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Gregory J. Gerling

Position: Associate Professor Office: Olsson 101D Phone: 434-924-0533 Fax: Email: gg7h@virginia.edu **Personal Homepage**

Degrees: Ph.D, The University of Iowa

Biography:

Dr. Gerling joined the faculty in 2005. Before leaving to further pursue academia, Dr. Gerling was a software engineer with Motorola and had held short-term positions with Rockwell-Collins and NASA Ames Research Center. He is a member of the IEEE Robotics and Automation, Haptics, Computer, and Engineering in Medicine and Biology Societies, and the Human Factors and Ergonomics Society.

Research Interests:

- Haptics
- Computational neuroscience
- Human factors/ergonomics
- Human-machine interaction

Research Groups:

Human Factors

Research Centers:

Representative Publications:

- 1. Lesniak, D.R., Marshall, K.L., Wellnitz, S.A., Jenkins, B.A., Baba, Y., Rasband, M.N., Gerling, G.J., and Lumpkin, E.A. (2014). Computation Identifies Structural Features that Govern Neuronal Firing Properties in Slowly Adapting Touch Receptors. eLife, 3:e01448.
- 2. Gerling, G.J., Rivest, I.I., Lesniak, D.R., Scanlon, J.R., and Wan, L. (2014). Validating a Population Model of Tactile Mechanotransduction of Slowly Adapting Type I Afferents at Levels of Skin Mechanics, Single-unit Response, and Psychophysics. IEEE Transactions on Haptics, in press.
- 3. Lesniak, D.R. and Gerling, G.J. (2014). Mimicking the End Organ Architecture of Slowly Adapting Type I Afferents May Increase the Durability of Artificial Touch Sensors. Proceedings of the 2014 IEEE Haptic Interfaces for Virtual Environment and Teleoperator Systems, Houston, TX in press.
- 4. Wang, Y., Marshall, K.L., Baba, Y., Gerling, G.J., Lumpkin, E.A. (2013). Hyperelastic material properties of mouse skin under compression. PLoS ONE, 8(6): e67439.
- 5. Kim, E.K., Sugg, K.B., Langhals, N.B., Lightbody, S.M., Baltrusaitis, M.E., Urbanchek, M.G., Cederna, P.S., Gerling, G.J. (2013). An Engineered Tactile Afferent Modulation Platform to Elicit Compound Sensory Nerve Action Potentials in Response to Force Magnitude. Proceedings of the IEEE World Haptics Conference 2013, The 5th Joint Eurohaptics Conference and IEEE Haptics Symposium, Daejeon, South Korea, pp. 241-230 (* best paper).
- 6. Baumgart, L.A., Gerling, G.J., and Bass, E.J. (2010). Characterizing the range of simulated prostate abnormalities palpable by digital rectal examination. Cancer Epidemiology, 34 (1), 79-84.
- 7. Wang, N., Gerling, G.J., Moyer Childress, R., and Martin M.L. (2010). Quantifying palpation techniques in relation to performance in a clinical prostate exam. IEEE Transactions on Information Technology in Biomedicine, 14(4): 1088-97.

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