短文

一类基于滚动时域优化原理的多路控制器设计及其在活套控制中的应用

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针对热连轧活套高度和张力的双输入双输出强耦合系统,文中提出一类基于滚动时域优化原理的多路控制策略。基于滚动优化原理,在每一个周期内,顺序求解子系统的控制律后及时更新系统。从 H_{∞} 观点出发,将解耦问题转化为干扰抑制和多目标优化问题,能够减轻计算机的负担,提高控制系统的性能.仿真结果证实了该方法具有良好的解耦效果和控制性能.

关键词 <u>H。控制</u> <u>预测控制</u> 活套控制 解耦控制

分类号

Design and Application of a Class of Multiplexed Receding Horizon Controllers for Looper Control System

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Abstract

Multiplexed receding horizon control strategy is proposed for looper height and tension double input-output strongly coupled system. Based on receding horizon control theory, after all subsystem controllers are obtained sequentially, the system is updated in time. The decoupling problem is transformed into a problem of combining disturbance rejection and comprehensive optimization based on H_{∞}

control theory, which can lighten computation burden and improve control performance. Simulation results prove the effectiveness of the method in both decoupling effect and control performance.

Key words $\underline{H_{\infty}}$ control receding horizon control looper control decoupling control

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