{\Delta H}^N$ model with a larger training set size.

4.2. Training Set Size Influence on SVR Model Quality

SVR model quality can be interpreted as the time required for generalization characteristics of the model. As shown in the previous figure, the training time is not the key issue.

As discussed previously, the size of the training set influences all the results. A detailed analysis of that influence is necessary. Here, we present the results of the analysis of the influence of the training set size on the model development using LIBSVM code package (see Figure 2). The characteristics of the target values are qualitatively very similar.

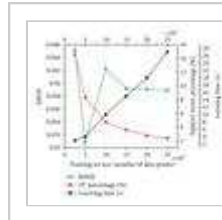


Figure 2: Training set size influence on model

Apart from the anomaly observed for the RMSE curve at the training set size of 100, the statistical and random characteristic of the training and testing data properties (low SV percentage) of the models increase with the training set size. The training time also increased exhibiting a nearly linear trend.

5. Conclusions

This work introduces a novel concept for fast evaluation of reactor core loading pattern regression model relying on the state of the art research in the field of machine learning.

Preliminary tests were conducted on the NPP Krško reactor core loading pattern reference data. Three support vector regression code packages were used for creating regression models of effective multiplication factor at the end of the cycle (k_{effEOC}), and power peaking ratio.

The preliminary tests revealed a great potential of the SVR method for reactor core loading pattern evaluation. However, prior to the final conclusion, additional tests and analyses are required, mainly focusing on the influence of the training set size, the required size of the training set and parameters of the SVR model.

In the case of the scenario involving machine learning from the reactor core loading pattern code, we do not anticipate any major changes in the learning system implementation. However, generation of training and testing data and requiring more hardware resources).

These are the issues that are within the scope of our future research.

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