

[本期目录](#) | [下期目录](#) | [过刊浏览](#) | [高级检索](#)[\[打印本页\]](#) [\[关闭\]](#)

信息科学

基于信息融合实现的激光陀螺调腔检测

马立^{1,2}, 徐次雄¹, 欧阳航空¹, 荣伟彬², 孙立宁^{2,3}

1. 上海大学 机电工程与自动化学院, 上海 200072;
2. 哈尔滨工业大学 机器人技术与系统国家重点实验室, 黑龙江 哈尔滨 150080;
3. 苏州大学 机器人与微系统研究中心, 江苏 苏州 215021

摘要: 考虑激光陀螺调腔人工检测耗时较长、易受干扰, 本文建立了激光陀螺自动调腔系统。在分析激光陀螺调腔工艺的基础上, 构建了一种由CCD相机和光电倍增管组成的多传感器信息融合体系结构, 提出了基于D-S证据理论的激光陀螺调腔检测方法。通过分析计算CCD相机和光电倍增管检测到的信号得出光斑、光阑中心点坐标差值及陀螺损耗值, 并由这些信息获得调腔质量的评价函数。然后, 根据D-S证据理论对评价函数进行融合处理, 分别获得陀螺调腔质量合格与不合格的信度函数, 应用最大支持度规则对调腔质量进行综合判断。实验结果显示, 基于D-S证据理论的激光陀螺调腔方法检测准确率为91.14%, 有效提高了调腔质量, 验证了该方法的可行性。

关键词: 激光陀螺 调腔 检测 D-S证据理论 信息融合

Detection of laser gyro cavity adjustment using information fusion

MA Li^{1,2}, XU Ci-xiong¹, OUYANG Hang-kong¹, RONG Wei-bin², SUN Li-ning^{2,3}

1. School of Mechatronic Engineering and Automation, Shanghai University, Shanghai 200072, China;
2. State Key Laboratory of Robotics and System, Harbin Institute of Technology, Harbin 150080, China;
3. Robotics and Microsystem Center, Soochow University, Suzhou 215021, China

Abstract: An automatic cavity adjustment system was established to improve the quality of laser gyro cavity adjustment and to overcome the drawbacks of manual detection such as low efficiency and low anti-interference capacity. According to the process of the cavity adjustment, a multi-sensor information fusion architecture was established by a CCD camera and a photomultiplier. A detection method of laser gyro cavity adjustment was proposed based on the D-S evidence theory. By analysis and calculation of the signals detected by the CCD camera and the photomultiplier, the center coordinate difference between facula and diaphragm and the loss value of the laser gyro were obtained and the evaluation function for each cavity adjustment result was deduced by these data. Furthermore, the qualified and unqualified belief functions of the cavity adjustment were obtained, respectively, and the quality of the cavity adjustment was verified based on the maximum support rule. The experimental result indicates that the accuracy of the detection method based on D-S evidence theory is 91.14%, which improves the quality of cavity adjustment effectively and validates the feasibility of the proposed method.

Keywords: laser gyro cavity adjustment detection D-S evidence theory information fusion

收稿日期 2011-12-06 修回日期 2012-03-01 网络版发布日期 2012-05-10

基金项目:

国家自然科学基金资助项目(No. 50905105); 机器人技术与系统国家重点实验室开放课题资助项目(No. SKLRS-2010-MS-02); 上海大学创新基金资助项目(No. SHUCX112200)

通讯作者: 马立

作者简介: 马立 (1977-), 女, 黑龙江佳木斯人, 博士, 副教授, 2007年于哈尔滨工业大学获得博士学位, 主要从事微操作机器人技术方面的研究。

E-mail: malian@shu.edu.cn

作者Email: malian@shu.edu.cn

参考文献:

- [1] OTMAN B, YUAN X H. Engine fault diagnosis based on multi-sensor information fusion using Dempster-Shafer evidence theory[J]. *Information Fusion*, 2007, 8(4): 379-386. [2] GUO H Y, LI Z L. A two-stage method to identify structural damage sites and extents by using evidence theory and micro-search genetic algorithm [J]. *Mechanical Systems and Signal Processing*, 2009, 23(3): 769-782. [3] MADHI T, REZA G, REZA E. Knitted fabric defect classification for uncertain labels based on Dempster-Shafer theory of evidence[J]. *Expert Systems with Applications*, 2011, 38(5): 5259-5267. [4] 龚卫国, 王林泓, 贺莉芳. 基于特征子模式典型相关分析的热释电红外信号识别 [J]. 光学 精密工程, 2011, 19(4): 884-891. GONG W G, WANG L H, HE L F. Pyroelectric infrared signal recognition based on feature sub-pattern canonical correlation analysis [J]. *Opt. Precision Eng.*, 2011, 19(4): 884-891. (in Chinese) [5] ERVAS E, MPIMPOUDIS A, ANAGNOSTOPOULOS C, et al.. Multisensor data fusion for fire detection [J]. *Information Fusion*, 2011, 12(3): 150-159. [6] GUO K H, LI W L. Combination rule of D-S evidence theory based on the strategy of cross merging between evidences [J]. *Expert Systems with Applications*, 2011, 38 (10): 13360-13366. [7] LIN T CH. Decision-based fuzzy image restoration for noise reduction based on evidence theory [J]. *Expert Systems with Applications*, 2011, 38(7): 8303-8310. [8] AYTUNC P, MEHMET G. Information fusion with dempster-shafer evidence theory for software defect prediction [J]. *Procedia Computer Science*, 2011, 3: 600-605. [9] MOHAMED A B, YVES D S, AHMED F, et al.. A ranking model in uncertain, imprecise and multi-experts contexts: The application of evidence theory [J]. *International Journal of Approximate Reasoning*, 2011, 52(8): 1171-1194. [10] AI L M, WANG J, WANG X L. Multi-features fusion diagnosis of tremor based on artificial neural network and D-S evidence theory [J]. *Signal Processing*, 2008, 88(12): 2927-2935. [11] 马巍. 基于证据理论

信息融合的电站锅炉故障诊断 . 北京:华北电力大学 , 2010. MA W. *Fault diagnosis of the power plant boiler based on the evidence theory of information fusion* . Beijing: North China Electric Power University, 2010. (in Chinese) [12] LAURENCE B, SOPHIE M. Pedestrian crossing detection based on evidential fusion of video-sensors [J]. *Transportation Research Part C: Emerging Technologies*, 2009, 17(5): 484-497. [13] AHMAD O, VALÉRIE K, UIF H. Improvement of X-ray castings inspection reliability by using Dempster-Shafer data fusion theory [J]. *Pattern Recognition Letters*, 2011, 32(2): 168-180. [14] 陈谋, 谭晓宇, 姜长生. 基于信息融合的空中红外小目标识别 [J]. 光学 精密工程, 2009, 17(8): 2032-2039. CHEN M, TAN X Y, JIANG C SH. IR small target recognition in sky background based on information fusion[J]. *Opt. Precision Eng.*, 2009, 17(8): 2032-2039. (in Chinese) [15] LATIFA O, ALEXANDRA D, THIERRY D, et al. Fault diagnosis in railway track circuits using Dempster-Shafer classifier fusion [J]. *Engineering Applications of Artificial Intelligence*, 2010, 23(1): 117-128. [16] 高晶, 孙继银, 刘婧, 等. 基于区域模糊阈值的前视红外目标识别 [J]. 光学 精密工程, 2011, 19(12): 3056-3063. GAO J, SUN J Y, LIU J, et al.. FLIR target recognition based on local fuzzy threshold[J]. *Opt. Precision Eng.*, 2011, 19(12): 3056-3063. (in Chinese) 本刊中的类似文章

1. 栗大超 李国卿 张晶鑫 于海霞 徐可欣.GGBP蛋白修饰的表面等离子共振微创血糖检测仪[J]. 光学精密工程, 2013, 21(9): 2333-2339
2. 张红颖 胡正.CenSurE特征和时空信息相结合的运动目标检测[J]. 光学精密工程, 2013, 21(9): 2452-2463
3. 陈剑鸣 吕启蒙 吴光敏 楚合群 John D Mai.分子印迹型薄膜体声波谐振毒品检测传感器[J]. 光学精密工程, 2013, 21(9): 2272-2278
4. 张海峰 刘晓为 李海 陈楠.电极表面粗糙度对检测电容的影响[J]. 光学精密工程, 2013, 21(9): 2266-2271
5. 党敬民 翟冰 高宗丽 陈晨 王一丁.纳秒级脉冲型群红外量子级联激光器驱动电源[J]. 光学精密工程, 2013, 21(9): 2209-2216
6. 龙亮 钟少龙 徐静 吴亚明.微型光纤磁传感器的设计与制作[J]. 光学精密工程, 2013, 21(9): 2294-2302
7. 杨世海 王国民.天文光学望远镜摩擦驱动滑移动态检测与修正[J]. 光学精密工程, 2013, 21(8): 2056-2063
8. 刘勇 钱鸿鹄 朱灵 赵树弥 张龙.微流控实时荧光PCR成像非均匀性的校正[J]. 光学精密工程, 2013, 21(8): 2161-2168
9. 杨亮 苏岩 裴安萍 夏国明.脉冲密度反馈对力平衡微机械陀螺的影响[J]. 光学精密工程, 2013, 21(8): 2087-2094
10. 陈阔 冯华君 徐之海 李奇 陈跃庭.行星中心亚像素精度定位算法[J]. 光学精密工程, 2013, 21(7): 1881-1890
11. 王斌 汪宗洋 吴元昊 马鑫雪 卫沛锋 王建立 吕杰.利用多通道相位差异波前探测法检测自适应光学系统非共光路像差[J]. 光学精密工程, 2013, 21(7): 1683-1692
12. 闵永智 党建武 张振海.图像式无砟轨道表面沉降在线监测系统[J]. 光学精密工程, 2013, 21(6): 1621-1627
13. 朱咸昌 伍凡 曹学东 吴时彬.基于Hartmann-Shack波前检测原理的微透镜阵列焦距测量[J]. 光学精密工程, 2013, 21(5): 1122-1128
14. 任寰 马力 刘旭 何勇 郑万国 朱日宏.多表面干涉情况下光学元件面形检测技术[J]. 光学精密工程, 2013, 21(5): 1144-1150
15. 李一芒 何听 魏仲慧 郭敬明.采用降维技术的红外目标检测与识别[J]. 光学精密工程, 2013, 21(5): 1297-1303

Copyright by 光学精密工程