



兰维瑶1995年毕业于重庆大学精密仪器系，1998年毕业于厦门大学自动化系，分别获学士和硕士学位。2004年毕业于香港中文大学自动化与计算机辅助工程系，获博士学位。2004年4月至2006年12月在新加坡国立大学电子与计算机工程系从事博士后研究工作。2006年12月起在厦门大学自动化系任副教授。2008年8月晋升为教授。主要研究方向为：非线性控制理论及应用、智能控制技术、鲁棒及最优控制。课题组招收控制理论与控制工程方向博士研究生，控制理论与控制工程、检测技术与自动化装置方向学术型硕士研究生、控制工程方向专业型硕士研究生。联系方式：wylan@xmu.edu.cn。

### 兰维瑶 [教授]

#### ● 承担项目

NO. 1	具有未建模动态的一类非线性系统的鲁棒自适应控制，国家自然科学基金项目（2007.1-2009.12），项目批准号：60674037，项目负责人：王丹。
NO. 2	一类非最小相位非线性系统的H无穷控制问题研究，国家自然科学基金项目（2008.1-2010.12），项目批准号：60704042，项目负责人：兰维瑶。
NO. 3	复合非线性反馈控制技术在伺服控制问题中的应用，福建省自然科学基金项目（2008.5-2011.4），项目批准号：2008J0033，项目负责人：兰维瑶。
NO. 4	基于复合非线性反馈的非线性伺服控制问题研究，国家自然科学基金项目（2011.01-2013.12），项目批准号：61074004，项目负责人：兰维瑶。

#### ● 著作论文

NO. 1	D. Lin, W. Lan, and M. Li, "Composite nonlinear feedback control for linear singular systems with input saturation," <i>Systems and Control Letters</i> , vol. 60, no. 10, pp. 825-831, 2011.
NO. 2	W. Lan and J. Huang. "Semi-global stabilization and output regulation for linear singular systems with input saturation," <i>IEEE Transactions on Automatic Control</i> , Vol. 48, No. 7, pp. 1274-1280, 2003.
NO. 3	W. Lan and J. Huang. "On the discrete-time robust nonlinear servomechanism problem," <i>Communications in Information and Systems</i> , Vol. 3, No. 2, pp. 75-100, October 2003.
NO. 4	W. Lan and J. Huang. "Robust output regulation for discrete-time nonlinear systems," <i>International Journal of Robust and Nonlinear Control</i> , Vol 15, pp. 63-81, 2005.
NO. 5	W. Lan, Z. Chen and J. Huang, "Semi-global robust output regulation for nonlinear systems in normal form using output feedback," <i>Communications in Information and Systems</i> , Vol. 5, No. 4, pp. 285 - 400, 2005.
NO. 6	W. Lan, Ben M. Chen and Y. J. He, "On improvement of transient performance in tracking control for a class of nonlinear systems with input saturation," <i>Systems and Control Letters</i> , Vol. 55, No. 2, pp. 132-138, 2006.
NO. 7	W. Lan, Ben M. Chen and Z. Ding, "Adaptive estimation and rejection of unknown sinusoidal disturbances for a class of nonlinear MIMO systems," <i>Int. J. Adapt. Contr. and Sig. Proc.</i> , 20(2), 2006.
NO. 8	Y. He, Ben M. Chen and W. Lan. "On improving transient performance in tracking control for a class of nonlinear discrete-time systems with input saturation," <i>IEEE Transactions on Automatic Control</i> , vol. 52, no. 7, pp. 1307-1313, 2007.
NO. 9	W. Lan and J. Huang. "Neural network based approximate output regulation of discrete-time nonlinear systems," <i>IEEE Transactions on Neural Networks</i> , vol. 18, no. 4, pp. 1196-1208, 2007.
NO. 10	W. Lan and B. M. Chen, F. L. Lewis "Explicit constructions of global stabilization and nonlinear H <sub>infinity</sub> control law for a class of nonminimum phase . . . , " <i>International Journal of Robust and Nonlinear Control</i> , vol. 18, pp. 1257-1284, 2008.
NO. 11	W. Lan and Ben M. Chen. "Explicit construction of H <sub>infinity</sub> control law for a class of . . . , " <i>Automatica</i> , vol. 44, no. 3, pp. 738-744, 2008.
NO. 12	D. Wang and W. Lan, "Adaptive neural control for a class of uncertain nonlinear systems with unknown time delay," <i>International Journal of Robust and Nonlinear Control</i> , vol. 19, no. 7, pp. 807-821, 2009.
NO. 13	D. Wang, J. L. Huang, W. Lan, and X. Q. Li, "Neural network based robust adaptive control of nonlinear systems with unmodeled dynamics," <i>Mathematics and Computers in Simulation</i> , vol. 79, no. 5, pp. 1745-1753, 2009.
	W. Lan and Dan Wang, "Structural design of composite nonlinear feedback control for

NO. 14 "linear systems with actuator constraint," Asian Journal of Control , vol. 12, no. 5, pp. 616-625, 2010.

NO. 15 W. Lan, C. K. Thum, and B. M. Chen, "A hard disk drive servo system design using composite nonlinear feedback control with optimal nonlinear gain tuning methods," IEEE Transactions on Industrial Electronics, vol. 57, no. 5, pp. 1735-1745, 2010.