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教育经历

1996年9月-2000年7月, 湖北汽车工业学院, 机械设计制造及其自动化, 大学本科, 学士学位

2001年9月-2007年12月, 山东大学, 机械工程学院, 研究生, 博士学位

工作背景

2007年3月-至今, 青岛科技大学, 副教授

研究领域

机器人技术, 智能控制, 机器视觉, 机械设计及创新设计等

代表性成果

Wang Xian-lun, Cui Yu-xia, Huang Jing. Intelligent force/position control of robotic manipulators based on fuzzy logic,1/3,系统仿真学报(EI) ,2007年19卷11期, p2467-2471.

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Wang Xian-lun, Li Ping, Yang Fei-qi. Gait planning of humanoid robot based on ZMP and cubic spline interpolation,1/3,Applied Mechanics and Materials(EI),2013,427,p 1394-1397.

Wang Xian-lun, Li Li, Cui Yu-xia. Detection and Location of Underwater Pipeline based on Mathematical Morphology for an AUV,1/3,2013 Key engineering materials(EI), 2013,561,p591-596.

Wang Xian-lun, Wang Huajie, Cui Yu-xia. Research on testing system of single robot based on virtual prototype for robot soccer,1/3,2013 Applied Mechanics and Materials(EI),2013,427,p995-998.

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王宪伦, 喻洋, 王道全, 崔玉霞. 凿岩机器人的建模与运动学分析1/42016 矿山机械2016年44卷1期p 90-93.

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