

论文

Output Feedback Control for MIMO Nonlinear Systems with Exogenous Signals

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摘要 The paper addresses the global output tracking of a class of multi-input multi-output (MIMO) nonlinear systems affected by disturbances, which are generated by a known exosystem. An adaptive controller is designed based on the proposed observer and the backstepping approach to asymptotically track arbitrary reference signal and to guarantee the boundedness of all the signals in the closed loop system. Finally, the numerical simulation results illustrate the effectiveness of the proposed scheme.

关键词 [Backstepping method, exogenous signals.](#)

分类号

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Abstract The paper addresses the global output tracking of a class of multi-input multi-output (MIMO) nonlinear systems affected by disturbances, which are generated by a known exosystem. An adaptive controller is designed based on the proposed observer and the backstepping approach to asymptotically track arbitrary reference signal and to guarantee the boundedness of all the signals in the closed loop system. Finally, the numerical simulation results illustrate the effectiveness of the proposed scheme.

Key words [Backstepping method](#) [exogenous signals](#) [multi-input multi-output nonlinear](#) [output feedback control](#)

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通讯作者

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