

时滞系统分数阶PI^{??}极点配置控制器设计

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Pole placement with fractional-order PI^{??} controllers for time-delay systems

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摘要

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摘要

利用参数空间法研究用PI^{??}控制器实现时滞系统的闭环极点配置问题. 复平面上的阻尼角扇形区域和相对稳定性区域(该两区域构成一个梯形区域)被映射到控制器参数平面, 相应的控制器参数可以将闭环极点配置在梯形区域内, 从而保证所要求的系统性能. 仿真结果显示, 对于适当选取的分数阶PI^{??}控制器的参数, 采用分数阶控制器可以取得比整数阶控制器更好的控制效果, 从极点配置的角度揭示了分数阶控制器的优越性.

关键词: 极点配置, 分数阶PI^{??}控制器, 参数空间法, 时滞系统

Abstract:

The pole placement with fractional-order PI^{??} controllers for time-delay systems is discussed by using the parameter space approach. The damping ratio angular sector region and the relative stability region in complex plane, which form a trapezoid region in the left-half of the complex plane, are mapped into the controller parameters space. Thus, the corresponding controller parameters can place all the closed-loop poles in the specified trapezoid region, and guarantee the performances of the closed-loop systems. Simulation results show that for appropriately selected parameters of the fractional-order PI^{??} controller, better system performances can be achieved with the fractional-order controller than with the integer-order controller, and the superiority of fractional-order controllers is proved from the view point of the pole placement.

Key words: pole placement fractional-order PI^{??} controllers parameter space approach time-delay systems

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