

# 汽车车身先进设计制造 国家重点实验室

State Key Laboratory Of Advanced Design And Manufacturing For Vehicle Body

今天是 2013-06-06

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目前从事的研究领域及主惠研究方向 机械振动与控制、非线性动力学、计算力学

### 主要学习工作经历

徐适临教授于2009年10月回国任职湖南大学机械与运载工程学院,任教授(博士导师)。获得湖南大学重点学科建设 基金支持,领导一个研究组开展研究与数学工作。作为研究项目负责人,目前止承担机械系统隔据方面科研项目。 1992年获中英友好奖学金由国家教委公派留学英国,1996年6月获得论顿大学工学博士。1996年9月在新加坡国立大 学计算力学中心任高级研究员。1998年7月在新加坡高性能计算研究院担任研究部门经理。1999年8月至2009年10月 期向在新加坡南洋狸工大学从事教学与科研,任副教授。出国前,在大追狸工大学力学系从事教学与科研工作,任讲 师(毕业留校)。

# 主要兼职

2002年-2008年 新加坡计算力学学会 副金长

香港城市大学混沌控制与同步研究中心 海外特邀会员 2002年-至今

2005年-2008年 大值理工大学 "海天学者"特聘教授

游聘教授 2005年-2008年 湖南大学

2009年- 至今 湖南大学深海装备研究中心 主任

2010年- 至今 湖南大学机械与这载学院学术委员会 副主任

# 获奖情况

- (1) 荻中英友好奖学金,由国家教委公派赴英国留学,1992年 1996年。
- (2) 裝圈除IEEE最佳论文奖。4th International Symposium on Communication Systems, Networks & Digital Signal Processing, 2004年。

### 主要学术贡献

在国际非线性动力等学术领域,徐适临数提升拓了Chaos Projective Synchronization新的研究方向。自开创性论文 (D. Xu, "Control of Projective Synchronization in Chaotic Systems", Physical Review E 63, (2001), pp. 27201-27204 )从理论上证实这种同步记视象具有不可预测性后,提出了同步记控制的概念。为了解决这种肠理视象的产生 条件,带领博士研究团队用了几年时向做了一系列的基础理论性探索。完成了从三维到无穷维,从追读到离散系统的 同步化生成条件。在此理论基础上,展开了投射混沌同步化控制和混沌保密逼讯应用研究并获得国际奖项。主要研究 成果发表在美国物理学全的《物理评论》(Physical Review E), 《混沌》(CHAOS), 英国皇家学会朝刊《数学物理及工 程科学》(PROCEEDINGS OF THE ROYAL SOCIETY A - MATHEMATICAL PHYSICAL AND ENGINEERING SCIENCES),英國物理学报《Physics Letters A〉,德國的《混沌,孤立子和分形》(CHAOS SOLITONS & FRACTALS)等署名國際期刊。这些研究工作获得了國際学界高度关注。近年来在Projective Synchronization研究主题 4,早期工作被各国学者大量引用,每年他引次数愈百。多篇论文被国际署名学者引用。

# 国际学术期刊论文审稿人

IEEE Transactions on Circuits and Systems I IEEE Transactions on Circuits and Systems II Journal of Economic Dynamics and control International Journal of Systems and Science International Journal of Bifurcation and Chaos
Journal of Vibration and Noise
Chaos, Solitons and Fractals
Nonlinear Dynamics
Physica A
Physics Letters A
IEEE/ASME Transaction on Mechatronics
Modern Physics Letters B
Communication in Nonlinear Science and Numerical Simulations
International Journal of Impact Engineering
IEEE/ASME Transaction on Robotics
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Inverse Problems in Science and Engineering

Mechanism and Machine Theory

专利

徐道临, 刘铁牛,"一种新型套管扶正器", 专利号90200916.8, 中国, 1990年。

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- 2. Self-locating control of chaotic systems using Newton algorithm Author(s): Xu D, Bishop SR Source: PHYSICS LETTERS A Volume: 210 Issue: 4-5 Pages: 273-278 Published: JAN 15 1996 (Impact factor: 1.711, Citation: 34)
- 3. Manipulating the scaling factor of projective synchronization in three-dimensional chaotic systems Author(s): Xu DL, Li ZG, Bishop SR Source: CHAOS Volume: 11 Issue: 3 Pages: 439-442 Published: SEP 2001 (Impact factor: 2.188, Citation: 34)
- 4. Controlling the ultimate state of projective synchronization in chaotic systems of arbitrary dimension Author(s): Xu DL, Chee CY Source: PHYSICAL REVIEW E Volume: 66 Issue: 4 Article Number: 046218 Part: Part 2 Published: OCT 2002 (Impact factor: 2.483, Citation: 33)
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最近更新 (2010-04-06)

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