Random Conley-Markov Connection Matrix for Gradient Flows

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Morse-Conley Connection Matrix

Motivation Morse Decomposition Conley Index and Connection Matrix

Random Dynamical Systems Motivations and results Random Dynamic System Transition matrix and Markov property

Conley-Markov Connection Matrix and Optimals Conley-Markov Connection matrix Examples and Conclusions

Motivation Morse Decomposition Conley Index and Connection Matrix

Classical Morse–Conley theory

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Morse Decomposition for Dynamical Systems on compact metric spaces : φ : ℝ × X → X, initiated by Morse, was established by Morse, Smale, ect by using the gradient-like flows for Morse decomposition of DS. Smale's proof of Higher dimensional Poincare Conjecture.

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- R. Bott : to the critical submanifolds with nondegeneracy by applying 'normal bundles' trick in differential topology. The famous Bott perodicity.
- ► Conley's extension : invariant isolated set and index pair and pointed space are vital to many applications for Dynamical sysytems without differential topology advantages of compact metric space X.

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- ▶ Even it is scarce in the sense of the perfect Morse functions. It is called Arnold Conjecture for symplectic closed manifolds with Hamiltonian functions.

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- ► Even for the gradient-like flow, those algorithms cannot tell the local minima from the global minimum.
- ► Results : The Conley-Markov connection matrix we study, would provide a solution.

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Attractor-repeller pairs

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- Attractor–Repeller pairs (A_i, R_i) :

$$\emptyset = A_0 \subset A_1 \subset \cdots \land A_n = X = R_0 \supset R_1 \cdots \supset R_n = \emptyset.$$

with $R_i = \{x \in X : \omega(x) \cap A_i = \emptyset\}.$

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• Morse set : $M_i = A_i \cap R_{i-1}, 1 \le i \le n$.

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- Morse set : $M_i = A_i \cap R_{i-1}, 1 \le i \le n$.
- (M_i)_{1≤i≤n} is called a Morse decomposition of X. (Morse theory from the dyanmical system point of view).

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Main result on DS

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- If ϕ is a DS on a compact metric space X, then the followings are equivalent.
- Morse decomposition of the DS $\phi : (M_i)_{1 \le i \le n}$.
- ► Stratification structure : for any $x \in X$, $\omega(x)$, $\alpha(x) \in \bigcup_{j=1}^{n} M_j$: if $x_1, \cdots, x_p, \alpha(x_k) \subset M_{j_{k-1}}, \omega(x_k) \subset M_{j_k}, 1 \le k \le p$, then $j_0 \le j_p$.

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- $\phi(t)N_0 \subset N_1$ for $t \in \mathbb{R}^+$
- $x \in N_1, x \cdot \mathbb{R}^+$ does not lie in N_1 , then there exists $T \ge 0$ such that $\phi[0, T] \cdot x \subset N_1$ and $\phi(T) \cdot x \in N_0$.

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Homotopy index of pointed spaces

► Let (X, A) be a topological pair. X is the set of those subsets of X of the form {x} with x not in A, together with the set A.

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- ▶ $\overline{0}$ be the pointed one-point space. If $X \coprod Y/\{x_0, y_0\} = [X, x_0] \lor [Y_0, y_0] = \overline{0}$, then $[X, x_0] = [Y, y_0] = \overline{0}$.

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- $\blacktriangleright \ [X/A] \land [Y/B] = [X \times Y/(X \times B \cup A \times Y)].$

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Generalized Morse inequality

▶ For any isolated invariant set S and its isolated neighborhood (N_1, N_0) , define

$$p(t, h(S)) = \sum_{k \ge 0} \operatorname{rank} H^k(N_1, N_0) t^k.$$

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$$p(t, h(S)) = \sum_{k \ge 0} \operatorname{rank} H^k(N_1, N_0) t^k.$$

▶ Non-degenerate critical point $z \in Z$,

$$h(\{z\}) = [\dot{S}^m], \quad m = \frac{1}{2} \dim Z - j$$

for the Hamiltonian dynamical system in symplectic manifold Z with the Morse index j. Here m is the Maslov index.

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 Existing index pair for isolated invariant set and Morse decomposition.
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$$\sum_{j=1}^{n} p(t, h(M_j)) = p(t, h(S)) + (1+t)Q(t)$$

See Conley Isolated Invariant sets and the Morse index, AMS (1978), vol.38; and Conley, Zehnder, Communication in Pure and Applied Math., 37 (1984), 207–253.

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Advantages from Conley index theory :

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- ▶ Need not to be manifolds.
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- ▶ Compactness is required
- Cohomology of the homotopy index can be adjusted to different cohomologies.

Motivation Morse Decomposition Conley Index and Connection Matrix

Connection Matrix

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Connection Matrix

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- ► $\Delta : \bigoplus_{i \in P} CH(M(i); \mathbf{R}) \to \bigoplus_{i \in P} CH(M(i); \mathbf{R})$ be a linear map such that $\Delta = (\Delta(i, j))_{i,j \in P}$ as a matrix maps, where $\Delta(i, j) : CH_*(M(i); \mathbf{R}) \to CH(M(j); \mathbf{R})$. Similarly, we have $\Delta(I) = (\Delta(i, j))_{i,j \in I}$.

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- ► Franzosa proved : There exists a Conley connection matrix for a Morse decomposition.

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► The non-trivial connection entry $\Delta(i, j) \neq 0$ implies that $C(M(\pi_i), M(\pi_j)) \neq \emptyset$.

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- Reineck showed : Suppose a Morse-Smale flow has no periodic orbits. Each nonzero map in the connection matrix is flow defined, and the Conley connection matrix is unique.
- ▶ Franzosa later relaxed Reineck's result for periodic orbits with doubly connected rest points, and constructed a non-unique Conley connection matrix at the bifurcation point.

Motivations and results Random Dynamic System Transition matrix and Markov property

Motivations and results

Morse functions form a dense open subset in the space of smooth functions. For a gradient flow induced by a Morse function, the values of the Morse function will detect the global minimum.

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- Morse functions form a dense open subset in the space of smooth functions. For a gradient flow induced by a Morse function, the values of the Morse function will detect the global minimum.
- ► A Morse function is called excellent if differential critical points correspond to different critical values. Any Morse function can be arbitrarily approximated in the C²-topology by excellent Morse functions.
- But the construction from this theoretical result cannot provide any useful way to find the global minimum or maximum.

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$$\alpha(M) \ge \sum b_i(M)$$

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▶ What the small white noise can do to the Dynamic Systems

Motivations and results Random Dynamic System Transition matrix and Markov property

DRS

A measurable (C^k, k = 0, · · · , ∞, C^ω) random dynamical system on the measurable (C^k) space (C^k-manifold) (X, B) over a metric dynamic system (Ω, F, P, (θ(t))_{t∈T}) with time T is a mapping

$$\phi:\mathbb{T}\times\Omega\times X\to X,\quad (t,\omega,x)\mapsto\phi(t,\omega,x),$$

with the following properties :

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- ► (ii) Regularity : $\phi(t, \omega) : X \to X$ is measurable $(C^k, k = 0, \cdots, \infty, C^{\omega}).$

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- ► (ii) Regularity : $\phi(t, \omega) : X \to X$ is measurable $(C^k, k = 0, \cdots, \infty, C^{\omega}).$
- (iii) Cocycle Condition : $\phi(0, \omega) = id_X$ for all $\omega \in \Omega$ and $\phi(t + s, \omega) = \phi(t, \theta(s)\omega) \circ \phi(s, \omega)$ for all $s, t \in \mathbb{T}, \omega \in \Omega$.

Motivations and results Random Dynamic System Transition matrix and Markov property

White Noise on Gradient-like flow

► A random set C is an invariant if $\phi(t, \omega)C(\omega) = C(\theta(t)\omega)$ for all $t \in \mathbb{T}$ and **P**-a.s.

White Noise on Gradient-like flow

- A random set C is an invariant if $\phi(t,\omega)C(\omega) = C(\theta(t)\omega)$ for all $t \in \mathbb{T}$ and **P**-a.s.
- ▶ The random perturbation of the gradient-like flow is

$$\dot{x} = -X(x) + \varepsilon I d_{n \times n} \xi(t, \omega),$$

where $x = \pi(t, \omega)$. Its stochastic differential integral equation is given by

$$x(t) - x(0) = -\int_0^t X(x(s))ds + \int_0^t \varepsilon Id_{n \times n}dW_s.$$

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► There exists a unique solution of the stochastic differential equation with an initial condition $\pi(0,\omega) = x_0(\omega)$, where $x_0(\omega)$ is an *M*-valued measurable function of $(W_s(\omega), s \leq t)$.

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▶ a simple Markov process on M: for every bounded measurable function h and all $s, t \in [0, T]$ with $s \le t$

$$E[h(x_t)|\mathcal{F}_s)](\omega) = E[h(x_s,\omega)]$$

for *P*-a.e. $\omega \in \Omega(M)$,

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for *P*-a.e. $\omega \in \Omega(M)$,

• and the transition probability law $p(0, x_0, t, x_t)$ (the conditional probability law of $\pi(t, \omega)$ with $\pi(0, \omega) = x_0$) is same with the probability law of the solution $x(t) = \pi(t, \omega)$ of the Fokker-Planck equation with initial condition $x(0) = x_0$.

Motivations and results Random Dynamic System Transition matrix and Markov property

White Noise on Gradient-like flow

• Let $S^1 = \mathbb{R}/(2\pi\mathbb{Z})$ be a compact 1-dimensional circle with a Morse function $f(x) = \cos(2x)$. Hence the random perturbation of the gradient flow is given by

$$\dot{x}(\omega) = 2\sin 2x(t,\omega) + \varepsilon \xi(x(t,\omega)),$$

where ξ is the 1-dimensional Brownian motion and $\omega \in \Omega(S^1)$.

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For every path of ω ∈ Ω(S¹), the rest point of the random dynamic system can be any point in S¹ since the Brownian motion take any finite value at finite time with probability 1. Hence almost surely D : ω ↦ D(ω) = S¹.

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- The random invariant set moves along the path almost surely to cover the whole manifold S^1 , Similarly for T^n .

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Transition matrix

► For each t and $\omega \in \Omega(M)$, we define the Conley connection matrix as

$$\Delta_A(t,\omega): \oplus_{\alpha \in A} CH_*(S_\alpha(t,\omega);\mathbb{R}) \to \oplus_{\alpha \in A} CH_*(S_\alpha(t,\omega);\mathbb{R})$$

- a linear map such that $\Delta_A(t,\omega) = (\Delta(\alpha,\beta)(t,\omega))_{\alpha,\beta\in A}$, where
- $\Delta(\alpha,\beta)(t,\omega): CH_*(S_\alpha(t,\omega);\mathbb{R}) \to CH_*(S_\beta(t,\omega);\mathbb{R}).$

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$$\Delta_A(t,\omega): \oplus_{\alpha \in A} CH_*(S_\alpha(t,\omega);\mathbb{R}) \to \oplus_{\alpha \in A} CH_*(S_\alpha(t,\omega);\mathbb{R})$$

a linear map such that $\Delta_A(t,\omega) = (\Delta(\alpha,\beta)(t,\omega))_{\alpha,\beta\in A}$, where

- $\Delta(\alpha,\beta)(t,\omega): CH_*(S_\alpha(t,\omega);\mathbb{R}) \to CH_*(S_\beta(t,\omega);\mathbb{R}).$
- ► For each isolated invariant compact subset $S_{\alpha}(t, \omega)$, there is a well-defined $\Delta(\alpha, \alpha)(t, \omega)$ of degree zero.

Motivations and results Random Dynamic System Transition matrix and Markov property

Markov Property

► For the gradient-like flow with partial ordering (P, <), Let Δ be the connection matrix with respect to the ordering. If $\Delta(\alpha, \beta)$ is of degree -1 for $\alpha \neq \beta \in P$, then $(\Delta - D) \circ (\Delta - D) = 0$, i.e., $\Delta \circ \Delta + D^2 = \Delta \circ D + D \circ \Delta$, where $D = (\Delta(\alpha, \alpha))$ is the diagonal matrix of Δ .

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- ► For each $\omega \in \Omega(M)$ with $S_{\alpha}(t, \omega)$ an isolated invariant point for all $\alpha \in A$, then the probability $p_{\alpha\beta}(t, \omega) = p(-\infty, S_{\alpha}(t, \omega); +\infty, S_{\beta}(t, \omega))$ form a transition matrix $P(t, \omega) = (p_{\alpha\beta}(t, \omega))_{\alpha,\beta\in A}$ which is Markov of the finite state A.

Conley-Markov Connection matrix Examples and Conclusions

Conley-Markov connection matrix

▶ Define a Conley-Markov connection matrix as

$$CM(t,\omega) = (\Delta_A(t,\omega), p_A(t,\omega))$$

$$= \left(\left\{ \Delta(\alpha, \beta)(t, \omega), p_{\alpha\beta}(t, \omega) \right\} \right)_{\alpha, \beta \in A}$$

where $\Delta_A(t,\omega) = (\Delta(\alpha,\beta)(t,\omega))_{\alpha,\beta\in A}$ and $p_A(t,\omega) = (p_{\alpha\beta}(t,\omega))_{\alpha,\beta\in A}$.

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▶ For any compact closed manifold M and a gradient-like vector field X, there exists a well-defined Conley-Markov connection matrix for invariant subsets.

Conley-Markov Connection matrix Examples and Conclusions

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► For $\varepsilon \neq 0$ and $0 \leq s \leq t \leq T$, there exists a transition matrix $T_{st}(\omega)$ such that $T_{st}(\omega)\Delta(s,\omega) = \Delta(t,\omega)$.
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- ► For $\varepsilon \neq 0$ and $0 \leq s \leq t \leq T$, there exists a transition matrix $T_{st}(\omega)$ such that $T_{st}(\omega)\Delta(s,\omega) = \Delta(t,\omega)$.
- ▶ The limit of $CM(t, \omega)$ for $\varepsilon \to 0$, exists, but not necessary equal to the classical Conley Connection matrix.

Conley-Markov Connection matrix Examples and Conclusions

Examples

•
$$dx = -\nabla f(x)dt + \varepsilon dW_t$$
 with
 $f(x) = -\alpha(x-1)^2 + x^4/10$, critial points are
 $x_1 = -5.4, x_2 = 1, x_3 = 4.4.$

Conley-Markov Connection matrix **Examples and Conclusions**

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Conley-Markov Connection matrix **Examples and Conclusions**

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▶ Conley-Markov connection matrix

$$CM^{\varepsilon=6}(t,\omega) = \begin{bmatrix} 0.8139 & 0.0000 & 0.0000\\ 0.7452 & 0.0000 & 0.0556\\ 0.0012 & 0.0001 & 0.6587 \end{bmatrix}$$
$$CM^{\varepsilon=0.75}(t,\omega) = \begin{bmatrix} 0.9999 & 0.0000 & 0.0000\\ 0.9996 & 0.0000 & 0.0003\\ 0.0000 & 0.0000 & 0.9998 \end{bmatrix}$$

Conley-Markov Connection matrix Examples and Conclusions

Conclusions

 Conley Connection matrix for finding the global information; the transition-probability for determining the possible local information.

Conley-Markov Connection matrix Examples and Conclusions

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- If $\Delta(\alpha, \beta)(t, \omega) = 0$, there are still possible trajectory flow linesdue to $p_{\alpha\beta}(t, \omega) > 0$. Detecting possible gradient flows which cannot be detected from the Conley homological connection matrix.

Conley-Markov Connection matrix Examples and Conclusions

Conclusions

- Conley Connection matrix for finding the global information; the transition-probability for determining the possible local information.
- If $\Delta(\alpha, \beta)(t, \omega) = 0$, there are still possible trajectory flow linesdue to $p_{\alpha\beta}(t, \omega) > 0$. Detecting possible gradient flows which cannot be detected from the Conley homological connection matrix.
- Even with $p_{\alpha\beta}(t,\omega) = 0$, T_{st} show the strength for detecting the bifurcation with strong possibility.