

[an error occurred while processing this directive] 光学精密工程 2012, 20(12) 2812-2820 ISSN: 1004-924X CN: 22-1198/TH

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信息科学

姿态对地指向不断变化成像时的像移速度计算

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摘要： 基于线阵时间延迟积分(TDI)CCD推扫成像原理, 分析了敏捷卫星在三轴姿态机动过程中动态成像的像移问题。由于姿态对地指向不断改变会导致像面空间方位不断改变, 从而造成像移速度的改变, 本文通过坐标变换法推导出了动态成像方式下的像移速度数学解析表达式, 仿真得到了不同姿态机动角速度情况下TDICCD积分时间数量级。数值仿真分析表明: 当前50 μs级的航天相机在700 km的轨道高度可以实现以0.5($^{\circ}$)/s角速度上限进行动态推扫成像; 当姿态机动角速度大于0.5($^{\circ}$)/s时, 曝光时间越来越短, 需要设计更高水平的相机。以上结论表明, 对于不同角速度的动态成像任务, 需要量化TDICCD积分时间数量级, 实现在三轴姿态机动过程中开启光学有效载荷来完成推扫成像的动态成像。

关键词： 敏捷成像 TDI-CCD相机 像移 积分时间 像移速度 动态成像

Calculation of image motion velocity for agile satellite dynamic imaging to changed continuously attitude point

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Abstract: According to the principle of push-broom imaging of a linear array Time Delay Integration(TDI) CCD, the image motion in dynamic imaging of a agile satellite is analyzed in three-axis attitude maneuvering. As the changed continuously attitude points to the earth can change the spatial orientation and result in a changed image motion velocity, the image quality and image resolution will be deteriorated. To decrease the influence of attitude change on image quality, this article uses the coordinate transformation to acquire the mathematical expression of the image motion velocity in dynamic imaging, and obtains the variety of the image motion velocity in simulation analysis to quantify the magnitude of the integration time. Numerical simulation shows that the current level of space camera can achieve the max angular velocity limit dynamic push-broom imaging of 0.5($^{\circ}$)/s on an orbit height of 700 km. When the attitude maneuvering angular velocity is greater than 0.5($^{\circ}$)/s, it needs to design a high level camera because the exposure time is shorter and shorter. Based on the above conclusion, it suggests that the magnitude of integration time for TDI CCD (TDI) should be quantified for dynamic imaging at different angle speeds, and only in this way can the push-broom dynamic imaging be implemented in three-axis attitude maneuvering.

Keywords: agile imaging Time Delay Integration(TDI)-CCD camera image motion integration time image motion velocity dynamic imaging

收稿日期 2012-08-27 修回日期 2012-09-28 网络版发布日期

基金项目:

航天东方红卫星有限公司自主研发课题资助项目(No.025YF-Z-01)

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